

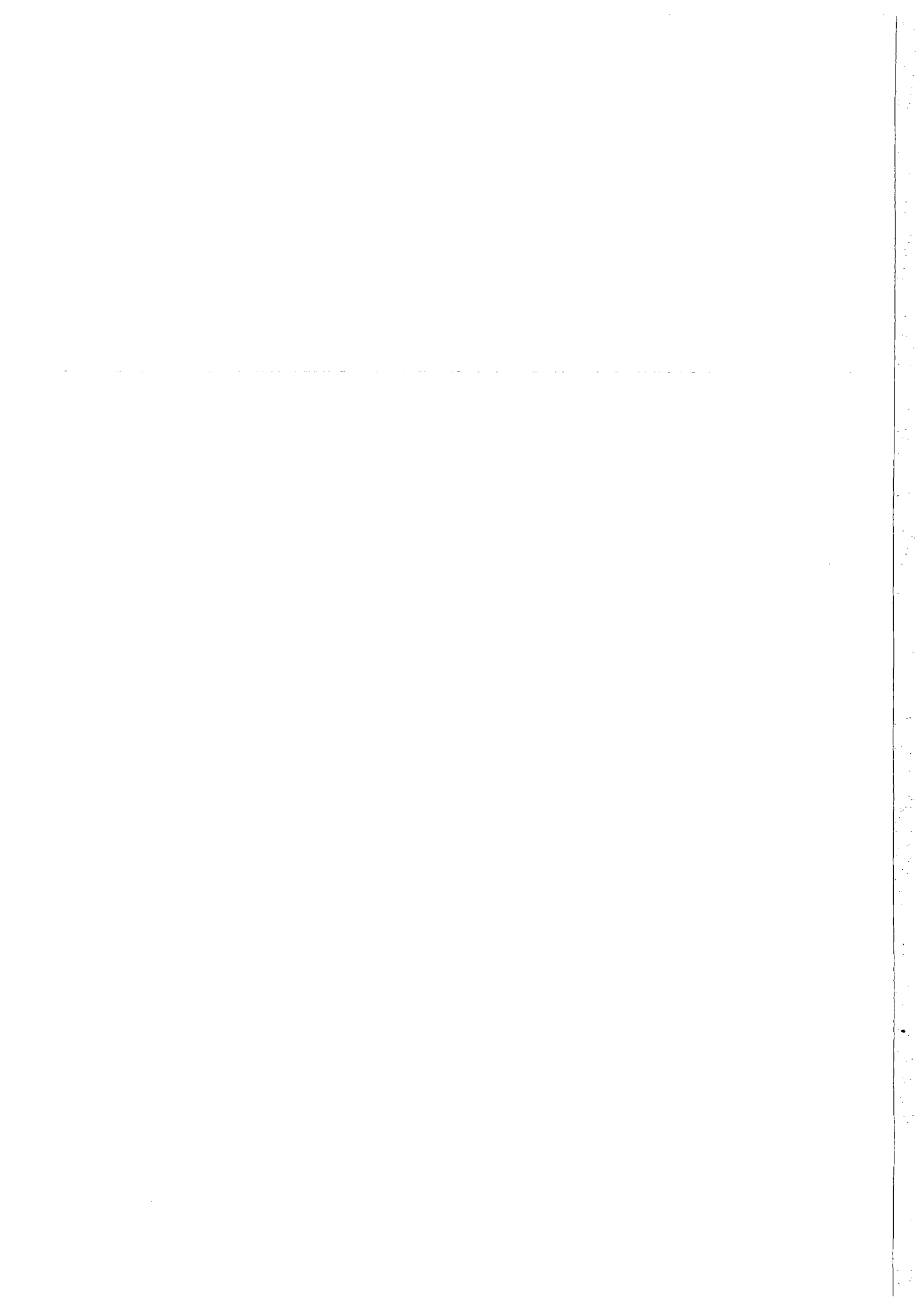
NORSAR Scientific Report No. 2-91/92

Semiannual Technical Summary

1 October 1991 – 31 March 1992

Kjeller, May 1992

APPROVED FOR PUBLIC RELEASE, DISTRIBUTION UNLIMITED



UNCLASSIFIED

SECURITY CLASSIFICATION OF THIS PAGE

REPORT DOCUMENTATION PAGE

1a. REPORT SECURITY CLASSIFICATION UNCLASSIFIED		1b. RESTRICTIVE MARKINGS NOT APPLICABLE	
2a. SECURITY CLASSIFICATION AUTHORITY NOT APPLICABLE		3. DISTRIBUTION/AVAILABILITY OF REPORT APPROVED FOR PUBLIC RELEASE DISTRIBUTION UNLIMITED	
2b. DECLASSIFICATION/DOWNGRADING SCHEDULE NOT APPLICABLE		5. MONITORING ORGANIZATION REPORT NUMBER(S) Scientific Report 2-91/92	
4. PERFORMING ORGANIZATION REPORT NUMBER(S) Scientific Report 2-91/92		7a. NAME OF MONITORING ORGANIZATION HQ/AFTAC/TTS	
6a. NAME OF PERFORMING ORGANIZATION NTNF/NORSAR	6b. OFFICE SYMBOL (if applicable)	7b. ADDRESS (City, State, and ZIP Code) Patrick AFB, FL 32925-6001	
6c. ADDRESS (City, State, and ZIP Code) Post Box 51 N-2007 Kjeller, Norway		9. PROCUREMENT INSTRUMENT IDENTIFICATION NUMBER	
8a. NAME OF FUNDING/SPONSORING ORGANIZATION Defense Advanced Research Projects Agency	8b. OFFICE SYMBOL (if applicable) NMRO	10. SOURCE OF FUNDING NUMBERS	
8c. ADDRESS (City, State, and ZIP Code) 3701 N. Fairfax Dr. #717 Arlington, VA 22203-1714		PROGRAM ELEMENT NO. R&D	PROJECT NO. NORSAR Phase 3
		TASK NO. SOW Task 5.0	WORK UNIT ACCESSION NO. Seq.no. 003A2

11. TITLE (Include Security Classification)
SEMIANNUAL TECHNICAL SUMMARY, 1 OCTOBER 1991 - 31 MARCH 1992 (UNCLASSIFIED)

12. PERSONAL AUTHOR(S)

13a. TYPE OF REPORT Scientific Summary	13b. TIME COVERED FROM 1 Oct 91 TO 31 Mar 92	14. DATE OF REPORT (Year, Month, Day) May 1992	15. PAGE COUNT 152
---	---	---	-----------------------

16. SUPPLEMENTARY NOTATION
NOT APPLICABLE

17. COSATI CODES			18. SUBJECT TERMS (Continue on reverse if necessary and identify by block number) NORSAR, Norwegian Seismic Array
FIELD	GROUP	SUB-GROUP	
8	11		

19. ABSTRACT (Continue on reverse if necessary and identify by block number)

This Semiannual Technical Summary describes the operation, maintenance and research activities at the Norwegian Seismic Array (NORSAR), the Norwegian Regional Seismic Array (NORESS) and the Arctic Regional Seismic Array (ARCESS) for the period 1 October 1991 - 31 March 1992. Statistics are also presented for additional seismic stations, which through cooperative agreements with institutions in the host countries provide continuous data to the NORSAR Data Processing Center (NPDC). These stations comprise the Finnish Experimental Seismic Array (FINESA), the German Experimental Seismic Array (GERESS), and two 3-component stations in Poland: Ksiaz and Stary Folwark.

(cont.)

20. DISTRIBUTION/AVAILABILITY OF ABSTRACT <input type="checkbox"/> UNCLASSIFIED/UNLIMITED <input type="checkbox"/> SAME AS RPT. <input type="checkbox"/> DTIC USERS		21. ABSTRACT SECURITY CLASSIFICATION	
22a. NAME OF RESPONSIBLE INDIVIDUAL Mr. Mike Baker		22b. TELEPHONE (Include Area Code) (407) 494-7665	22c. OFFICE SYMBOL AFTAC/TTS

Abstract (cont.)

This Semiannual Report also presents statistics from operation of the Intelligent Monitoring System (IMS). The IMS has been operated in an experimental mode, and the performance has been very satisfactory. Since October 1991, a new version of the IMS that accepts data from an arbitrary number of arrays and single 3-component stations has been operated.

The NORSAR Detection Processing system has been operated throughout the period with an average uptime of 99.6% as compared to 99.3% for the previous reporting period. A total of 1944 seismic events have been reported in the NORSAR monthly seismic bulletin. The performance of the continuous alarm system and the automatic bulletin transfer by telex to AFTAC has been satisfactory. The system for direct retrieval of NORSAR waveform data through an X.25 connection has been tested successfully for acquiring such data by AFTAC. Processing of requests for full NORSAR and regional array data on magnetic tapes has progressed according to established schedules.

On-line detection processing and data recording at the NORSAR Data Processing Center (NDPC) of NORESS, ARCESS, FINESA and GERESS data have been conducted throughout the period. Data from the two stations in Poland have been recorded and processed in an experimental mode. Monthly processing statistics for the arrays as well as results of the IMS analysis for the reporting period are given.

There have been no modifications made to the NORSAR data acquisition system. The process of evaluating and testing technical options for refurbishment of the array is continuing.

Maintenance activities in the period comprise preventive/corrective maintenance in connection with all the NORSAR subarrays, NORESS and ARCESS. In addition, the maintenance center has been involved with occasional maintenance of equipment for FINESA and work in connection with the two stations in Poland. Other activities have involved testing of the NORSAR communications systems, and field studies at sites in Spitsbergen and the Kola Peninsula.

Starting 1 October 1991, an effort has begun to carry out a complete technical refurbishment of the NORSAR array. This project is funded jointly by AFTAC, DARPA and NTNF. During the reporting period, efforts have focused upon continuing our evaluation of technical options for field instrumentation, in particular state-of-the-art A/D converters, data acquisition and synchronization devices. During the next few months, we plan to test several such systems under realistic operating conditions in the field. Initial testing of some systems has already started. When these studies have been completed, a recommendation for a system to be installed will be presented to the funding agencies.

Summaries of nine scientific contributions are presented in Chapter 7 of this report.

Section 7.1 contains an evaluation of global event detection performance during the recently conducted GSETT-2 experiment. The NEIC monthly bulletins have been used as a reference. The global 90% detection threshold is estimated at $m_b = 4.7$, in terms of NEIC

network magnitudes. As expected, the 90% threshold is significantly lower for the northern hemisphere (4.4) than for the southern hemisphere (5.0). A detailed discussion of the largest undetected events in each hemisphere is given. It is pointed out that detection threshold is closely tied to required location accuracy: The more relaxed the location requirements are, the "better" the detection capability will appear to be.

Section 7.2 is a case study of regional detection and location performance during GSETT-2. Using the bulletin of the Seismological Institute, University of Helsinki, as a reference, it is shown that the 90% detection threshold for the GSETT-2 system in Fennoscandia/NW Russia is close to magnitude 2.5 in terms of the duration magnitudes used in that bulletin. A similar study for the western and northern regions of Norway, using the University of Bergen bulletins as a reference, has likewise resulted in an estimated 90% threshold close to magnitude 2.5. The GSETT-2 location accuracy for Fennoscandia/NW Russia has also been evaluated, using known mining sites and other information for a reference. The results show that in a region with dense coverage of high quality arrays such as Fennoscandia, an excellent monitoring capability may be achieved.

Section 7.3 contains a third GSETT-2 detectability study. This study has been conducted for the W. Caucasus region, using as a data base the aftershock sequence from the 29 April 1991 W. Caucasus earthquake. A local bulletin was provided by the Obninsk seismological center for this purpose. We have found that the GSETT-2 detectability is significantly better than that of the NEIC in this particular case (average improvement 0.3 magnitude units). The difference is the largest during the first few hours after the main shock. This indicates that the GSETT-2 system succeeded in alleviating to some extent one of the main monitoring problems for a world-wide network (reduced performance following large earthquakes).

Section 7.4 presents a three-dimensional velocity modelling of the structure beneath the NORSAR array. Six layers down to a depth of 129 km are modeled by both seismic tomography and diffraction tomography. The models are used to construct travel time correction tables for NORSAR P-waves, and the results are compared to real data.

Section 7.5 describes results from a 12-day study of a network of 3 microarrays in Fennoscandia, comprising the center instrument and A-ring of each of the three regional arrays NORESS, ARCESS and FINESA. For each microarray, individual detection processing and f-k analysis are performed, and the generalized beamforming (GBF) technique is used to associate phases automatically to form regional seismic events. By comparison to the full Fennoscandian array network, it is found that successful automatic phase association and regional event location can be achieved using a sparse network of seismic microarrays (interstation distance about 1000 km).

Section 7.6 presents statistics on the number of detections versus apparent slowness for each of the four regional arrays NORESS, ARCESS, GERESS and FINESA. In a series of 3-D plots, all detections reported by each individual array during a 6-month period are displayed. Detections with dominant frequencies above and below 6 Hz are shown separately. The differences between the arrays are discussed, and the reasons for the main peaks in the diagrams are pointed out.

Section 7.7 presents a new array controller (NORAC) developed at NORSAR. The main design idea has been to develop an inexpensive, simple unit that can handle data from a variety of digitizers and that satisfies a number of very specific design requirements not met by currently available systems. The first prototype of NORAC has been tested successfully for a period of 2 months, and will be installed in the planned Apatity high-frequency array.

Section 7.8 presents a summary report on a one-month experiment in continuous threshold monitoring of Novaya Zemlya. Starting 1 February 1992, we began collecting continuous statistics for the Threshold Monitoring performance of NORESS, ARCESS and FINESA with regard to the northern Novaya Zemlya test site. The purpose was to demonstrate, in an experimental mode, the practical application of this monitoring method. Detailed statistics for the month of February have been compiled, and confirm previous reports on the TM capability. Within the confidence limits inherent in the method, we are able to document that no seismic event of $m_b \geq 2.6$ occurred at that test site during the month of February. Only for 0.12% of the time (i.e., 43 minutes during February) did the threshold exceed 2.6, and these occurrences could all be "explained" as resulting from one of the three conditions a) a "large" identified teleseismic event, b) a "large" identified regional event or c) a short outage of the most important array (ARCESS).

Section 7.9 presents a study correlating the number of signal detections and temperature at the two arrays NORESS and ARCESS. In many cases a clear correlation can be seen, for example with increasing number of detections during nighttime. At ARCESS, there is a large increase in detections when the frost occurs in the fall and again in the springtime. At NORESS, there are periods with considerable increase in detection rate not related to temperature, but instead caused by increased water flow in a nearby river.

AFTAC Project Authorization	:	T/9141/B/PKP
ARPA Order No.	:	4138 AMD # 16
Program Code No.	:	0F10
Name of Contractor	:	Royal Norwegian Council for Scientific and Industrial Research (NTNF)
Effective Date of Contract	:	1 Oct 1988
Contract Expiration Date	:	30 Sep 1993
Project Manager	:	Frode Ringdal (06) 81 71 21
Title of Work	:	The Norwegian Seismic Array (NORSAR) Phase 3
Amount of Contract	:	\$ 9,954,194
Contract Period Covered by Report	:	1 October 1991 - 31 March 1992

The views and conclusions contained in this document are those of the authors and should not be interpreted as necessarily representing the official policies, either expressed or implied, of the Defense Advanced Research Projects Agency, the Air Force Technical Applications Center or the U.S. Government.

This research was supported by the Advanced Research Projects Agency of the Department of Defense and was monitored by AFTAC, Patrick AFB, FL32925, under contract no. F08606-89-C-0005.

NORSAR Contribution No. 466

Table of Contents

	<u>Page</u>
1. Summary	1
2. NORSAR Operation	4
2.1 Detection processor (DP) operation	4
2.2 Array communications	8
2.3 NORSAR event detection operation	11
3. Operation of Regional Arrays	16
3.1 Recording of NORESS data at NDPC, Kjeller	16
3.2 Recording of ARCESS data at NDPC, Kjeller	19
3.3 Recording of FINESA data at NDPC, Kjeller	22
3.4 Event detection operation	24
3.5 IMS operation	45
3.6 GBF operation	46
4. Improvements and Modifications	47
4.1 NORSAR	47
4.2 NORESS/ARCESS/FINESA/GERESS/Poland	48
5. Maintenance Activities	50
5.1 Activities in the field and at the Maintenance Center	50
5.2 Array status	54
6. Documentation Developed	55
7. Summary of Technical Reports / Papers Published	56
7.1 Global event detection performance during GSETT-2	56
7.2 Regional detection and location performance during GSETT-2 Initial results for the Fennoscandian array network	66
7.3 GSETT-2 evaluation: Detection of aftershocks from the W. Caucasus earthquake of 29 April 1991	79
7.4 Travel time corrections for a 3-D velocity model beneath the NORSAR array	86
7.5 Automatic phase association and event location using data from a network of seismic microarrays	95
7.6 Distribution in slowness space of regional array detections	121
7.7 NORAC: A new array controller	128
7.8 Continuous seismic threshold monitoring of the northern Novaya Zemlya test site; long-term operational characteristics	133
7.9 Correlation between temperature and number of detections	147

1 Summary

This Semiannual Technical Summary describes the operation, maintenance and research activities at the Norwegian Seismic Array (NORSAR), the Norwegian Regional Seismic Array (NORESS) and the Arctic Regional Seismic Array (ARCESS) for the period 1 October 1991 - 31 March 1992. Statistics are also presented for additional seismic stations, which through cooperative agreements with institutions in the host countries provide continuous data to the NORSAR Data Processing Center (NPDC). These stations comprise the Finnish Experimental Seismic Array (FINESA), the German Experimental Seismic Array (GERESS), and two 3-component stations in Poland: Ksiaz and Stary Folwark.

This Semiannual Report also presents statistics from operation of the Intelligent Monitoring System (IMS). The IMS has been operated in an experimental mode, and the performance has been very satisfactory. Since October 1991, a new version of the IMS that accepts data from an arbitrary number of arrays and single 3-component stations has been operated.

The NORSAR Detection Processing system has been operated throughout the period with an average uptime of 99.6% as compared to 99.3% for the previous reporting period. A total of 1944 seismic events have been reported in the NORSAR monthly seismic bulletin. The performance of the continuous alarm system and the automatic bulletin transfer by telex to AFTAC has been satisfactory. The system for direct retrieval of NORSAR waveform data through an X.25 connection has been tested successfully for acquiring such data by AFTAC. Processing of requests for full NORSAR and regional array data on magnetic tapes has progressed according to established schedules.

On-line detection processing and data recording at the NORSAR Data Processing Center (NPDC) of NORESS, ARCESS, FINESA and GERESS data have been conducted throughout the period. Data from the two stations in Poland have been recorded and processed in an experimental mode. Monthly processing statistics for the arrays as well as results of the IMS analysis for the reporting period are given.

There have been no modifications made to the NORSAR data acquisition system. The process of evaluating and testing technical options for refurbishment of the array is continuing.

Maintenance activities in the period comprise preventive/corrective maintenance in connection with all the NORSAR subarrays, NORESS and ARCESS. In addition, the maintenance center has been involved with occasional maintenance of equipment for FINESA and work in connection with the two stations in Poland. Other activities have involved testing of the NORSAR communications systems, and field studies at sites in Spitsbergen and the Kola Peninsula.

Starting 1 October 1991, an effort has begun to carry out a complete technical refurbishment of the NORSAR array. This project is funded jointly by AFTAC, DARPA and NTNF. During the reporting period, efforts have focused upon continuing our evaluation

of technical options for field instrumentation, in particular state-of-the-art A/D converters, data acquisition and synchronization devices. During the next few months, we plan to test several such systems under realistic operating conditions in the field. Initial testing of some systems has already started. When these studies have been completed, a recommendation for a system to be installed will be presented to the funding agencies.

Summaries of nine scientific contributions are presented in Chapter 7 of this report.

Section 7.1 contains an evaluation of global event detection performance during the recently conducted GSETT-2 experiment. The NEIC monthly bulletins have been used as a reference. The global 90% detection threshold is estimated at $m_b = 4.7$, in terms of NEIC network magnitudes. As expected, the 90% threshold is significantly lower for the northern hemisphere (4.4) than for the southern hemisphere (5.0). A detailed discussion of the largest undetected events in each hemisphere is given. It is pointed out that detection threshold is closely tied to required location accuracy: The more relaxed the location requirements are, the "better" the detection capability will appear to be.

Section 7.2 is a case study of regional detection and location performance during GSETT-2. Using the bulletin of the Seismological Institute, University of Helsinki, as a reference, it is shown that the 90% detection threshold for the GSETT-2 system in Fennoscandia/NW Russia is close to magnitude 2.5 in terms of the duration magnitudes used in that bulletin. A similar study for the western and northern regions of Norway, using the University of Bergen bulletins as a reference, has likewise resulted in an estimated 90% threshold close to magnitude 2.5. The GSETT-2 location accuracy for Fennoscandia/NW Russia has also been evaluated, using known mining sites and other information for a reference. The results show that in a region with dense coverage of high quality arrays such as Fennoscandia, an excellent monitoring capability may be achieved.

Section 7.3 contains a third GSETT-2 detectability study. This study has been conducted for the W. Caucasus region, using as a data base the aftershock sequence from the 29 April 1991 W. Caucasus earthquake. A local bulletin was provided by the Obninsk seismological center for this purpose. We have found that the GSETT-2 detectability is significantly better than that of the NEIC in this particular case (average improvement 0.3 magnitude units). The difference is the largest during the first few hours after the main shock. This indicates that the GSETT-2 system succeeded in alleviating to some extent one of the main monitoring problems for a world-wide network (reduced performance following large earthquakes).

Section 7.4 presents a three-dimensional velocity modelling of the structure beneath the NORSAR array. Six layers down to a depth of 129 km are modeled by both seismic tomography and diffraction tomography. The models are used to construct travel time correction tables for NORSAR P-waves, and the results are compared to real data.

Section 7.5 describes results from a 12-day study of a network of 3 microarrays in Fennoscandia, comprising the center instrument and A-ring of each of the three regional arrays NORESS, ARCESS and FINESA. For each microarray, individual detection processing and f-k analysis are performed, and the generalized beamforming (GBF) technique is used

to associate phases automatically to form regional seismic events. By comparison to the full Fennoscandian array network, it is found that successful automatic phase association and regional event location can be achieved using a sparse network of seismic microarrays (interstation distance about 1000 km).

Section 7.6 presents statistics on the number of detections versus apparent slowness for each of the four regional arrays NORESS, ARCESS, GERESS and FINESA. In a series of 3-D plots, all detections reported by each individual array during a 6-month period are displayed. Detections with dominant frequencies above and below 6 Hz are shown separately. The differences between the arrays are discussed, and the reasons for the main peaks in the diagrams are pointed out.

Section 7.7 presents a new array controller (NORAC) developed at NORSAR. The main design idea has been to develop an inexpensive, simple unit that can handle data from a variety of digitizers and that satisfies a number of very specific design requirements not met by currently available systems. The first prototype of NORAC has been tested successfully for a period of 2 months, and will be installed in the planned Apatity high-frequency array.

Section 7.8 presents a summary report on a one-month experiment in continuous threshold monitoring of Novaya Zemlya. Starting 1 February 1992, we began collecting continuous statistics for the Threshold Monitoring performance of NORESS, ARCESS and FINESA with regard to the northern Novaya Zemlya test site. The purpose was to demonstrate, in an experimental mode, the practical application of this monitoring method. Detailed statistics for the month of February have been compiled, and confirm previous reports on the TM capability. Within the confidence limits inherent in the method, we are able to document that no seismic event of $m_b \geq 2.6$ occurred at that test site during the month of February. Only for 0.12% of the time (i.e., 43 minutes during February) did the threshold exceed 2.6, and these occurrences could all be "explained" as resulting from one of the three conditions a) a "large" identified teleseismic event, b) a "large" identified regional event or c) a short outage of the most important array (ARCESS).

Section 7.9 presents a study correlating the number of signal detections and temperature at the two arrays NORESS and ARCESS. In many cases a clear correlation can be seen, for example with increasing number of detections during nighttime. At ARCESS, there is a large increase in detections when the frost occurs in the fall and again in the springtime. At NORESS, there are periods with considerable increase in detection rate not related to temperature, but instead caused by increased water flow in a nearby river.

2 NORSAR Operation

2.1 Detection Processor (DP) operation

There have been 55 breaks in the otherwise continuous operation of the NORSAR online system within the 6-month reporting interval. The uptime percentage for the period is 99.6% as compared to 99.3% for the previous period.

Fig. 2.1.1 and the accompanying Table 2.1.1 both show the daily DP downtime for the days between 1 October 1991 and 31 March 1992. The monthly recording times and percentages are given in Table 2.1.2.

The breaks can be grouped as follows:

a)	Hardware failure	4
b)	Stops related to program work or error	1
c)	Hardware maintenance stops	5
d)	Power jumps and breaks	0
e)	TOD error correction	8
f)	Communication lines	21

The total downtime for the period was 19 hours and 42 minutes. The mean-time-between-failures (MTBF) was 4.6 days, as compared to 5.0 for the previous period.

J. Torstveit

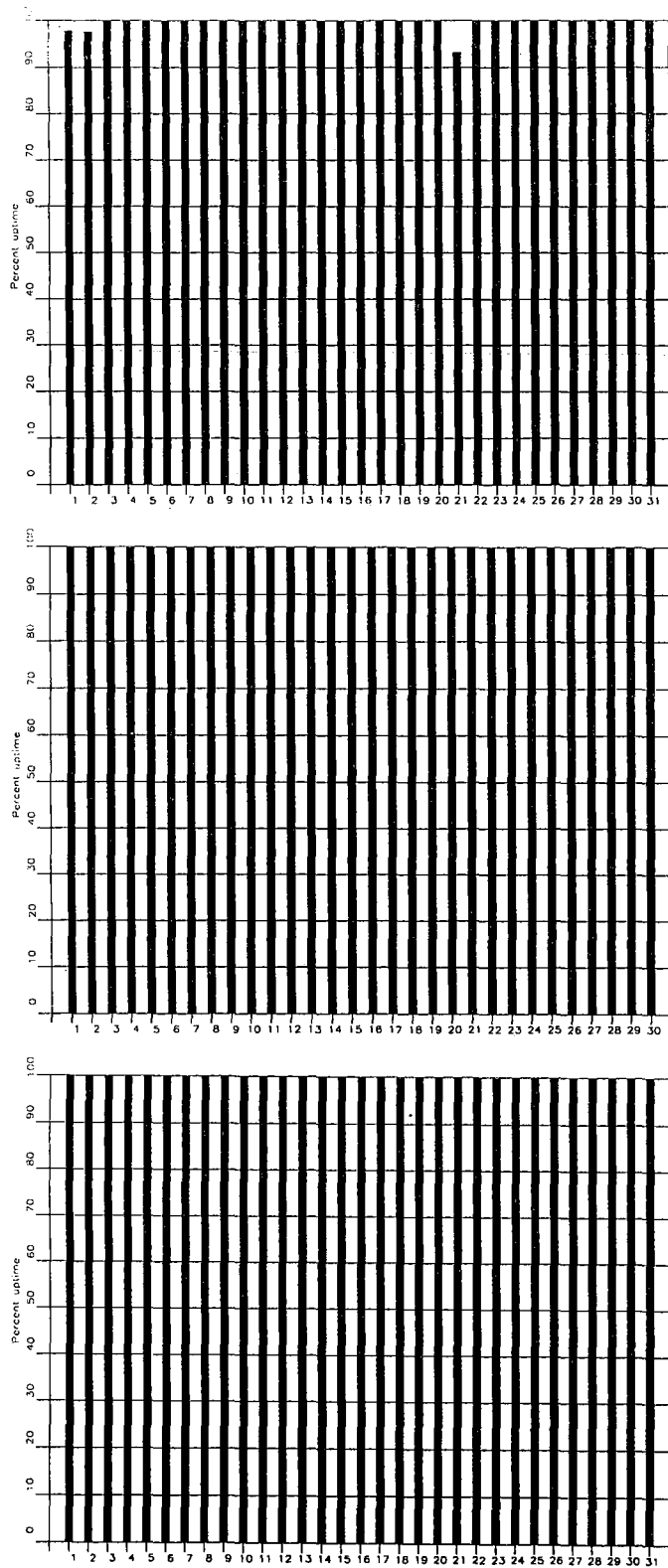


Fig. 2.1.1. Detection Processor uptime for October (top), November (middle) and December (bottom) 1991.

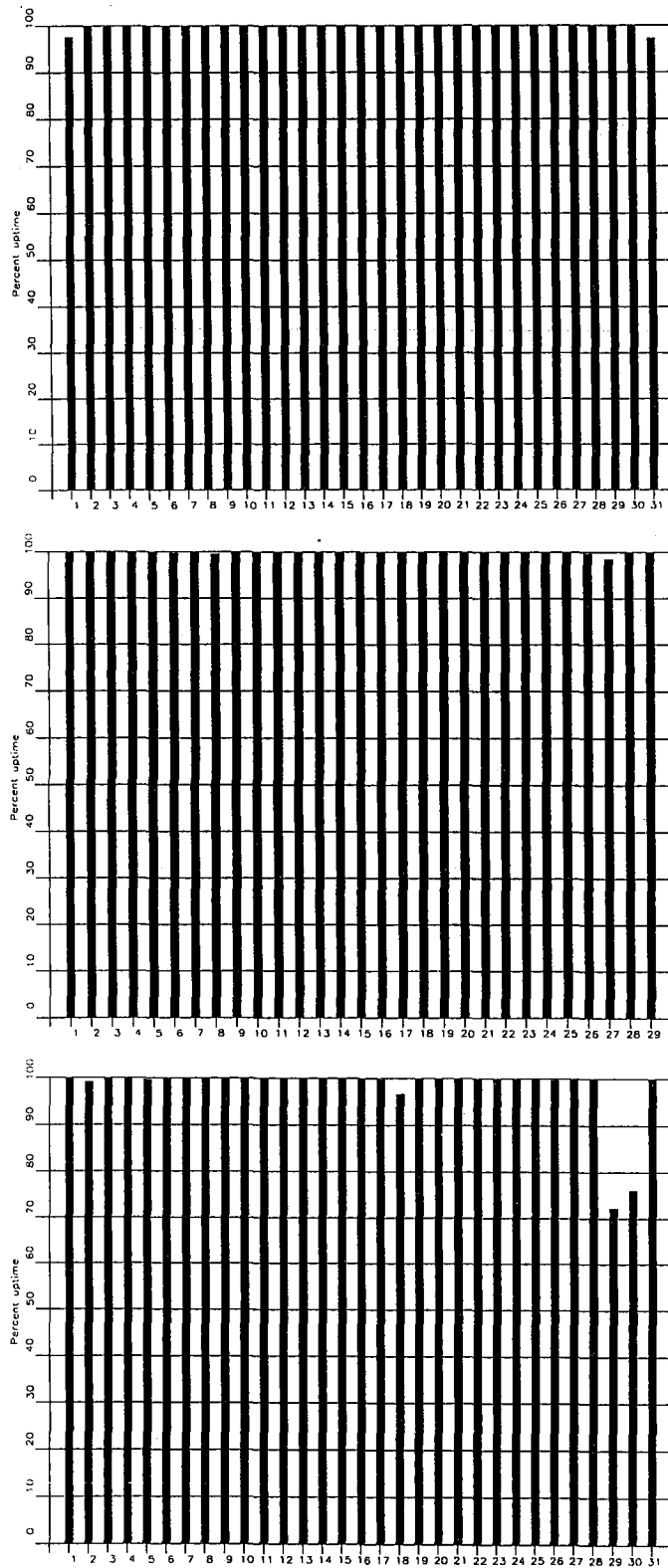


Fig. 2.1.1. Detection Processor uptime for January (top), February (middle) and March (bottom) 1992.

Date	Time	Cause
1 Oct	1226 - 1258	Hardware maintenance
2 Oct	0641 - 0715	Line failure
21 Oct	1000 - 1138	Line failure
1 Jan	1040 - 1114	Software work
31 Jan	0216 - 0256	Hardware failure
8 Feb	1011 - 1017	Hardware failure
27 Feb	0831 - 0854	Hardware maintenance
2 Mar	1033 - 1045	Hardware failure
18 Mar	0252 - 0340	Hardware failure
29 Mar	1720 -	Hardware failure
30 Mar	- 0452	

Table 2.1.1. The major downtimes in the period 1 October 1991 - 31 March 1992.

Month	DP Uptime Hours	DP Uptime %	No. of DP Breaks	No. of Days with Breaks	DP MTBF* (days)
Oct 91	741.07	99.62	7	7	3.9
Nov 91	719.51	99.98	3	3	7.5
Dec 91	695.17	99.96	5	5	5.2
Jan 92	742.27	99.80	8	8	3.4
Feb 92	743.13	99.89	8	6	3.2
Mar 92	730.23	98.17	8	7	3.4
		99.57	39	36	4.6

*Mean-time-between-failures = total uptime/no. of up intervals.

Table 2.1.2. Online system performance, 1 October 1991 - 31 March 1992.

2.2 Array communications

General

Table 2.2.1 reflects the performance of the communications system throughout the reporting period. The most common events which have affected the communications systems have been: Line outage (5), reduced line performance (2), Modcomp stop (2), bad communications cable (1), bad connection (1), SLEM (stuck) (1), and an inoperative Modcomp operator terminal (1).

Detailed Summary

October (weeks 40-44), 30.9-3.11.91

Most reliable performance for all systems weeks 40-42, partly week 44 (-06C). Week 43 01A, 02B and 06C were affected; 01A by a bad communications cable (23-25 Oct), resulting in low line level toward Kjeller (-32.0 dBm). 02B was affected by a bad connection between Lillestrøm and Kjeller (22-23 Oct). 27 Oct 06C changed status (NODATA). A Modcomp restart restored operation 28 October.

November (weeks 45-48), 4.11-1.12.91

Most reliable performance experienced in November 1991, although we had a short outage, approx. 20 mins., on 02C 12 Nov.

December (weeks 49-52), 2-29.12.91

Two communications systems were affected in December 1991: 03C 4-11.12 due to reduced line performance toward the subarray; 06C 5-9.12 probably also caused by reduced line performance. The remaining systems performed most satisfactorily

January (weeks 1-5), 30.12.91-2.2.92

Apart from a Modcomp stop approx. 56 minutes 31 January, all the systems have performed most satisfactorily.

February (weeks 6-9), 3.2-1.3.92

A stuck SLEM affected 06C 25-26 February. The remaining systems performed most satisfactorily.

March (weeks 10-13), 2-29.3.92

02C communications system was down 13-14 March, probably due to a line outage.

06C communications line went down 29 March at 1720 hrs GMT. Immediately afterwards (17.20.34 GMT), the Modcomp stopped, and we were not able to start it until the next day

at 0447 GMT. Service was requested, and between 1246 and 1333 GMT the Modcomp was down. A defective memory cooling fan was replaced. Also the operator terminal was replaced, as the old one failed during the attempts to restart the system.

O.A. Hansen

Sub-Arrays	Oct (5) 30.9-3.10.91	Nov (4) 4.10-1.12.91	Dec (4) 2.12-29.12.91	Jan (5) 30.12.91-2.2.92	Feb (4) 3.2-1.3.92	Mar (4) 2.3-29.3.92	Average 1/2 year
01A	0.021 ¹⁾	0.001	0.001	0.003	0.001	0.002 ⁷⁾	0.003
01B	0.001	0.001	0.003	0.003	0.0005	0.0005 ⁸⁾	0.001
02B	0.001 ²⁾	0.0007	0.0006	0.0005	0.0006	0.0006 ⁹⁾	0.0006
02C	0.002	0.050	0.001	0.001	0.001	0.0008 ¹⁰⁾	0.009
03C	0.003	0.001	3.574 ⁴⁾	0.003	0.004	0.004 ¹¹⁾	0.597
04C	0.018	0.0007	0.002	0.001	0.002	0.002 ¹²⁾	0.004
06C	0.025 ³⁾	0.0007	1.190 ⁵⁾	0.003	0.0008 ⁶⁾	0.0006 ¹³⁾	0.204
Aver	0.009	0.008	0.68	0.002	0.001	0.001	0.117

Figures representing error rate (in per cent) followed by number 1), 2), etc., are related to legend below.,

Table 2.2.1. Communications performance. The numbers represent error rates in per cent based on total transmitted frames/week (1 October 1991 - 31 March 1992).

- 1),2) Average 4 weeks (40-42.44)(40,42,44)
- 3),4),5),6),7),8),9),11),12),13) Average 3 weeks (40-42)(50,51,52)(50,51,52)(6,7,8)(10,11,12)(10,11,12)(10,11,12)(10,11,12)(10,11,12)
- 10) Average 2 weeks (10,12)

2.3 NORSAR Event Detection operation

In Table 2.3.1 some monthly statistics of the Detection and Event Processor operation are given. The table lists the total number of detections (DPX) triggered by the on-line detector, the total number of detections processed by the automatic event processor (EPX) and the total number of events accepted after analyst review (teleseismic phases, core phases and total).

	Total DPX	Total EPX	Accepted Phases			Daily
			P-phases	Core Phases	Sum	
Oct 91	11450	1429	231	83	314	10.1
Nov 91	13225	1454	188	69	257	8.6
Dec 91	13693	1715	446	63	509	16.4
Jan 92	12399	1465	203	53	256	8.3
Feb 92	12225	1249	204	46	250	8.6
Mar 92	11900	1389	289	69	358	11.5
			1561	383	1944	10.6

Table 2.3.1. Detection and Event Processor statistics, 1 October 1991 - 31 March 1992.

NORSAR Detections

The number of detections (phases) reported by the NORSAR detector during day 274 1991, through day 091 1992, was 75,589, giving an average of 413 detections per processed day (183 days processed). Table 2.3.2 shows daily and hourly distribution of detections for NORSAR.

B. Paulsen Gammelby

T. Schøyen

NAO .DPX Hourly distribution of detections

Day	00	01	02	03	04	05	06	07	08	09	10	11	12	13	14	15	16	17	18	19	20	21	22	23	Sum	Date		
77	20	17	26	30	24	16	16	7	30	9	18	18	15	11	20	15	31	12	14	13	19	10	21	17	429	Mar 17	Tuesday	
78	26	19	15	19	22	14	10	14	15	23	13	11	17	12	17	2	14	20	13	14	21	12	14	17	374	Mar 18	Wednesday	
79	13	22	18	4	12	10	20	9	8	13	15	20	34	16	11	10	4	14	8	20	22	7	13	13	336	Mar 19	Thursday	
80	10	13	25	21	19	19	16	4	10	12	10	5	13	14	16	13	8	11	15	9	7	14	8	17	309	Mar 20	Friday	
81	17	15	12	18	12	7	11	13	11	11	14	15	12	12	11	14	21	9	10	10	10	13	14	13	23	318	Mar 21	Saturday
82	20	25	27	15	33	15	14	19	23	23	17	18	27	10	11	19	21	14	17	19	14	16	21	19	457	Mar 22	Sunday	
83	17	23	30	14	19	12	10	12	7	4	10	5	12	15	10	12	16	14	9	11	12	11	15	18	318	Mar 23	Monday	
84	17	22	21	16	20	15	3	2	8	6	7	0	13	12	6	14	6	13	8	14	15	11	8	17	274	Mar 24	Tuesday	
85	12	9	14	15	11	6	1	6	13	3	19	4	22	5	9	18	21	21	13	12	9	18	22	10	293	Mar 25	Wednesday	
86	10	13	11	11	6	8	2	7	2	2	2	25	7	17	20	10	20	20	11	11	13	8	18	26	280	Mar 26	Thursday	
87	21	17	23	18	30	18	5	6	9	9	22	16	22	19	21	21	13	14	26	34	25	24	23	21	457	Mar 27	Friday	
88	22	18	25	27	17	26	15	18	20	22	19	16	16	15	16	14	27	16	20	21	14	20	24	16	464	Mar 28	Saturday	
89	26	19	17	16	30	19	22	26	22	11	13	15	20	17	12	11	11	3	0	0	0	0	0	0	310	Mar 29	Sunday	
90	0	0	0	0	12	10	11	15	5	8	11	21	8	2	15	9	6	6	20	16	21	14	17	11	238	Mar 30	Monday	
91	15	22	17	20	11	7	11	5	15	25	6	16	32	18	10	20	19	23	10	9	10	21	20	18	380	Mar 31	Tuesday	
NAO	00	01	02	03	04	05	06	07	08	09	10	11	12	13	14	15	16	17	18	19	20	21	22	23				
Sum	3850	3729	3281	2333	2631	2687	3078	2949	3173	3097	3307	3466																
	3554	3791	3696	2612	2483	2686	3393	3056	3179	3040	3161	3366	75598	Total sum														
183	19	21	21	20	20	18	14	13	14	14	15	15	19	17	17	16	17	17	17	17	17	18	18	19	413	Total average		
128	19	20	20	20	20	16	12	10	11	12	13	13	18	16	16	15	16	16	15	16	16	17	18	19	385	Average workdays		
55	20	22	21	21	22	22	19	20	19	20	19	18	20	19	18	20	21	20	20	19	19	21	20	20	479	Average weekends		

Table 2.3.2. Daily and hourly distribution of NORSAR detections. For each day is shown number of detections within each hour of the day and number of detections for that day. The end statistics give total number of detections distributed for each hour and the total sum of detections during the period. The averages show number of processed days, hourly distribution and average per processed day.

3 Operation of regional arrays

3.1 Recording of NORESS data at NDPC, Kjeller

Table 3.1.1 lists the main outage times and reasons, and as can be seen the main reasons for the outages are transmission line failures. All outages were of relatively short duration, however.

The average recording time was 99.78% as compared to 89.89% during the previous reporting period.

Date	Time	Cause
04 Oct	1049 - 1059	Transmission line failure
04 Oct	1237 - 1253	Transmission line failure
14 Nov	0945 - 0955	Transmission line failure
14 Nov	2253 -	Transmission line failure
15 Nov	- 0006	
12 Dec	1306 - 1313	Transmission line failure
20 Dec	0021 - 0116	Transmission line failure
03 Jan	1033 - 1225	Testing hardware/software
15 Jan	1121 - 1137	Transmission line failure
24 Jan	1233 - 1256	Hub failure
06 Feb	0210 - 0223	Transmission line failure
21 Feb	0000 - 0026	Transmission line failure
27 Feb	0915 - 1001	Transmission line failure
10 Mar	0916 - 0936	Transmission line failure

Table 3.1.1. Interruptions in recording of NORESS data at NDPC, 1 October 1991 - 31 March 1992.

Monthly uptimes for the NORESS on-line data recording task, taking into account all factors (field installations, transmission line, data center operation) affecting this task were as follows:

October	:	99.86
November	:	99.74
December	:	99.83
January	:	99.53
February	:	99.77
March	:	99.92

Fig. 3.1.1 shows the uptime for the data recording task, or equivalently, the availability of NORESS data in our tape archive, on a day-by-day basis, for the reporting period.

J. Torstveit

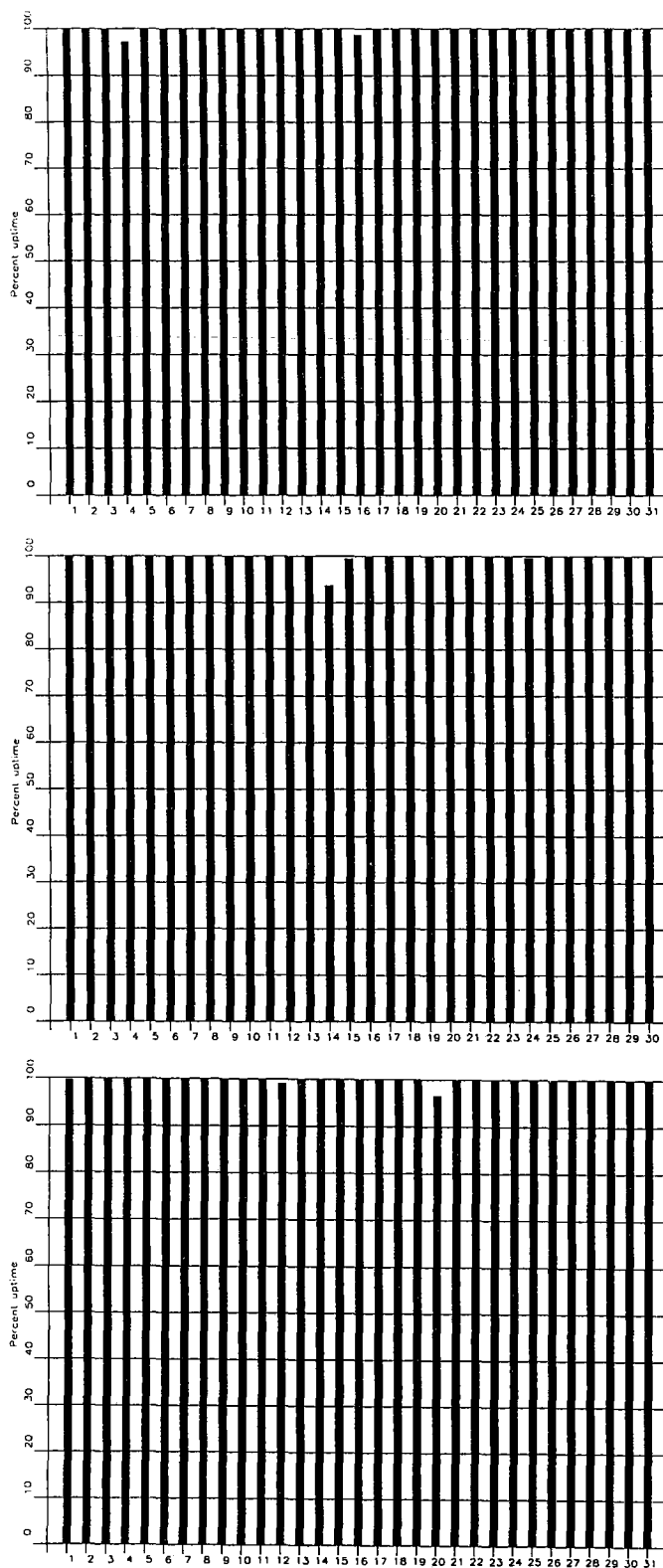


Fig. 3.1.1. NORESS data recording uptime for October (top), November (middle) and December (bottom) 1991.

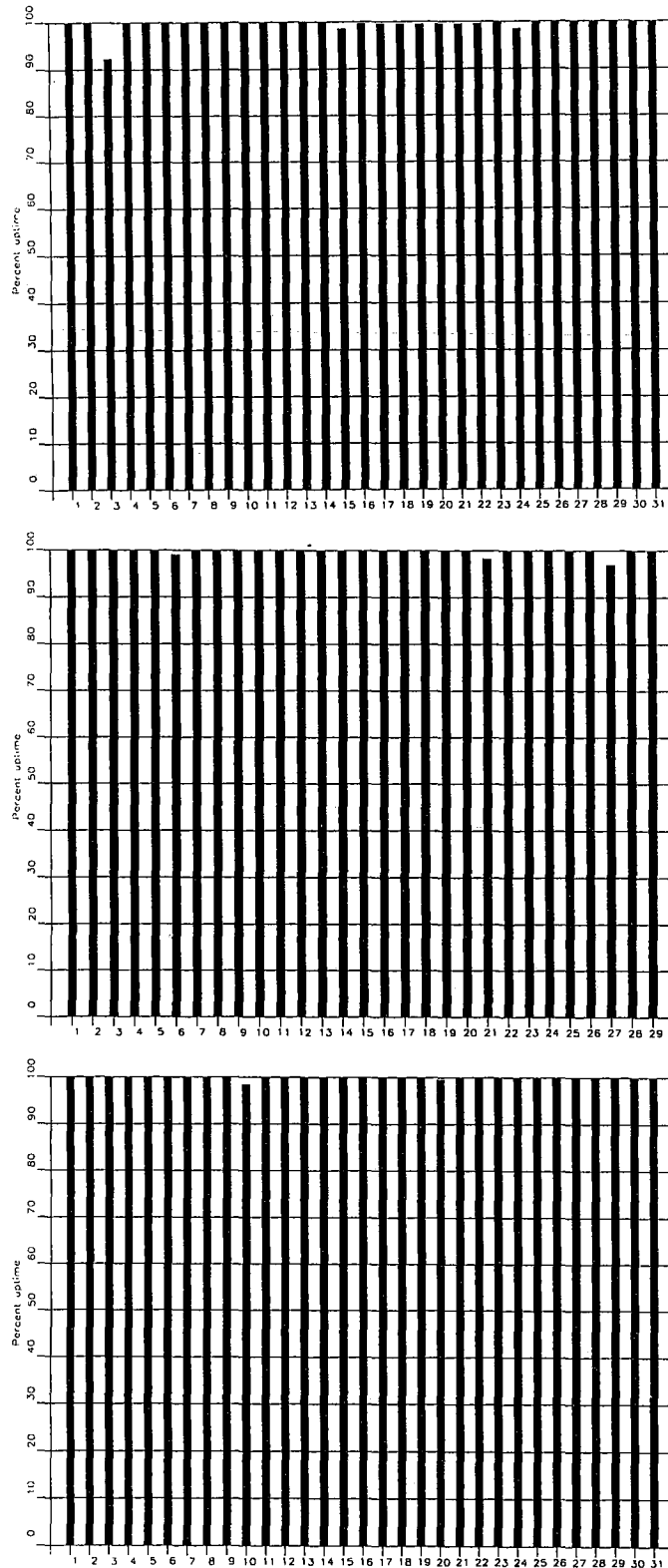


Fig. 3.1.1. (cont.) NORESS data recording uptime for January (top), February (middle) and March (bottom) 1992.

3.2 Recording of ARCESS data at NDPC, Kjeller

Table 3.2.1 lists the main outage times and reasons. The main contributing factor is a power break that resulted from a severe storm on 21 January.

The average recording time was 99.28 % as compared to 97.32% for the previous reporting period..

Date	Time	Cause
07 Dec	1806 - 1940	Hardware failure NDPC
31 Dec	2311 - 0000	Software failure NDPC
21 Jan	1039 -	Power break HUB
22 Jan	- 1200	Power break HUB

Table 3.2.1. The main interruptions in recording of ARCESS data at NDPC, 1 October 1991 - 31 March 1992.

Monthly uptimes for the ARCESS on-line data recording task, taking into account all factors (field installations, transmissions line, data center operation) affecting this task were as follows:

October	:	99.99%
November	:	99.91%
December	:	99.68%
January	:	96.31%
February	:	99.93%
March	:	99.86%

Fig. 3.2.1. shows the uptime for the data recording task, or equivalently, the availability of ARCESS data in our tape archive, on a day-by-day basis, for the reporting period.

J. Torstveit

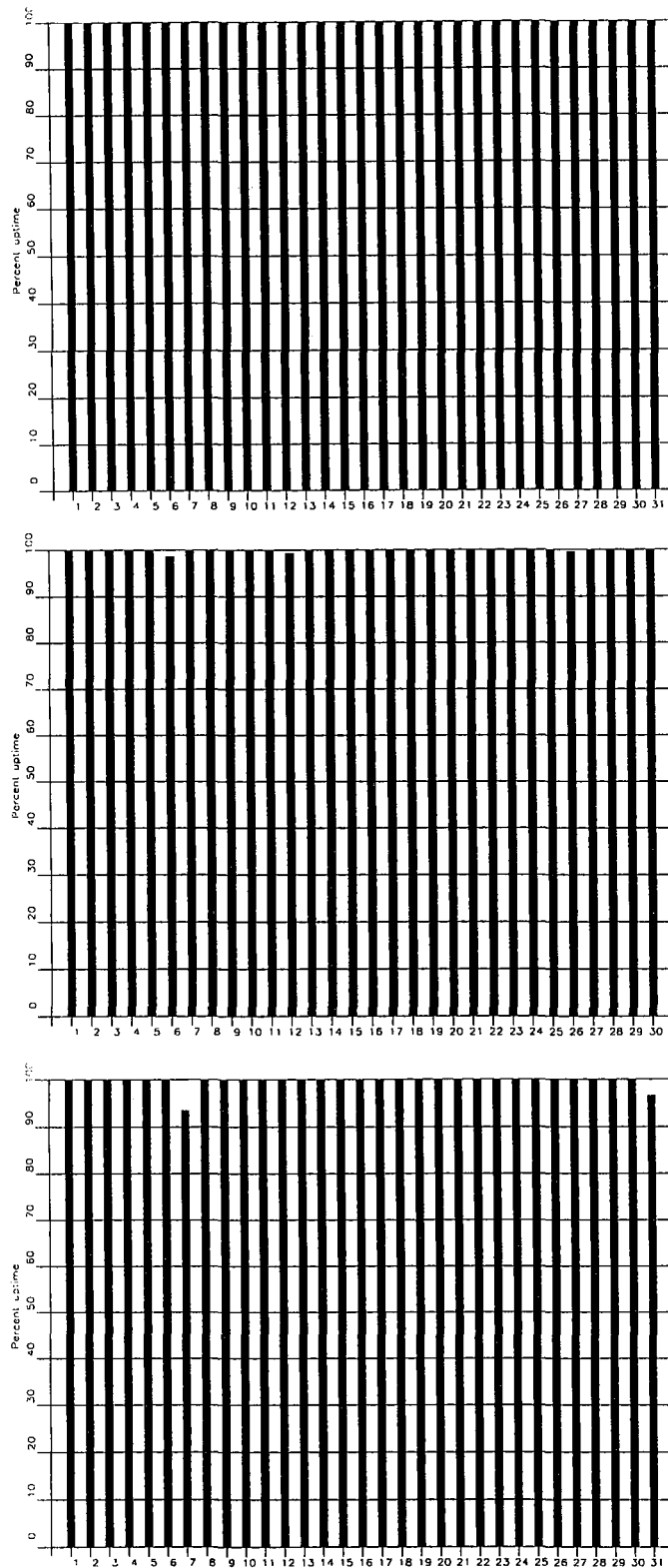


Fig. 3.2.1. ARCESS data recording uptime for October (top), November (middle) and December (bottom) 1991.

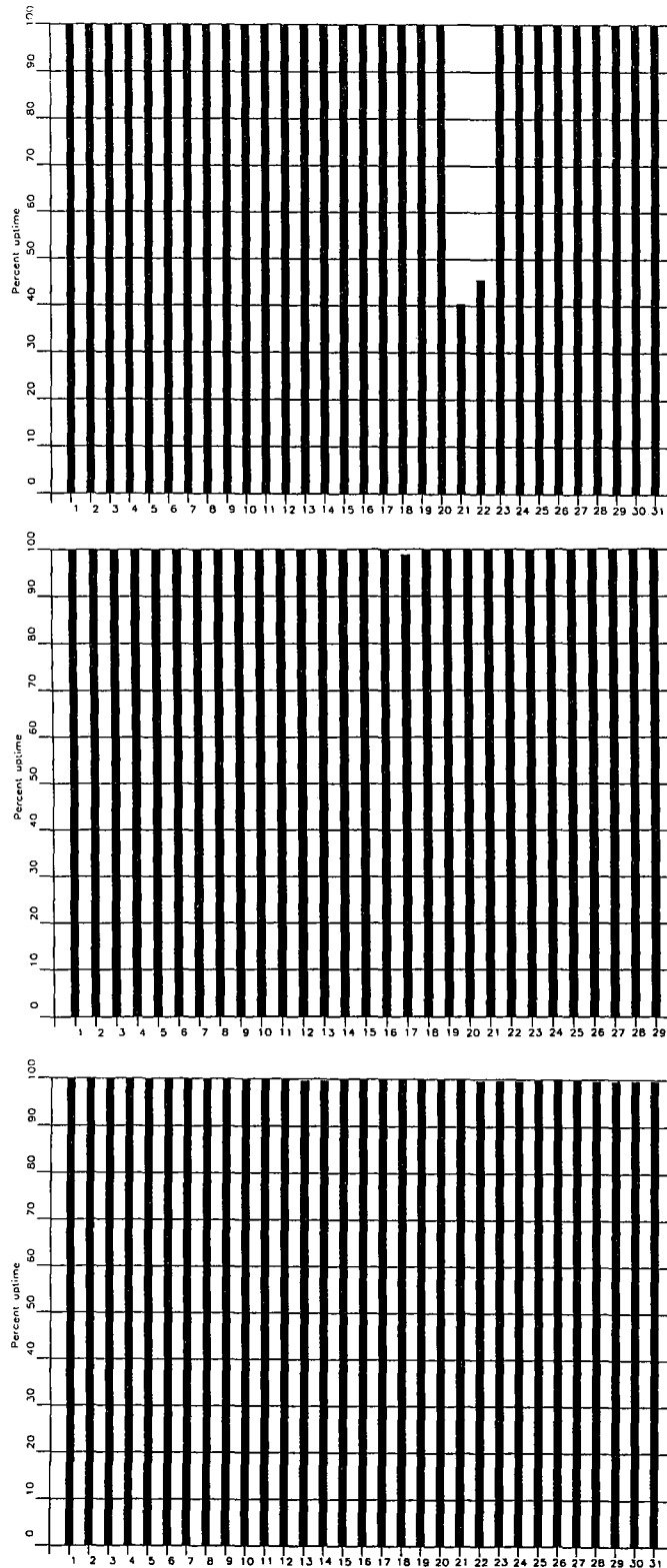


Fig. 3.2.1. ARCESS data recording uptime for January (top), February (middle) and March (bottom) 1992.

3.3 Recording of FINESA data at NDPC, Kjeller

The average recording time was 95.5% as compared to 66.2% for the previous period. As can be seen from Table 3.3.1 below, the only reason for the downtime is transmission line failure.

Date	Time	Cause
23 Oct	0928 -	Transmission line failure
31 Oct	- 1134	Transmission line failure
05 Jan	1802 - 1834	Transmission line failure
06 Jan	1637 - 1657	Transmission line failure
06 Jan	1712 - 1719	Transmission line failure
06 Jan	1805 - 1811	Transmission line failure
07 Jan	1045 - 1055	Transmission line failure
07 Jan	1240 - 1249	Transmission line failure
07 Jan	1253 - 1259	Transmission line failure
07 Jan	2011 - 2016	Transmission line failure
24 Mar	0449 - 0722	Transmission line failure

Table 3.3.1. The main interruptions in recording of FINESA data at NDPC, 1 October 1991 - 31 March 1992.

Monthly uptimes for the FINESA on-line data recording task, taking into account all factors (field installations, transmission lines, data center operation) affecting this task were as follows:

October	:	74.23%
November	:	99.97%
December	:	99.89%
January	:	99.56%
February	:	99.96%
March	:	99.59%

Fig. 3.3.1 shows the uptime for the data recording task, or equivalently, the availability of FINESA data in our tape archive, on a day-by-day basis, for the reporting period.

J. Torstveit

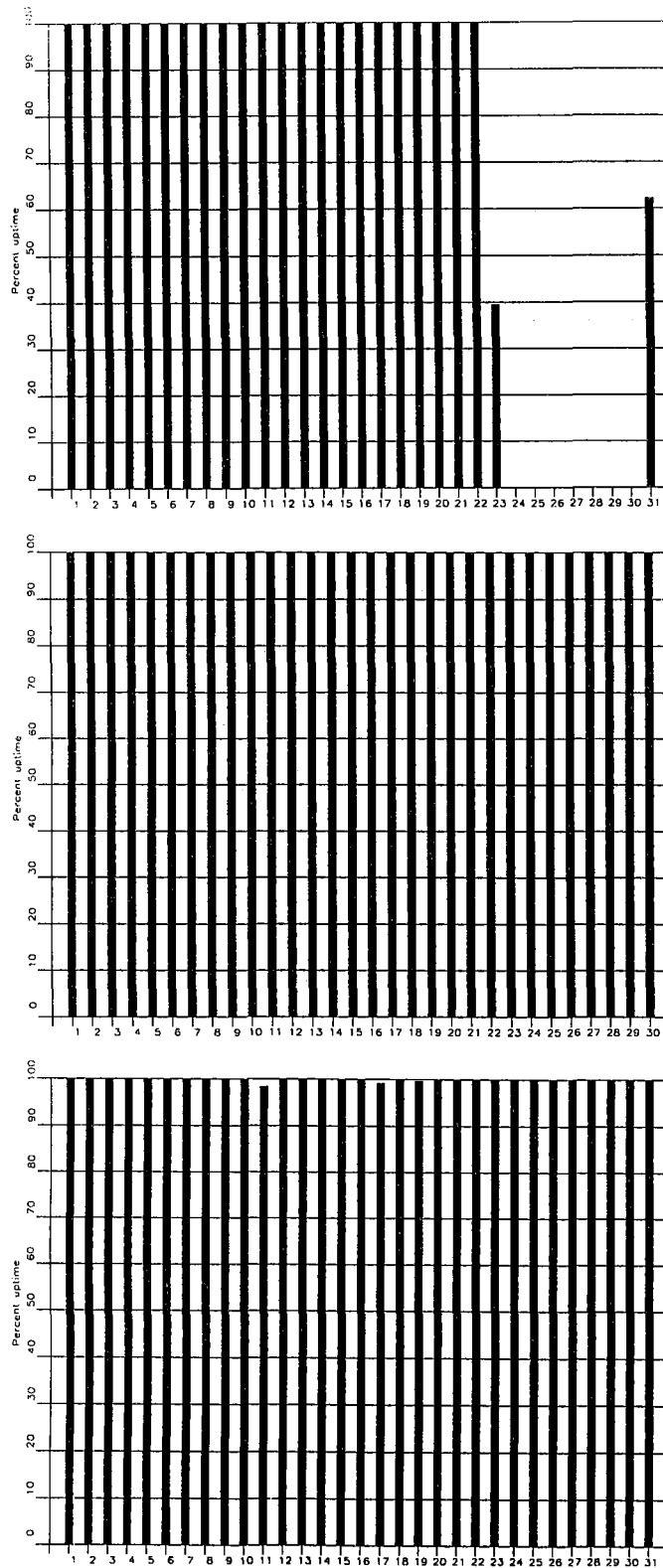


Fig. 3.3.1. FINESA data recording uptime for October (top), November (middle) and December (bottom) 1991.

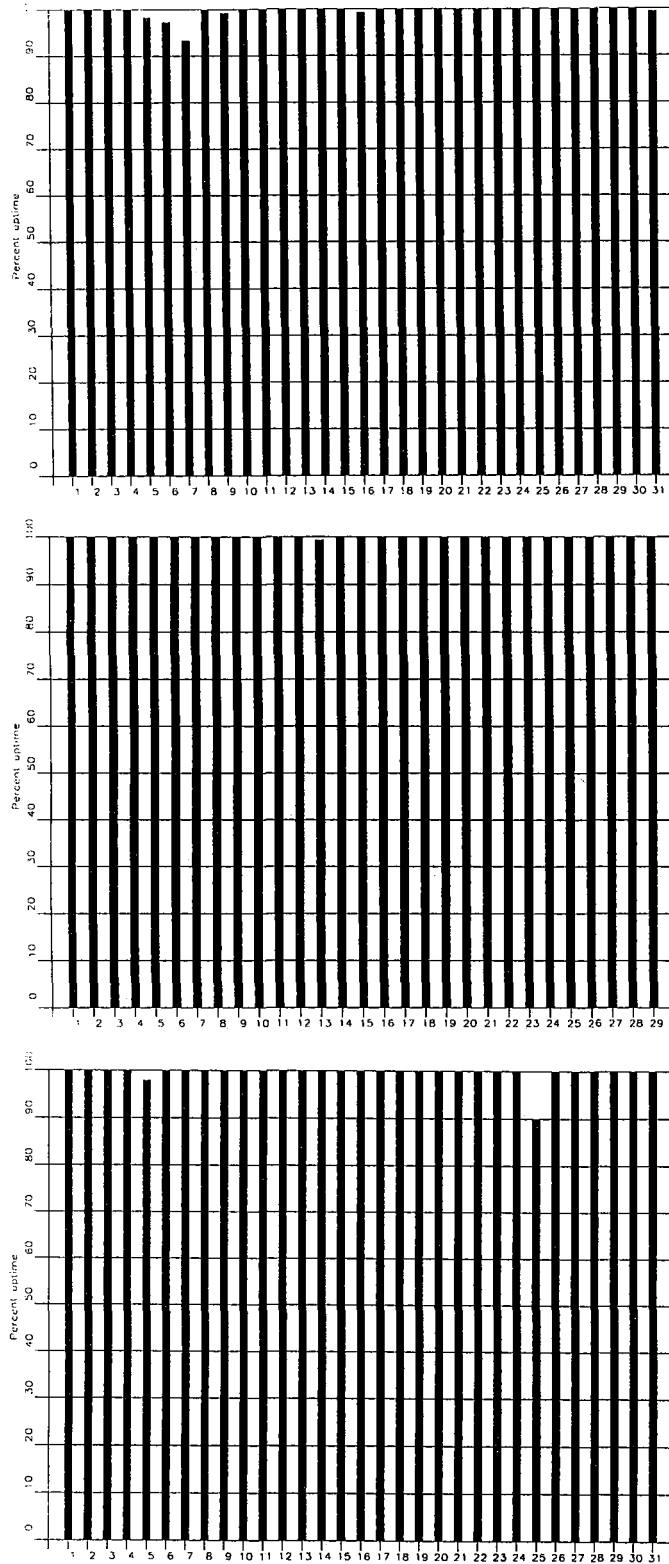


Fig. 3.3.1. FINESA data recording uptime for January (top), February (middle) and March (bottom) 1992.

3.4 Event detection operation

This section reports results from simple one-array automatic processing using signal processing recipes and "ronapp" recipes for the ep program (NORSAR Sci. Rep. No 2-88,89).

Three systems are in parallel operation to associate detected phases and locate events:

1. The ep program with "ronapp" recipes is operated independently on each array to obtain simple one-array automatic solutions.
2. The Generalized Beamforming method (GBF) (see F. Ringdal and T. Kværna (1989), A multichannel processing approach to real time network detection, phase association and threshold monitoring, BSSA Vol 79, no 6, 1927-1940) processes the four arrays jointly and presents locations of regional events.
3. The IMS system is operated on the same set of arrivals as ep and GBF and reports also teleseismic events in addition to regional ones.

IMS results are reported in section 3.5 and GBF results in section 3.6.

In addition to these three event association processes, we are running test versions of the so-called Threshold Monitoring (TM) process. This is a process that monitors the seismic amplitude level at the four regional arrays continuously in time to estimate the upper magnitude limit of an event that might go undetected by the network. The current TM process is beamed to several sites of interest, including the Novaya Zemlya test site. Simple displays of so-called threshold curves reveal instants of particular interest; i.e., instants when events above a certain magnitude threshold may have occurred in the target region. Results from the three processes described above are used to help resolve what actually happened during these instances. For more details, see section 7.8.

NORESS detections

The number of detections (phases) reported from day 274 1991, through day 091 1992, was 44,786, giving an average of 245 detections per processed day (183 days processed).

Table 3.4.1 shows daily and hourly distribution of detections for NORESS. See also Section 7.6 for distribution of detections versus apparent velocity and azimuth.

Events automatically located by NORESS

During days 274 1991, through 091 1992, 2716 local and regional events were located by NORESS, based on automatic association of P- and S-type arrivals. This gives an average of 14.8 events per processed day (183 days processed). 63% of these events are within 300 km, and 87% of these events are within 1000 km.

ARCESS detections

The number of detections (phases) reported during day 274 1991, through day 091 1992, was 74,532, giving an average of 407 detections per processed day (183 days processed).

Table 3.4.2 shows daily and hourly distribution of detections for ARCESS.

Events automatically located by ARCESS

During days 274 1991, through 092 1992, 3371 local and regional events were located by ARCESS, based on automatic association of P- and S-type arrivals. This gives an average 18.4 events per processed day (183 days processed). 46% of these events are within 300 km, and 85% of these events are within 1000 km.

FINESA detections

The number of detections (phases) reported during day 274 1991, through day 091 1992, was 50,417, giving an average of 293 detections per processed day (172 days processed).

Table 3.4.3 shows daily and hourly distribution of detections for FINESA.

Events automatically located by FINESA

During days 274 1991, through 091 1992, 3055 local and regional events were located by FINESA, based on automatic association of P- and S-type arrivals. This gives an average of 17.8 events per processed day (172 days processed). 67% of these events are within 300 km, and 88% of these events are within 1000 km.

GERESS detections

The number of detections (phases) reported from day 274 1991, through day 091 1992, was 30,407, giving an average of 182 detections per processed day (167 days processed).

Table 3.4.4 shows daily and hourly distribution of detections for GERESS.

Events automatically located by GERESS

During days 274 1991, through 091 1992, 2224 local and regional events were located by GERESS, based on automatic association of P- and S-type arrivals. This gives an average of 13.3 events per processed day (167 days processed). 68% of these events are within 300 km, and 88% of these events are within 1000 km.

Poland detections

The number of detections (phases) reported by the station KSP from day 274 1991, through day 351 1991, was 27,448, giving an average of 352 detections per processed day (78 days processed).

Table 3.4.5 shows daily and hourly distribution of detections for the KSP station in Poland.

The data transmitted from the station SFP were very unreliable and were not process during the reporting period. It was found that the signal processing results for KSP data generated too many false events for IMS; consequently this processing was stopped during December 1991.

J. Fyen

NRS .FKX Hourly distribution of detections

Day	00	01	02	03	04	05	06	07	08	09	10	11	12	13	14	15	16	17	18	19	20	21	22	23	Sum	Date
77	2	2	2	1	1	3	2	6	23	2	8	9	12	6	8	17	18	3	5	5	8	13	7	11	174	Mar 17 Tuesday
78	6	4	0	3	6	1	3	1	2	10	12	7	10	11	13	6	13	13	2	3	19	1	1	2	149	Mar 18 Wednesday
79	0	1	2	6	7	1	9	6	3	5	15	14	24	15	16	13	10	11	10	14	14	1	1	3	201	Mar 19 Thursday
80	1	0	3	4	3	8	5	1	8	8	11	9	9	21	4	12	8	9	17	4	18	4	2	2	171	Mar 20 Friday
81	4	4	4	5	1	6	3	5	5	12	7	12	4	9	4	4	10	8	9	5	9	8	4	13	155	Mar 21 Saturday
82	6	6	0	3	12	0	5	4	3	1	7	6	5	1	3	7	4	0	2	5	2	2	2	3	89	Mar 22 Sunday
83	5	2	4	4	8	4	30	16	16	7	16	12	15	25	26	11	9	11	17	3	11	1	1	2	256	Mar 23 Monday
84	2	6	3	8	6	3	44	35	21	20	15	2	11	21	6	14	4	18	2	7	24	7	2	4	285	Mar 24 Tuesday
85	0	1	2	1	3	1	3	1	9	7	7	1	12	7	15	16	20	14	4	7	24	6	7	4	172	Mar 25 Wednesday
86	1	3	3	2	6	0	1	3	4	5	11	25	13	15	20	12	18	12	5	8	5	13	3	1	189	Mar 26 Thursday
87	10	7	2	2	15	7	6	4	4	3	10	13	17	17	12	5	3	9	23	7	8	7	2	4	197	Mar 27 Friday
88	5	9	12	6	6	7	7	6	5	5	9	7	3	2	2	3	3	18	12	14	12	29	27	29	238	Mar 28 Saturday
89	30	41	63	53	56	43	37	20	12	5	4	14	14	13	9	3	1	12	12	11	20	15	13	25	526	Mar 29 Sunday
90	21	24	27	14	9	9	9	13	1	7	12	23	8	22	7	5	17	12	9	10	19	7	2	0	287	Mar 30 Monday
91	1	8	6	18	2	2	4	3	9	13	2	9	21	24	8	16	19	14	22	7	8	3	7	4	230	Mar 31 Tuesday
NRS	00	01	02	03	04	05	06	07	08	09	10	11	12	13	14	15	16	17	18	19	20	21	22	23		
Sum	1792	1744	1553	1553	1576	2062	2752	2131	1768	1536	1599	1715														
	1724	1720	1880	1455	1519	1861	2745	2573	2084	1828	2059	1557	44786	Total sum												
183	9	10	9	10	10	8	8	8	8	9	10	11	15	15	14	12	11	10	10	8	11	9	9	9	245	Total average
128	10	10	9	9	10	7	6	8	8	8	11	11	16	17	16	12	12	10	10	8	12	8	8	9	247	Average workdays
55	8	9	10	10	11	12	11	11	9	9	9	11	12	11	9	10	11	10	9	8	9	9	10	11	239	Average weekends

Table 3.4.1. Daily and hourly distribution of NORESS detections. For each day is shown number of detections within each hour of the day and number of detections for that day. The end statistics give total number of detections distributed for each hour and the total sum of detections during the period. The averages show number of processed days, hourly distribution and average per processed day.

ARC .FKX Hourly distribution of detections

Day	00	01	02	03	04	05	06	07	08	09	10	11	12	13	14	15	16	17	18	19	20	21	22	23	Sum	Date
77	16	8	22	13	26	21	27	22	36	17	19	31	17	15	19	11	20	5	17	15	17	13	13	16	436	Mar 17 Tuesday
78	9	1	13	6	9	10	9	13	24	17	19	31	34	18	18	9	7	12	2	6	9	10	13	17	316	Mar 18 Wednesday
79	0	11	12	16	9	10	17	9	23	27	28	25	53	15	24	47	12	16	11	20	16	7	10	19	437	Mar 19 Thursday
80	3	5	12	27	11	9	19	16	29	18	40	24	41	36	14	7	9	18	12	18	11	6	16	18	419	Mar 20 Friday
81	10	15	5	11	11	9	13	10	10	9	23	36	14	3	16	14	13	10	8	10	12	10	8	14	294	Mar 21 Saturday
82	6	10	15	11	18	8	11	7	15	10	10	21	5	8	12	15	11	10	17	15	17	17	20	15	304	Mar 22 Sunday
83	14	1	4	8	9	8	12	8	22	24	22	22	16	4	11	9	14	6	5	9	9	6	13	29	285	Mar 23 Monday
84	11	29	15	30	23	16	18	13	28	13	24	12	36	17	25	9	12	25	4	16	18	9	18	22	443	Mar 24 Tuesday
85	11	13	15	17	19	31	20	37	41	48	25	38	37	24	39	27	13	13	10	15	14	20	24	26	577	Mar 25 Wednesday
86	22	28	13	25	19	16	29	20	14	18	18	27	27	24	28	14	24	19	12	12	9	11	20	20	469	Mar 26 Thursday
87	12	18	2	6	8	6	15	8	18	33	29	26	36	28	29	23	16	9	4	14	15	13	19	12	399	Mar 27 Friday
88	7	4	11	11	7	10	20	6	13	15	16	21	15	10	10	6	8	10	4	7	7	11	5	19	253	Mar 28 Saturday
89	10	9	7	1	15	9	7	13	9	18	5	8	15	32	12	13	19	8	10	12	15	21	13	4	285	Mar 29 Sunday
90	13	4	6	8	9	23	17	18	7	24	18	21	29	9	10	18	8	16	8	20	12	28	30	4	360	Mar 30 Monday
91	5	15	8	8	4	9	13	24	19	37	13	31	31	25	5	23	18	21	26	13	17	22	13	10	410	Mar 31 Tuesday
ARC	00	01	02	03	04	05	06	07	08	09	10	11	12	13	14	15	16	17	18	19	20	21	22	23		
Sum	2421	2342	2495	2570	3370	3947	4274	3190	2906	3101	2795	4029														
	2489	2126	2434	3131	2951	3727	4476	4162	2865	2751	2786	3194	74532	Total sum												
183	14	13	12	13	13	14	17	14	16	18	20	22	24	23	23	17	16	16	15	17	15	15	17	22	407	Total average
128	15	14	12	14	13	14	19	15	18	20	22	23	26	25	23	17	17	16	14	15	13	14	17	22	420	Average workdays
55	10	11	11	11	13	12	13	12	12	15	17	18	20	18	21	17	13	15	17	21	19	18	18	21	373	Average weekends

Table 3.4.2. Daily and hourly distribution of ARCESS detections. For each day is shown number of detections within each hour of the day and number of detections for that day. The end statistics give total number of detections distributed for each hour and the total sum of detections during the period. The averages show number of processed days, hourly distribution and average per processed day.

FIN .FKX Hourly distribution of detections																											
Day	00	01	02	03	04	05	06	07	08	09	10	11	12	13	14	15	16	17	18	19	20	21	22	23	Sum	Date	
77	4	7	10	4	2	5	2	7	21	12	17	12	19	19	10	5	12	13	12	6	6	8	3	2	218	Mar 17	Tuesday
78	6	7	3	7	7	4	2	8	5	17	14	7	19	14	9	6	15	10	7	7	5	6	1	11	197	Mar 18	Wednesday
79	3	4	6	7	2	4	7	5	5	16	8	14	22	11	11	5	3	5	5	9	13	7	3	11	186	Mar 19	Thursday
80	11	11	10	8	5	4	9	4	12	25	14	18	21	19	11	15	8	4	7	9	9	3	2	4	243	Mar 20	Friday
81	5	3	3	12	3	6	7	2	5	9	8	8	7	4	2	3	7	5	1	6	7	2	3	11	129	Mar 21	Saturday
82	5	7	4	3	6	1	3	2	7	4	5	2	1	5	4	3	5	6	11	6	8	11	8	7	124	Mar 22	Sunday
83	12	6	11	13	5	4	5	8	4	9	11	16	18	20	10	9	9	1	8	4	8	14	12	12	229	Mar 23	Monday
84	10	17	17	5	10	3	4	3	8	16	19	12	16	22	15	8	11	7	2	11	6	10	6	12	250	Mar 24	Tuesday
85	7	6	6	9	7	0	0	7	11	14	15	17	35	9	8	2	4	7	7	11	8	24	12	15	241	Mar 25	Wednesday
86	16	9	7	17	12	5	1	7	2	23	20	24	24	27	16	7	15	15	5	4	9	2	6	3	276	Mar 26	Thursday
87	15	5	4	8	8	4	5	9	7	26	18	23	33	31	11	9	9	3	3	8	7	5	7	2	260	Mar 27	Friday
88	4	4	5	12	5	16	5	2	13	11	10	17	5	7	3	7	4	3	6	2	6	2	1	1	151	Mar 28	Saturday
89	6	7	6	7	8	3	6	9	10	12	1	10	16	18	9	7	8	20	4	9	10	16	5	19	226	Mar 29	Sunday
90	12	9	9	6	5	2	9	6	7	10	17	15	24	7	14	8	8	4	8	8	11	5	2	8	214	Mar 30	Monday
91	6	11	13	7	2	3	3	11	10	12	17	14	29	28	8	7	7	2	4	9	5	4	6	17	235	Mar 31	Tuesday
FIN	00	01	02	03	04	05	06	07	08	09	10	11	12	13	14	15	16	17	18	19	20	21	22	23			
Sum	2255	2441	1583	1342	2436	2909	2944	1610	1676	1905	2068	2261															
	2154	2179	1974	1400	1624	2637	3433	2086	1712	1734	1965	2089	50417	Total sum													
172	13	13	13	14	11	9	8	8	9	14	15	17	20	17	12	9	10	10	10	11	11	12	12	13	293	Total average	
121	13	13	13	15	11	9	7	7	9	15	17	19	23	19	12	9	9	9	9	10	10	11	10	12	292	Average workdays	
51	11	13	11	12	11	10	11	9	10	11	12	12	12	12	11	9	11	11	13	13	14	15	16	16	288	Average weekends	

Table 3.4.3. Daily and hourly distribution of FINESA detections. For each day is shown number of detections within each hour of the day and number of detections for that day. The end statistics give total number of detections distributed for each hour and the total sum of detections during the period. The averages show number of processed days, hourly distribution and average per processed day.

GER .FKX Hourly distribution of detections																											
Day	00	01	02	03	04	05	06	07	08	09	10	11	12	13	14	15	16	17	18	19	20	21	22	23	Sum	Date	
77	6	2	3	2	2	7	1	3	25	9	19	11	10	17	10	15	8	3	2	6	2	0	4	8	175	Mar 17 Tuesday	
78	2	5	4	7	4	3	2	17	25	11	27	24	11	6	13	5	10	2	8	2	12	4	1	4	209	Mar 18 Wednesday	
79	4	4	1	1	1	4	7	11	13	5	23	18	27	12	11	16	12	4	16	5	8	17	4	11	235	Mar 19 Thursday	
80	8	4	5	7	3	12	2	5	28	15	20	26	21	8	12	10	11	11	4	19	9	4	9	4	257	Mar 20 Friday	
81	6	4	0	3	7	7	9	1	4	1	11	10	7	7	9	1	2	4	17	0	0	0	0	0	110	Mar 21 Saturday	
82	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	Mar 22 Sunday
83	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	Mar 23 Monday
84	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	3	8	7	5	0	9	32	Mar 24 Tuesday	
85	9	2	5	4	4	0	0	5	23	12	20	12	21	11	9	15	5	9	7	2	6	3	3	4	191	Mar 25 Wednesday	
86	2	9	5	3	0	2	1	3	10	11	13	21	9	11	7	7	17	5	6	3	4	4	2	2	157	Mar 26 Thursday	
87	5	0	3	0	1	5	2	12	14	8	16	25	21	10	2	6	8	3	2	9	7	1	0	0	160	Mar 27 Friday	
88	10	7	3	2	2	11	11	1	2	3	11	9	8	11	2	6	3	2	7	12	11	9	8	3	154	Mar 28 Saturday	
89	4	6	2	2	3	1	3	3	8	2	5	3	7	18	3	3	11	3	3	1	3	9	7	12	122	Mar 29 Sunday	
90	6	4	3	0	4	6	13	11	10	20	18	22	16	12	8	7	2	5	11	10	7	1	7	5	208	Mar 30 Monday	
91	6	2	2	13	3	3	6	8	11	15	23	13	14	9	9	14	3	1	7	1	1	5	8	4	181	Mar 31 Tuesday	
GER																											
Sum	916	826	852	901	1703	2267	1676	1323	1011	1091	1152	881												30407	Total sum		
167	5	5	5	5	5	5	4	5	10	10	13	14	16	10	10	8	7	6	7	7	7	7	6	5	182	Total average	
118	5	6	5	5	6	5	4	6	12	11	15	16	19	11	11	9	7	6	7	7	8	7	5	5	198	Average workdays	
49	4	4	4	4	5	6	5	4	5	7	7	8	9	6	7	5	6	6	6	6	6	7	6	5	139	Average weekends	

Table 3.4.4. Daily and hourly distribution of GERESS detections. For each day is shown number of detections within each hour of the day and number of detections for that day. The end statistics give total number of detections distributed for each hour and the total sum of detections during the period. The averages show number of processed days, hourly distribution and average per processed day.

KSP .FKX Hourly distribution of detections

Day	00	01	02	03	04	05	06	07	08	09	10	11	12	13	14	15	16	17	18	19	20	21	22	23	Sum	Date	
330	35	5	16	14	25	8	6	1	3	8	9	9	23	17	10	6	8	4	7	6	14	17	16	8	275	Nov 26	Tuesday
331	17	10	16	12	14	7	7	16	4	3	14	11	9	18	11	11	10	5	8	7	19	19	13	16	277	Nov 27	Wednesday
332	8	21	22	17	18	11	4	6	8	4	22	16	29	8	6	6	7	9	14	7	15	28	9	19	314	Nov 28	Thursday
333	17	21	23	16	24	9	2	16	0	0	0	20	14	5	4	7	9	13	11	8	19	24	16	17	295	Nov 29	Friday
334	3	6	11	23	23	9	13	4	17	17	16	11	25	12	12	23	32	28	10	27	32	29	29	17	429	Nov 30	Saturday
335	11	15	18	33	37	13	22	18	30	30	18	17	24	19	20	20	24	25	25	21	26	25	15	23	529	Dec 01	Sunday
336	19	33	28	8	19	10	16	9	9	14	21	14	35	7	7	10	6	8	7	5	10	31	12	8	346	Dec 02	Monday
337	3	9	11	12	21	4	3	6	5	3	10	24	14	10	4	4	10	1	2	10	16	17	10	29	238	Dec 03	Tuesday
338	29	7	16	30	19	3	5	0	4	7	5	5	13	3	3	7	5	8	9	18	15	32	12	12	267	Dec 04	Wednesday
339	41	17	19	15	11	8	4	3	0	10	13	19	16	6	10	8	5	27	5	7	35	15	19	5	318	Dec 05	Thursday
340	12	12	11	35	26	4	6	9	2	11	5	9	14	8	8	2	8	6	11	17	15	15	17	15	278	Dec 06	Friday
341	14	28	20	13	18	2	18	10	11	12	5	11	19	17	20	12	42	33	22	27	24	10	16	11	415	Dec 07	Saturday
342	13	1	22	13	12	27	23	37	35	44	24	17	34	12	19	14	15	37	24	16	20	31	31	17	538	Dec 08	Sunday
343	21	15	18	14	23	10	3	6	10	7	10	9	20	19	5	10	5	6	4	8	8	19	8	9	267	Dec 09	Monday
344	5	14	7	11	15	7	5	6	11	10	6	9	13	8	13	9	9	3	8	4	17	24	40	57	311	Dec 10	Tuesday
345	51	61	78	5	18	6	10	7	8	10	17	13	19	5	6	9	4	12	13	8	18	22	20	13	433	Dec 11	Wednesday
346	15	30	30	19	25	7	3	9	6	9	7	16	23	18	11	11	17	8	8	11	16	39	16	13	367	Dec 12	Thursday
347	18	12	25	26	20	17	9	12	8	12	15	15	21	8	5	14	7	10	13	8	27	24	20	11	357	Dec 13	Friday
348	10	9	14	10	12	14	7	11	25	18	30	39	86	35	33	11	0	0	0	0	6	14	15	25	424	Dec 14	Saturday
349	10	83	33	18	27	14	39	16	34	24	20	31	25	9	19	10	19	31	13	37	31	22	23	20	608	Dec 15	Sunday
350	17	46	16	8	16	7	8	6	5	11	8	6	21	8	11	11	6	9	13	12	17	13	14	13	302	Dec 16	Monday
351	7	15	16	9	18	10	5	7	9	9	4	14	16	7	11	12	6	18	0	0	0	0	0	0	193	Dec 17	Tuesday
KSP	00	01	02	03	04	05	06	07	08	09	10	11	12	13	14	15	16	17	18	19	20	21	22	23			
Sum	1448	1340	760	762	915	1060	965	864	1092	857	1744	1620															
	1247	1546	1685	748	751	830	1483	951	927	874	1378	1601	27448	Total sum													
78	16	19	20	17	22	10	10	10	10	12	11	14	19	12	12	11	12	14	11	11	18	22	21	21	352	Total average	
56	17	18	20	17	22	8	7	8	7	9	10	12	18	11	10	10	9	10	9	9	16	23	21	21	320	Average workdays	
22	13	19	20	18	22	14	16	15	17	18	13	18	22	15	19	15	19	24	18	15	21	22	21	21	433	Average weekends	

45

Table 3.4.5. Daily and hourly distribution of KSP detections. For each day is shown number of detections within each hour of the day and number of detections for that day. The end statistics give total number of detections distributed for each hour and the total sum of detections during the period. The averages show number of processed days, hourly distribution and average per processed day.

3.5 IMS operation

The Intelligent Monitoring System (IMS) was installed at NORSAR in December 1989 and was operated at NORSAR from 1 January 1990 for automatic processing of data from ARCESS and NORESS. A new version of IMS that accepts data from an arbitrary number of arrays and single 3-component stations was installed at NORSAR in October 1991, and regular operation of the system comprising analysis of data from the 4 arrays ARCESS, NORESS, FINESA and GERESS started on 15 October 1991. As opposed to the first version of IMS, the one in current operation also locates events at teleseismic distance.

The operational stability of IMS has been very good during the reporting period. In fact the IMS event processor (pipeline) has had no downtime of its own; i.e., all data available to IMS have been processed by IMS.

Events automatically located by IMS

During days 288 1991, through 091 1992, 14,817 events (local, regional, teleseismic) were automatically located by IMS. This gives an average of 88.7 events per processed day (167 days processed). 40% of these events are within 300 km of nearest station, and 65% of these events are within 1000 km of nearest station.

46.3% of these events were defined by 2 regional phases and 13.8% were defined by 2 teleseismic phases. 87.4% of all events had 3 defining phases or less. 20.2% of the available detections (phases) were automatically associated to events.

Events located by analyst review of IMS results

During days 288, 1991, through 091, 1992, 8,087 events (local, regional and teleseismic) were defined following analyst review of IMS results. This gives an average of 51.8 events per processed day (167 days processed). 59% of these events are within 300 km of nearest station, and 73% of these events are within 1000 km of nearest station.

46.1% of these events were defined by 2 regional phases and 3.6% were defined by 2 teleseismic phases. 64.4% of all events had 3 defining phases or less. 11.3% of the available detections (phases) were associated to events. See section 7.6 for comments on the percentage of associated phases.

76.9% of the events had regional phases only. 21.4% of the events had teleseismic phases only.

Phase and event statistics

Table 3.5.1 gives a summary of phase detections and events declared by IMS. From top to bottom the table gives the total number of detections by the IMS, the number of detections that are associated with events automatically declared by the IMS, the number of detections that are not associated with any events, the number of events automatically declared

by the IMS, the total number of events defined by the analyst, and finally the number of events accepted by the analyst without any changes (i.e., from the set of events automatically declared by the IMS).

	Oct 91	Nov 91	Dec 91	Jan 92	Feb 92	Mar 92	Total
Phase detections	53275	45501	38258	35905	28252	30921	232112
-Associated phases	9778	8668	8496	5892	5626	8431	46891
-Unassociated phases	43497	36833	29762	30013	22626	22490	185221
Events automatically declared by IMS	3232	2772	2575	1846	1738	2654	14817
No. of events defined by the analyst	916	1350	1242	1025	1364	2190	8087
No. of events accepted without modifications	241	301	259	290	354	880	2325

Table 3.5.1. IMS phase detections and event summary.

U. Baadshaug

B. Ferstad

B. Paulsen Gammelby

B.Kr. Hokland

L.B. Loughran

3.6 GBF operation

Events automatically located by GBF

During days 274 1991, through 091 1992, 10,120 local and regional events were located by GBF. This gives an average of 55.3 events per processed day (183 days processed). 68% of these events are within 300 km of nearest station, and 89% of these events are within 1000 km of the nearest station.

76.9% of these events were defined by 2 regional phases. Teleseismic phases are currently not used by GBF. 86.7% of all events had 3 defining phases or less.

13.4% of the available detections (phases, including teleseismic) were associated to regional events.

T. Kværna

4 Improvements and Modifications

4.1 NORSAR

NORSAR data acquisition

No modification has been made to the NORSAR data acquisition system.

The data are recorded on a 30-hour circular disk buffer on the IBM system, and archived onto 1/2 inch magnetic tapes. In addition to this, the data are now regularly transmitted to a SUN system for recording on a 48-hour circular disk buffer.

NORSAR detection processing

The NORSAR detection processor has been running satisfactorily on the IBM 4381 computer during this reporting period.

Detection statistics are given in section 2. In addition to the detection processing done on IBM, the dp program is doing regular detection processing on a SUN system, using the unix-based circular disk buffer (see below). A detection SNR threshold of 20.0 triggers automatic saving of waveforms into CSS 3.0 data files.

NORSAR event processing

There have been no changes in the routine processing of NORSAR events, using the IBM system.

The new circular buffer on a SUN system will be used to convert old software and develop new event processor software for NORSAR data. The main difference between regional array processing as performed on the high-frequency arrays and NORSAR teleseismic array processing is that body waves do not have a plane wavefront across NORSAR. The consequence is that plane-wave fk-analysis does not work properly, and time delay corrections have to be used for beamforming. A new data base for time delay corrections needs to be built. With these new corrections and a higher sampling rate after the refurbishment, the large array will have excellent resolution in slowness space, and will provide very useful automatic locations for teleseismic signals. However, as an intermediate process, the old data files and programs for subarray time delay corrections have been converted for the SUN version of NORSAR event processing.

NORSAR refurbishment

Testing of new digitizers and data archiving systems have continued. The buried cables in the NORSAR array limit the amount of DC voltage that can be supplied at the remote sites. This necessitates testing at the actual remote sites, and we have been able to run the Nanometrics 16 bit gain-ranged converter (16 bit resolution, 24 bit dynamic range) with available DC power.

Another important issue is whether the 7 existing telephone lines to the subarray vaults may be upgraded from 2400 baud to 9600 baud. This has been discussed with the local telephone company, and some limited tests have been carried out. Within the subarrays there seems to be no problem in using existing cables for higher speed. An in-house project is underway to develop an acquisition system that meets the needs for both the NORSAR array and the other planned data acquisition projects (Apatity and Spitsbergen). The NORAC unit - NORSAR Array Controller - is described in section 7.7.

Using the NORAC, we have successfully collected synchronized data simultaneously from Nanometrics RD3 and Teledyne Geotech PDAS-100 (experimental version) digitizers.

At the NORSAR data center we are also evaluating the different acquisition systems at the NORESS/ARCESS, FINESA, NORSAR, and GERESS arrays, and the Poland and Apatity three-component stations. This experience allows us to concentrate our testing on how easily the digitizers may be synchronized and timed. For a detailed analysis of digitizer noise and resolution, we will also refer to manufacturers' specifications and experience at other installations. In our testing we will benefit from the simultaneous recording of NORESS and NORSAR data. It will be possible to arrange a setup with three independent recordings from the same instrument.

The problem with power at the remote sensors limits the number of systems that can be used in the refurbishment. The 24 bit resolution digitizers that are on the market have options for signal detection and data recording. This makes the systems needlessly sophisticated and expensive as compared to what is needed for the NORSAR refurbishment. These systems also generally consume too much power for installation at the NORSAR seismometer vaults.

The plan for the NORSAR refurbishment is to test digitizers during the spring and summer of 1992, and depending on whether technical requirements are met, we may start refurbishing one subarray during this autumn. A parallel recording of data for a longer period needs to be performed to ensure that we can correctly convert back and forth to the NORSAR data recorded over the past 20 years, to ensure continuity in the NORSAR data archive.

4.2 NORESS/ARCESS/FINESA/GERESS/Poland

Detection processing

The routine detection processing of the arrays is running satisfactorily on each of the array's SUN-3/280 acquisition systems. The same program is used for NORSAR, NORESS, ARCESS, FINESA, GERESS, KSP, SFP, but with different "recipes". The beam table for NORESS and ARCESS is found in NORSAR Sci. Rep. No. 1-89/90. The beam table for FINESA and GERESS is found in NORSAR Sci. Rep. No. 1-90/91.

Detection statistics are given in section 3.

Event processing. Phase estimation.

This process performs f-k and polarization analysis for each detection to determine phase velocity, azimuth and type of phase, and the results are put into the ORACLE detection data base for use by the IMS. Detection data for the three-component Polish stations were made available for IMS for a period, but created too many false events. These data are therefore currently not used in IMS processing.

Plot and epicenter determination

A description of single-array event processing is found in NORSAR Sci. Rep. No. 2-88/89, and NORSAR Sci. Rep. No. 2-89/90.

J. Fyen

5 Maintenance Activities

5.1 Activities in the field and at the Maintenance Center

This section summarizes the activities at the Maintenance Center (NMC) Hamar, and NDPC activities related to monitoring and control of NORSAR, including monitoring of NORESS and ARCESS. Activities at other field installations are also listed.

Activities involve preventive and corrective maintenance, modification of equipment, etc.

NORSAR

NORSAR subarrays were visited in October, November and December 1991 and January and February 1992. The different jobs involved adjustment of gain SP/LP channels and Mass Position (MP) and Free Period (FP) LP seismometers. Other activities have been replacement of relay card LP equipment, replacement of MP/FP motor EW seismometer LP, and RA-5 amplifiers SP channels. Cable splicing and location of cables have also been done. Activities related to NORSAR upgrading have continued throughout the period.

NORESS

This array was visited in October 1991 and January 1992. The Comsat satellite earth station was demounted including the 5 m antenna. Sites A1, C7 and D6 were repaired. The GPS clock was replaced with an LF-DC clock. Hub 13 interface card was replaced and Hub transmission speed changed from 32 to the original 64 Kbits.

ARCESS

In January the array was visited by NTA representatives. After a power failure they restarted the UPS (Uninterruptable Power Supply). Also the air-conditioner failed, but the local NORSAR representative started a ventilator fan.

Subarray/ Area	Task	Date
NORSAR		
01A	Adjusted channel gain all SP/LP instruments Also adjusted FP/MP LP instruments Replaced 4y relay card	4 Oct 91
01A	Cable splicing SP04	25,28,29 30 Oct
01B	Cable splicing SP05 Replaced RA-5 SP04	16,22 Oct 22 Oct
02B	Adjusted channel gain all SP/LP instruments Adjusted FP/MP LP seismometers	1 Oct
02B	Adjusted FP/MP LP instruments which afterwards could be adjusted from NORSAR, Kjeller	31 Oct
06C	Replaced RA-5 SP02	2 Oct
02B (tel)	Power unit receiver station replaced	31 Oct
NORESS		
	Demounted Comsat satellite earth station, incl. 5 m antenna Repaired A1, C7 and D6	14,17 Oct 18 Oct
NDPC		
	Daily check of all arrays, i.e., NORSAR, NORESS, ARCESS, FINESA, GERESS and Poland (KSP,SFP). NORSAR SP/LP instruments calibrated every week. Free Period (FP) and Mass Position (MP) have been measured and adjusted when outside tolerances, when feasible from NORSAR, Kjeller.	Oct
NORSAR		
01B	Replaced RA-5 amplifier SP04. Also cable was spliced	6,7,8 Nov
04C	Adjusted channel gain SP01,06 Adjusted channel gain all LP instruments Adjusted FP/MP	4 Nov
06C	Replaced RA-5 amplifier SP00	4 Nov
NDPC		
	Daily check of all arrays, i.e., NORSAR, NORESS, ARCESS, FINESA, GERESS and Poland (KSP,SFP). NORSAR SP/LP instruments calibrated every week (- week 48). Free Period (FP) and Mass Position (MP) have been measured and adjusted when outside tolerances.	Nov

Table 5.1. Activities in the field and the NORSAR Maintenance Center, including NDPC activities related to the NORSAR, NORESS, ARCESS, FINESA and GERESS arrays and the two 3-component stations in Poland (KSP, SFP), 1 October 1991 - 31 March 1992.

Subarray/ Area	Task	Date
NORSAR 01B (area)	Visited in connection with location of cables (in trenches) for Ringsaker Power Company	2 Dec
NMC	NORSAR upgrading tasks	Dec
NDPC	Daily check of all arrays, i.e., NORSAR, NORESS, ARCESS, FINESA, GERESS and Poland (KSP, partly SFP). NORSAR SP/LP instruments calibrated every week. Free Period (FP) and Mass Position (MP) have been measured and adjusted when outside tolerances, when possible from NORSAR, Kjeller.	Dec
		1992
NORSAR 01A	Adjusted gain all SP/LP channels	29 Jan
01B	Adjusted MP/FP all LP instruments	23 Jan
02B	Adjusted gain all SP/LP channels	21 Jan
03C	Adjusted gain all SL/LP channels Adjusted MP/FP all LP instruments	27 Jan
04C	Adjusted gain all SP/LP channels Adjusted MP/FP all LP instruments	28 Jan
06C	Adjusted gain all SP/LP channels Adjusted MP/FP all LP instruments	15 Jan
06C	Replaced MP/FP motor EW seismometer Adjusted gain channel 06	24 Jan
NORESS	GPS clock was replaced with an LF-DC clock	15 Jan
	Replaced Hub 13 interface card	16 Jan
	Hub transmission speed changed from 32 to 64 Kbits	23 Jan
ARCESS	Power failure	21 Jan
	NTA representative started the UPS	21 Jan
	Air-conditioner failed. Temperature rose to 40°C.	23 Jan
	NORSAR local representative started a ventilator fan	

Table 5.1 (cont.)

Subarray/ Area	Task	Date
NDPC	Daily check of all arrays, i.e., NORSAR, NORESS, ARCESS, FINESA, GERESS and Poland (KSP). NORSAR SP/LP instruments calibrated every week. Free Period (FP) and Mass Position (MP) have been measured and adjusted when outside tolerances, when possible from NORSAR, Kjeller.	Jan
NORSAR 02B	Adjusted MP/FP all LP instruments Adjusted channel gain all LP channels Adjusted channel gain SP01, 04 and 05	19 Feb
06C	Adjusted MP/FP all LP instruments Adjusted channel gain all LP instruments SLEM reset	18 Feb 26 Feb
NDPC	Daily check of all arrays, i.e., NORSAR, NORESS, ARCESS, FINESA, GERESS and Poland (KSP). NORSAR SP/LP instruments calibrated every week. Free Period (FP) and Mass Position (MP) have been measured and adjusted when outside tolerances, when possible from NORSAR, Kjeller.	Feb
NMC	NORSAR upgrading continued	Mar
NDPC	Daily check of all arrays, i.e., NORSAR, NORESS, ARCESS, FINESA, GERESS and Poland (KSP, SFP since 18.3.92). NORSAR SP/LP instruments calibrated every week. Free Period (FP) and Mass Position (MP) have been measured and adjusted when outside tolerances, when possible from NORSAR, Kjeller.	Mar

Table 5.1 (cont.)

5.2 Array status

As of 31 March 1992 the following NORSAR channels deviated from tolerances:

01A 01	8 Hz filter
02	8 Hz filter
04	30 dB attenuation

O.A. Hansen

6 Documentation Developed

- Bungum, H., A. Dahle, G. Toro, R. McGuire and O.T. Gudmestad (1992): Ground motions from intraplate earthquakes, Proc. 10th World Conf. on Earthq. Eng., Madrid, August 92.
- Dahle, A., H. Bungum, J. Havskov and B. Aspen (1992): Seismic surveillance of the Blåsjø Reservoir, Proc. 10th World Conf. on Earthq. Eng., Madrid, August 92.
- Hestholm, S.R, B.O. Ruud and E.S. Husebye (1992): Synthesizing 2D wave propagation in a heterogeneous lithosphere using finite difference techniques, manuscript submitted for publication.
- Kværna, T. (1992): Continuous seismic threshold monitoring of the northern Novaya Zemlya test site; long-term operational characteristics, AFGL Scientific Rep. No. 12, 28 February 1992.
- Mykkeltveit, S. (ed.) (1991): NORSAR Basic Seismological Research, Annual Technical Report, AFGL Scientific Rep. No. 11, 29 November 1991.
- Ringdal, F. and T. Kværna (1992): Continuous seismic Threshold Monitoring, submitted to Geophy. J. Int.
- Ruud, B.O., E.S. Husebye and S.R. Hestholm (1992): On crustal, short-period Rg propagation using array records from 4 continents, manuscript submitted for publication.
- Ruud, B.O., E.S. Husebye and C.D. Lindholm (1992): An exercise in automating seismic record analysis and network bulletin production, manuscript submitted for publication.
- Semiannual Tech. Summary, 1 Apr - 30 Sep 91, NORSAR Sci. Rep. 1-91/92, Kjeller, Norway.

7 Summary of Technical Reports/Papers Published

7.1 Global event detection performance during GSETT-2

Introduction

During the period 22 April to 9 June 1991, the Conference on Disarmament's Group of Scientific Experts carried out the main phase of its Second Technical Test (GSETT-2) (Reference: CD/1144). A total of 34 countries participated in this test, providing seismic data for 42 consecutive data days from 60 stations distributed around the globe (Fig. 7.1.1). Data were recorded and processed at National Data Centers, and parameters as well as waveform segments were transmitted to four experimental International Data Centers (EIDCs) for further analysis. Results of these analyses were summarized in event bulletins, which were transmitted back to participants from the EIDCs.

An important aspect of the performance evaluation of GSETT-2 is the completeness and quality of the final event bulletin (FEB). This seismological output is closely linked to the actual spatial distribution of seismic stations. For GSETT-2, a very heterogeneous global coverage yielded large regional variations in detection threshold. About one half of the participating stations were situated in and around Europe, consequently a large number of small events were detected, mainly quarry blasts and rock bursts of magnitude 1 to 4. On the other hand, in many areas of the globe where the station distribution was very sparse, only larger earthquakes were detected.

In this paper a preliminary assessment is made of the global event detection capability during GSETT-2. By comparing the FEBs to the bulletins of the National Earthquake Information Center (NEIC), we obtain detection statistics separately for the northern and southern hemisphere. We make no assessment in this paper of the location precision of the GSETT-2 network solutions. In sections 7.2 and 7.3, a more detailed discussion of the GSETT-2 performance in some selected regions is presented.

Method

The method used for detectability estimation has been described by Ringdal (1975), and is briefly summarized as follows:

1. A reference system, independent of the system to be evaluated, is used. Event lists and magnitudes from this reference system are compiled.
2. For each reference event, a comparison is made to see if the system to be evaluated has detected the event.
3. Based on the number of detections/no detections at each magnitude, a maximum likelihood approach is made to estimate a "detection curve" of the form

$$G(m; \mu, \sigma) = \int_{-\infty}^m \frac{1}{\sqrt{2\pi}\sigma} e^{-\frac{(x-\mu)^2}{2\sigma^2}} dx \quad (1)$$

Here $G(m; \mu, \sigma)$ denotes the incremental probability of detection, given event magnitude m . The detection curve is completely characterized by the parameters μ and σ . The 50 and 90 per cent incremental detection thresholds (μ_{50} and μ_{90}) become:

$$\mu_{50} = \mu \quad (2)$$

$$\mu_{90} = \mu + 1.29 \cdot \sigma \quad (3)$$

It should be noted that while the method assumes that the reference network provides independent event estimates, it is not necessary to have a complete event catalogue in any given magnitude range. Thus the reference events actually selected are assumed to be randomly sampled from the total number of events available, much in the same way as opinion survey polls attempt to address randomly selected subsets of the population. The resulting detectability estimates will be representative for the region considered only to the extent that the reference event set is representative.

When applying the method in practice, it is often desirable to restrict the range of values of σ when maximizing the likelihood function. This is done to reduce the influence of outliers in the data set. In this paper we have restricted σ to the interval 0.10-0.80 m_b units.

Reference network

The reference data base for this study has been the monthly bulletin from the U.S. National Earthquake Information Center (NEIC).

For the main phase of GSETT-2, upon which this analysis is based, the reference NEIC catalogue contained 829 seismic events with an assigned m_b value. The magnitude range was 2.6-6.4.

The criteria used to determine if a given reference event had been detected by the GSETT-2 network was as follows:

- Epicenter difference at most 3.0 degrees
- Origin time difference at most 60 seconds.

These criteria are the same as those used when merging FEB bulletins.

Results

The initial results from the detectability study are presented in Figs. 7.1.2-7.1.4. Each figure is based upon analyst comparison of the reference events with bulletin reports according to the criteria defined above.

Fig. 7.1.2 shows detectability statistics for the entire globe taken together. The 50% and 90% thresholds are estimated at m_b 3.7 and 4.7, respectively. In view of expected regional differences, we will look at the northern and southern hemisphere separately.

Fig. 7.1.3 shows results for the northern hemisphere. The estimated 50% and 90% thresholds are m_b 3.4 and 4.4, respectively. We observe that there is a relatively large range in detectability; thus there are detected events below $m_b = 3.0$, and non-detections as high as $m_b = 5.0$. This is of course due to the large regional variations in GSETT-2 network capability.

It is of interest to discuss in some details a few of the *non-detected* events of relatively large magnitude: Table 7.1.1 lists all NEIC-reported events of $m_b \geq 4.5$ in the northern hemisphere that were not detected according to the criterion given above. The following comments apply:

- Events 2, 4, 8, 9, 14 and 15 were not reported by any EIDC during GSETT-2.
- Events 5, 6, 7 occurred during the W. Caucasus aftershock sequence, and were not reported originally during GSETT-2 due to heavy workload. They were properly reported after reprocessing.
- Events 1, 3, 10, 11, 12, 13 and 16 were reported during GSETT-2, but the FEB location differed too much from the NEIC location to satisfy the "event matching" criterion.

Note that in some cases (1, 3, 13) one EIDC had a solution that was significantly closer to the NEIC solution than the one selected for the FEB.

In at least one case (event 12) it appears that the FEB solution was significantly better than the NEIC solution.

Fig. 7.1.4 shows results for the southern hemisphere. The estimated capabilities are considerably less than for the northern hemisphere, with 50% and 90% thresholds of $m_b = 4.1$ and 5.1, respectively.

Again, it is of interest to discuss some of the largest non-detected events: Table 7.1.2 lists the NEIC-reported events of $m_b \geq 5.0$ in the southern hemisphere that were not detected. The following comments apply:

- Events 1 and 2 were not reported by any EIDC during GSETT-2.
- Events 3, 4, 5, 6, and 7 were reported during GSETT-2, but the FEB location differed too much from the NEIC location to satisfy the "event matching" criterion.

Note that for events 3 and 5, there were EIDCs that had solutions very close to the NEIC solution, but they were not selected for the FEB.

In assessing these results, it must be remembered that "detection threshold" is closely tied to "location accuracy". The more relaxed our location requirements are, the "better" the detection capability will appear to be. Our results here represent what we think is a reasonable compromise for a global network of the type employed in GSETT-2. It would be of great interest to compare these results to theoretical network capability studies under the different assumptions and conditions in the models.

In this study, all magnitudes refer to reported NEIC network m_b values. The question of a possible bias in network m_b estimates has not been addressed here, but would need to be taken into account when comparing the results to theoretical capability studies.

F. Ringdal

S. Mykkeltveit

U. Baadshaug

References

CD/1144 (1992): Report on the Group of Scientific Experts' second technical test (GSETT-2), Conference on Disarmament, Geneva.

Ringdal, F. (1975): On the estimation of seismic detection thresholds, *Bull. Seism. Soc. Am.*, 65, 1631-1642.

No.	FEB	IDC	ORIGIN TIME	LAT	LON	DPT	NOB	MB
1	CSS	USGS	1991-113:08.58.47.700	9.97	-83.26	10	9	4.6
1	STO	STO	1991-113:08.58.48.100	13.14	-86.81	2	9	3.4
2	CSS	USGS	1991-114:19.11.45.700	31.81	104.54	33	10	4.7
3	CSS	USGS	1991-117:14.48.42.400	17.18	-100.30	53	38	4.6
3	STO	STO	1991-117:14.48.41.500	16.76	-103.80	1	11	4.0
4	CSS	USGS	1991-119:00.51.44.800	13.88	-92.59	62	7	4.6
5	CSS	USGS	1991-119:09.59.24.000	42.62	43.40	10	64	4.6
6	CSS	USGS	1991-119:10.19.41.300	42.22	43.59	10	24	4.5
7	CSS	USGS	1991-119:11.10.11.900	42.58	43.90	10	67	4.7
8	CSS	USGS	1991-119:18.28.17.500	51.00	-178.38	33	12	4.7
9	CSS	USGS	1991-122:06.54.14.300	34.80	26.48	20	32	4.6
10	CSS	USGS	1991-130:05.31.04.400	10.04	124.16	84	5	4.6
10	MOS	STO	1991-130:05.31.08.100	10.48	128.52	88	6	3.4
11	CSS	USGS	1991-136:20.31.05.200	17.04	-102.31	33	35	4.6
11	CNB	WAS	1991-136:20.32.10.400	21.23	-102.99	367	13	3.4
12	CSS	USGS	1991-145:18.59.23.200	42.96	147.59	33	6	4.8
12	STO	CNB	1991-145:18.59.47.700	44.33	137.97	11	18	4.1
13	CSS	USGS	1991-146:17.28.01.300	27.05	99.75	33	9	5.0
13	MOS	MOS	1991-146:17.29.22.600	15.91	103.93	16	8	3.7
14	CSS	USGS	1991-147:12.02.25.700	32.92	56.33	33	5	4.6
15	CSS	USGS	1991-148:20.04.50.000	24.65	94.36	142	9	4.7
16	CSS	USGS	1991-152:06.01.48.700	1.65	123.25	10	7	4.7
16	CNB	WAS	1991-152:06.00.21.700	10.58	119.27	0	8	4.1

Table 7.1.1. NEIC-reported events of $m_b \geq 4.5$ in the northern hemisphere not reported in the FEB (using the event matching criteria given in the text). Whenever an FEB event is close to matching one of the NEIC events, it is listed below it.

o.	FEB	IDC	ORIGIN TIME	LAT	LON	DPT	NOB	MB
1	CSS	USGS	1991-112:19.18.43.500	-11.48	166.19	63	13	5.1
2	CSS	USGS	1991-116:05.25.24.800	-5.43	129.73	227	11	5.0
3	CSS	USGS	1991-128:08.51.40.300	-22.04	68.32	10	37	5.1
3	CNB	WAS	1991-128:08.52.43.900	-20.42	69.73	582	16	3.7
4	CSS	USGS	1991-130:23.30.44.500	-37.00	-98.93	10	10	5.1
4	MOS	STO	1991-130:23.31.03.000	-34.47	-96.46	1	6	4.1
5	CSS	SGS	1991-134:19.17.53.800	-57.72	-25.37	52	16	5.1
5	MOS	CNB	1991-134:19.18.26.800	-34.13	-28.39	1	11	4.3
6	CSS	USGS	1991-141:12.43.35.800	-7.25	129.43	58	14	5.0
6	STO	WAS	1991-141:12.43.02.100	-6.52	126.14	0	8	4.2
7	CSS	USGS	1991-153:11.08.11.200	-18.81	-173.17	33	22	5.2
7	STO	STO	1991-153:11.09.17.800	-19.97	-178.43	285	27	4.7

Table 7.1.2. NEIC-reported events of $m_b \geq 5.0$ in the southern hemisphere not reported in the FEB (using the event matching criteria given in the text). Whenever an FEB event is close to matching one of the NEIC events, it is listed below it.

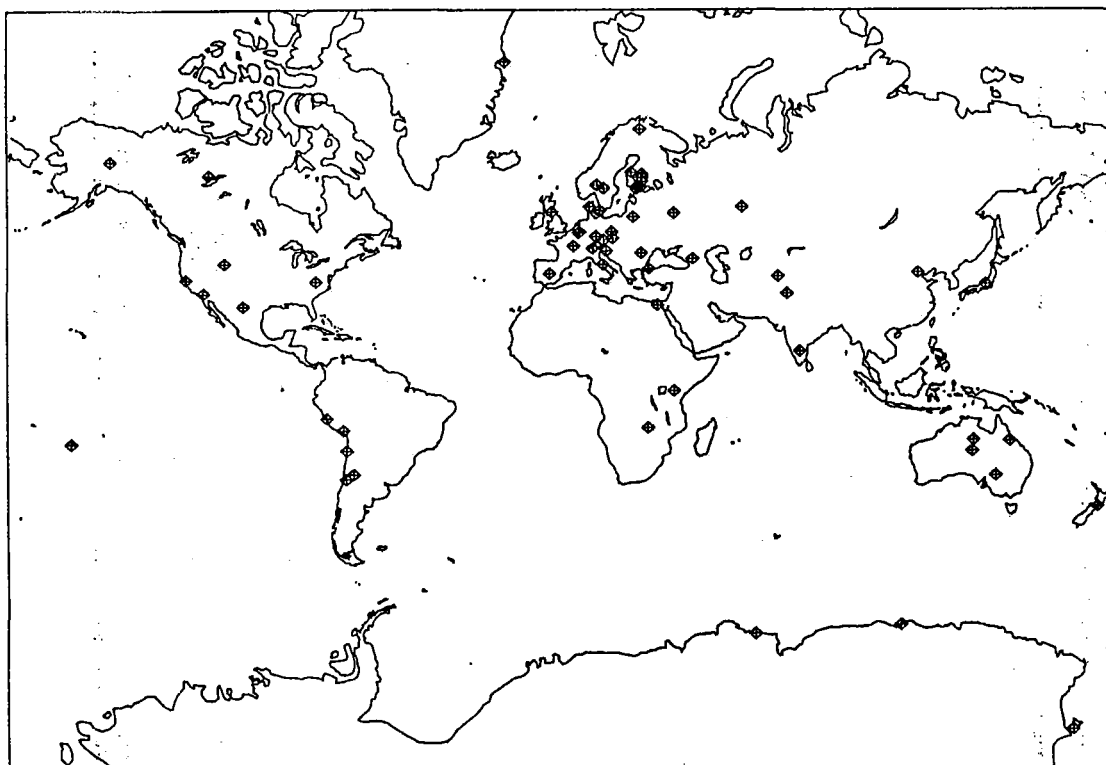


Fig. 7.1.1. Stations participating in the main phase of GSETT-2, April-June 1991 (after CD/1144). Detailed descriptions of station characteristics can be found in Group of Scientific Experts' Sourcebook for International Seismic Data Exchange, CRP/167.

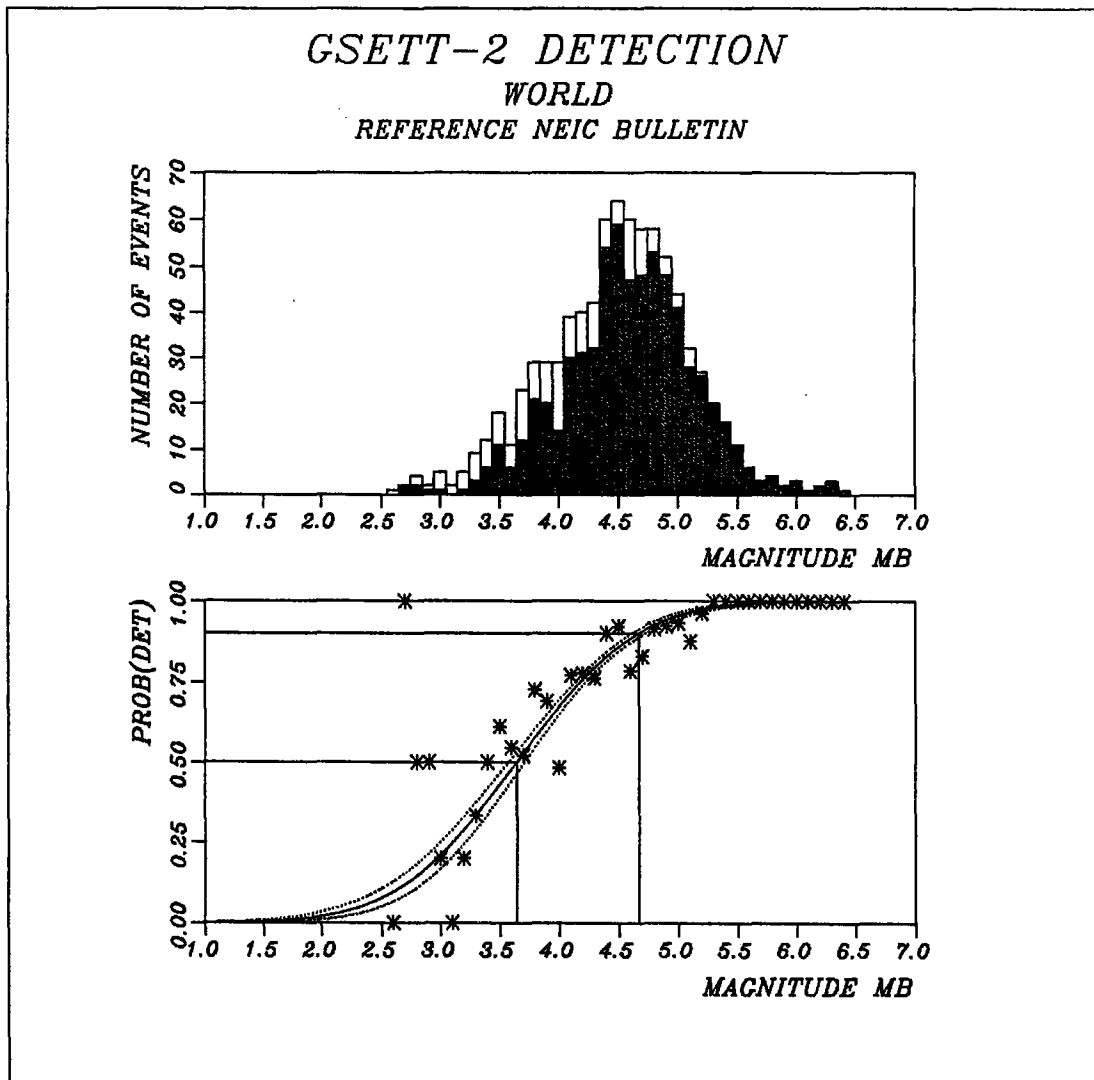


Fig. 7.1.2. Maximum likelihood detectability estimation for the GSETT-2 network, using the NEIC monthly bulletin as a reference. This figure shows statistics for the **entire world**. The upper half shows the reference event set and the number of events actually detected for each magnitude. The lower half shows the maximum likelihood detectability curve and its confidence limits. The actual percentage of detected events at each magnitude is also shown. The criteria for associating FEB events to NEIC events are given in the text.

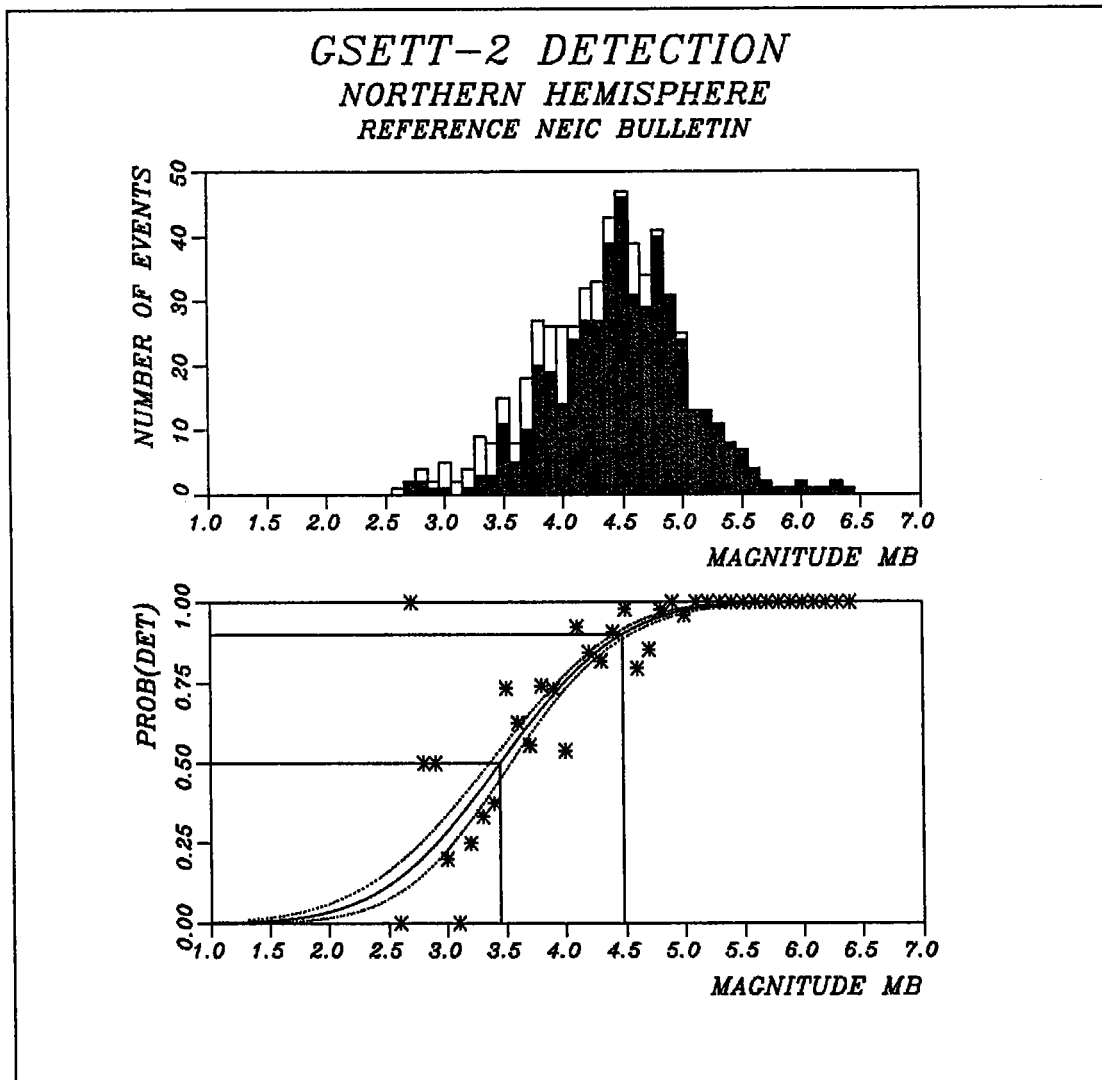


Fig. 7.1.3. Maximum likelihood detectability estimation for the GSETT-2 network, using the NEIC monthly bulletin as a reference. This figure shows statistics for the **northern hemisphere**. The upper half shows the reference event set and the number of events actually detected for each magnitude. The lower half shows the maximum likelihood detectability curve and its confidence limits. The actual percentage of detected events at each magnitude is also shown. The criteria for associating FEB events to NEIC events are given in the text.

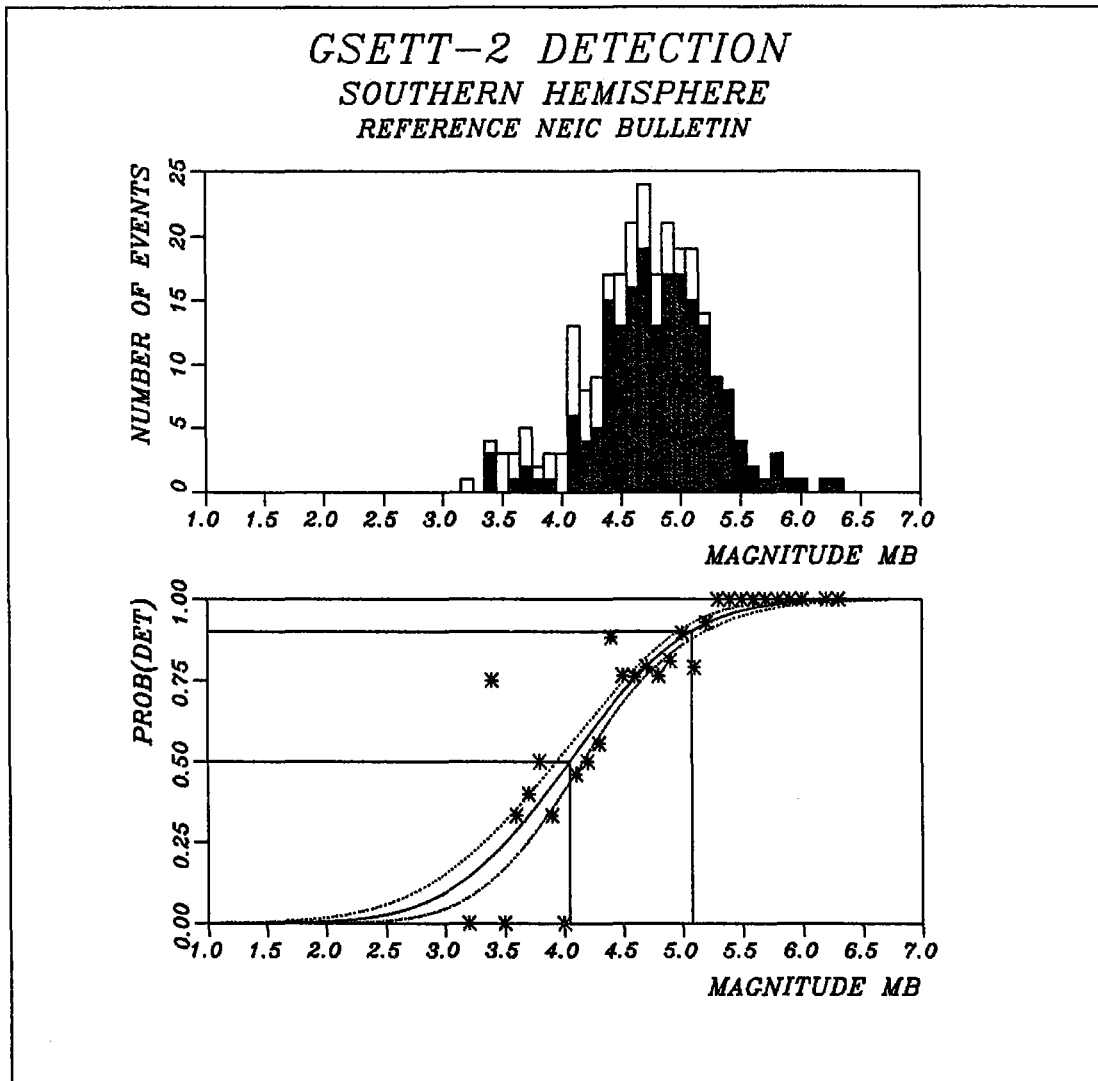


Fig. 7.1.4. Maximum likelihood detectability estimation for the GSETT-2 network, using the NEIC monthly bulletin as a reference. This figure shows statistics for the **southern hemisphere**. The upper half shows the reference event set and the number of events actually detected for each magnitude. The lower half shows the maximum likelihood detectability curve and its confidence limits. The actual percentage of detected events at each magnitude is also shown. The criteria for associating FEB events to NEIC events are given in the text.

7.2 Regional detection and location performance during GSETT-2: Initial results for the Fennoscandian array network

Introduction

In this paper a preliminary assessment is made of the event detection and location capability during GSETT-2 for Fennoscandia and NW Russia. This is the region that had maybe the best instrumental coverage during the experiment. In particular the regional arrays deployed in this area made significant contributions.

Our results for this region represent in a sense the "best" regional performance during GSETT-2. It is in no way representative for the performance on a global or more extended regional scale. However, it does serve to illustrate the potential capabilities of a monitoring network, assuming that an adequate density and number of high quality, sensitive array stations are deployed.

This investigation is composed of three separate studies. Firstly, we describe the results of a detectability study, where the reference data base is the seismic bulletin published by the University of Helsinki, Finland. The second study is also on detectability, and here the reference data base is the bulletin published by the University of Bergen, Norway. The third part of the investigation is a study on event location performance, where event locations in the FEBs are compared with locations published in the Helsinki bulletin.

Detectability study: Comparisons with the bulletin of the University of Helsinki

Method

The method used for detectability estimation has been described by Ringdal (1975):

- A reference system, independent of the system to be evaluated, is used. Event lists and magnitudes from this reference system are compiled.
- For each reference event, a comparison is made to see if the system to be evaluated has detected the event.
- Based on the number of detections/no detections at each magnitude, a maximum likelihood "detection curve" is estimated.

Reference network

The reference data base for this study has been the catalogue of seismic events in northern Europe regularly compiled by the Seismological Institute, University of Helsinki.

The stations used in compiling this catalogue are in almost all cases comprised on the Finnish seismic network single stations. For all practical purposes, the compilation is independent of the regional arrays in Fennoscandia (NORESS, ARCESS, FINESA). The magnitudes quoted in the bulletin are likewise derived independently of the regional arrays, and comprise either duration magnitudes (in most cases) or local magnitudes.

These magnitudes are fairly consistent with magnitudes calculated by the Intelligent Monitoring System, while their relationship to teleseismic m_b estimates is at present not well established.

For the month of May 1991, upon which this analysis is based, the reference catalogue contained 321 seismic events in the region bounded by 58° - 70° N, 20° - 40° E, of which 108 had an assigned magnitude in the range 1.7-2.9.

Results

The initial results from the detectability study are summarized in Figs. 7.2.1-7.2.2 (see also Ringdal, 1991). The figures are based upon analyst comparison of the reference events with bulletin reports according to the criteria:

a) **NDC-reported event:**

In Fig. 7.2.1, an event is considered detected if it was reported with 2 phases (P and S; or P and Lg) by at least one of the three regional arrays (NORESS, ARCESS, FINESA). In terms of GSETT-2 final event bulletins, this means that the event was either located as a multi-station event, or listed as an NDC-reported event. We note that the 50% threshold is close to 1.7, and the 90% threshold is 2.3 in this case.

b) **FEB-reported events:**

In Fig. 7.2.2, the FEB-reported events, located by at least one IDC, are shown. (We have not counted as detected events those events whose definition depended upon reportings from the Finnish network stations KAF and VAF, since these two stations were part of the reference network.) This added requirement has the effect of increasing the 50% threshold to 2.1, and the 90% threshold to 2.4.

Detectability study: Comparisons with the bulletin of the University of Bergen

Reference network

The seismic bulletin published by the Institute of Solid Earth Physics of the University of Bergen, Norway, has been the reference data base for this study.

The stations used by the University of Bergen in compiling their bulletin are shown in Fig. 7.2.3. The events reported in this bulletin are basically confined to southwestern and northern Norway, the North Sea and the continental margin to the west of Norway. This bulletin thus very suitably supplements the Helsinki bulletin with respect to coverage of Fennoscandian seismic events.

Detections from NORESS and ARCESS are to a certain extent used in compilation of the University of Bergen bulletin. However, only events that were reported without use of NORESS/ARCESS readings, or that would have been reported even if NORESS/ARCESS data were not used (i.e., events for which the University of Bergen network alone had a sufficient number of phases), were used as reference events. The magnitudes

given in the University of Bergen bulletin are duration magnitudes. These magnitude values are generally higher than those calculated by the Intelligent Monitoring System (typically by 0.5 magnitude units).

For the GSETT-2 period, 22 April - 2 June 1991, the University of Bergen bulletin contains 83 events satisfying the criteria mentioned above (a couple of small events very close to the JMI network are excluded from consideration). The coda magnitudes are in the range 0.3-4.0.

Results

For each of the 83 events in the reference data base, we checked whether or not the event was reported during GSETT-2 by the Norwegian NDC. Such reports of local/regional events always included a FOCUS line, and the event origin time and geographical coordinates were based on at least one P- and one S-phase from either NORESS or ARCESS. The results from this study are presented in Fig. 7.2.4, where the detectability curve has been computed in accordance with the method outlined above.

We can see from Fig. 7.2.4 that the 50% threshold is close to 1.5, and that the 90% threshold is a little less than 2.5. These results should be compared to those in Fig. 7.2.1, which were obtained for the same reporting criterion (two phases on at least one array). Taking into account that the University of Bergen magnitudes are slightly higher than those reported by IMS and the University of Helsinki, it appears that 90% event detection probability of the Fennoscandian regional array network is at magnitude 2.5 or lower across the entire Fennoscandia from the Norwegian continental shelf to northwestern Russia.

It should be noted that for three events counted as detected events in Fig. 7.2.4, only a single P phase was reported by the Norwegian NDC during GSETT-2. For one of these events, an Sn phase was also automatically detected, but by mistake not reported during GSETT-2. For the other two events, there were no automatic S-phase detections, but inspection of the associated waveforms reveals the presence of a regional event that could and would have been reported as such given more time and resources during the NDC analysis stage.

Event location performance: Comparison between the FEBs and the University of Helsinki bulletin

Data base

To evaluate the regional event location performance for Fennoscandia and northwestern Russia, we again selected as a reference data base the bulletin published by the Institute of Seismology of the University of Helsinki. For the GSETT-2 test period 22 April - 2 June 1991, altogether 430 local and regional events were reported in the Helsinki bulletins, and 257 of these events were also found in the "IDC section" of the corresponding FEBs. (Two different solutions were given for two of these events, thus resulting in a total of 259 events in the FEB data base.)

It must be noted that the two data bases are not entirely independent relative to each other: The FEB events located in Finland were generally composed of reported or added readings from the stations KAF, VAF (part of the reference network) and the FINESA array. However, this interdependence does not represent a problem in the study on event location performance reported on here.

The 257 reference events comprised six earthquakes, one in central Finland, one in the Svalbard region, and four in the North Sea/Norwegian Sea, while the remaining events were presumed regional explosions of low magnitude. Fig. 7.2.5 shows the epicenters of the events, together with the stations of the Finnish Seismograph Network.

Due to the relatively high mining activity in the region, a normal practice in producing the Helsinki bulletin is to apply a brief reporting, i.e., manually determined source information with no phase readings, to events from the known sites. However, epicenters for the events reported by the Finnish NDC during GSETT-2 were determined using an iterative location procedure.

According to the estimated location accuracy, the reference events were divided into five groups:

Group I

Nineteen quarry blasts from seven Finnish mines or quarries. The blasts were confirmed by the responsible authorities, and the location was reported with an accuracy of better than ± 500 m. In the Helsinki bulletin, the complete location procedure was applied for 14 of these events, and a true location accuracy of 4.2 ± 3 km was calculated for this group.

Group II

Events located in the area where the coverage of the reference network is good (approximately 60° - 66° N and 22° - 29° E). The average station-to-epicenter distance is 150 km. As the events in group I also belong to this group, a reasonable estimate for the location accuracy is ± 5 km.

Group III

Events located at the edges of the Finnish network, including the coast of Estonia. The average epicentral distance is 250 km. Events from the known mines in northern Sweden and northwestern Russia -- reported with manually determined epicenters in the Helsinki bulletin -- are also included in this group. The accuracy of the Helsinki bulletin location is estimated to be ± 10 km.

Group IV

Events in northern Fennoscandia, northwestern Russia and the Baltic Sea, the average epicentral distance being 450 km. Estimated accuracy of the location in the Helsinki bulletin is ± 15 km.

Group V

Five earthquakes off continental Fennoscandia, in the Norwegian Sea and the North Sea. The events are far from the reference network, the average distance being 1000 km. However, as these event reports contain also readings from other seismological institutes in the region (13-30 stations were used in the epicenter determination), a reasonable estimate for the location accuracy is ± 20 km.

Results from the FEB analysis

Table 7.2.1 shows the number of FEB events in each of the five groups versus the EIDC responsible for the representative solution. In Table 7.2.1 it is noteworthy that 61 per cent of the representative solutions for Fennoscandian events originated from the WAS EIDC. The median value plus 25% and 75% quadratiles (Q) for differences between the FEB solution and the true location (group I) or the reference location (groups II-V) are also given in Table 7.2.1.

Group	CNB	MOS	STO	WAS	Total	Median (km)	25% Q (km)	75% Q (km)
I	6	-	-	13	19	10.2	6.2	22.6
II	10	-	3	40	53	13.6	8.1	24.3
III	45	6	23	91	165	29.0	15.1	49.3
IV	-	-	4	13	17	36.6	17.7	53.7
V	1	-	2	2	5	42.5	27.5	87.7
Total	62	6	32	159	259			

Table 7.2.1. Location statistics for the regional events.

From Table 7.2.1 we make the following observations:

Group I events:

The median FEB location error (relative to true location) is 10.2 km. This can be compared to a true location error of 4.2 km obtained by using Finnish network data.

Group II events:

Here, the reference locations are estimated to be accurate to ± 5 km. The median FEB location "error" relative to these estimates is 13.6 km. Thus the FEB performance is similar to Group I events. (Estimate of "absolute" error is $\sqrt{13.6^2 - 5^2}$ km = 12.6 km.)

Group III events:

Here, the reference locations are estimated to be accurate to ± 10 km. The median FEB location "error" is 29.0 km. An estimate of "absolute" error is $\sqrt{29^2 - 10^2}$ km = 27.2 km. Thus Group III events have clearly inferior location accuracy compared to Groups I and II.

Group IV events:

Here, the reference locations are estimated to be accurate to ± 15 km. The median FEB location "error" relative to these estimates is 36.6 km. An estimate of the "absolute" error is $\sqrt{36.6^2 - 15^2}$ km = 33.4 km. This is slightly higher than for Group III.

Group V events:

Here, the number of events is too low to compute any meaningful statistics, but the FEB performance seems to be not very different from Group IV events.

A closer inspection of the FEBs shows that the location accuracy varied considerably between different EIDCs. The scatter can partly be explained by the different degree of experience with the analysis of data from this region. For example, some EIDCs did not place any constraints on the event depth in the location procedure for many of the events dealt with here.

Part of the location differences are due to the different velocity models used in the Helsinki bulletin and at the EIDCs. To illustrate this, we have plotted in Fig. 7.2.6 the difference in epicentral distance derived from the WAS EIDC standard travel-time tables and the Helsinki velocity model used in the Helsinki bulletin. As can be seen from the figure, differences up to 11 km exist at the regional distance range. The differences may be even greater in case other velocity models are applied.

Conclusions

The regional evaluation of detection results from GSETT-2 presented here shows that in a region with dense coverage of high-quality array stations as in Fennoscandia, it is possible to detect seismic events at very low magnitudes.

The 90 per cent threshold of around magnitude 2.5 found in this study for different parts of Fennoscandia must of course be considered with the appropriate caution: Thus it refers to regional magnitude scales that currently are not well calibrated in terms of global magnitude. Also, in other geological environments, the wave propagation and array noise suppression characteristics may be different. Therefore, it is not known to which extent such results would be possible to duplicate in other parts of the world.

Evaluation of the regional event location performance in Fennoscandia showed that in an area where the coverage of the GSETT-2 network is good, the location accuracy approaches that obtained by national networks.

There are indications that the location errors may be reduced by using regional velocity models. In addition, knowledge on the characteristics of seismicity in the region would further improve the results.

S. Mykkeltveit

M. Uski, Univ. of Helsinki, Finland

References

Ringdal, F. (1975): On the estimation of seismic detection thresholds, *Bull. Seism. Soc. Am.*, 65, 1631-1642.

Ringdal, F. (1991): Regional detection performance during GSETT-2: Initial results for the Fennoscandian array network. Semiann. Tech. Summ., 1Mar - 30 Sep 1991, NORSAR Sci. Rep. 1-91/92, Nov 91, NORSAR, Kjeller, Norway.

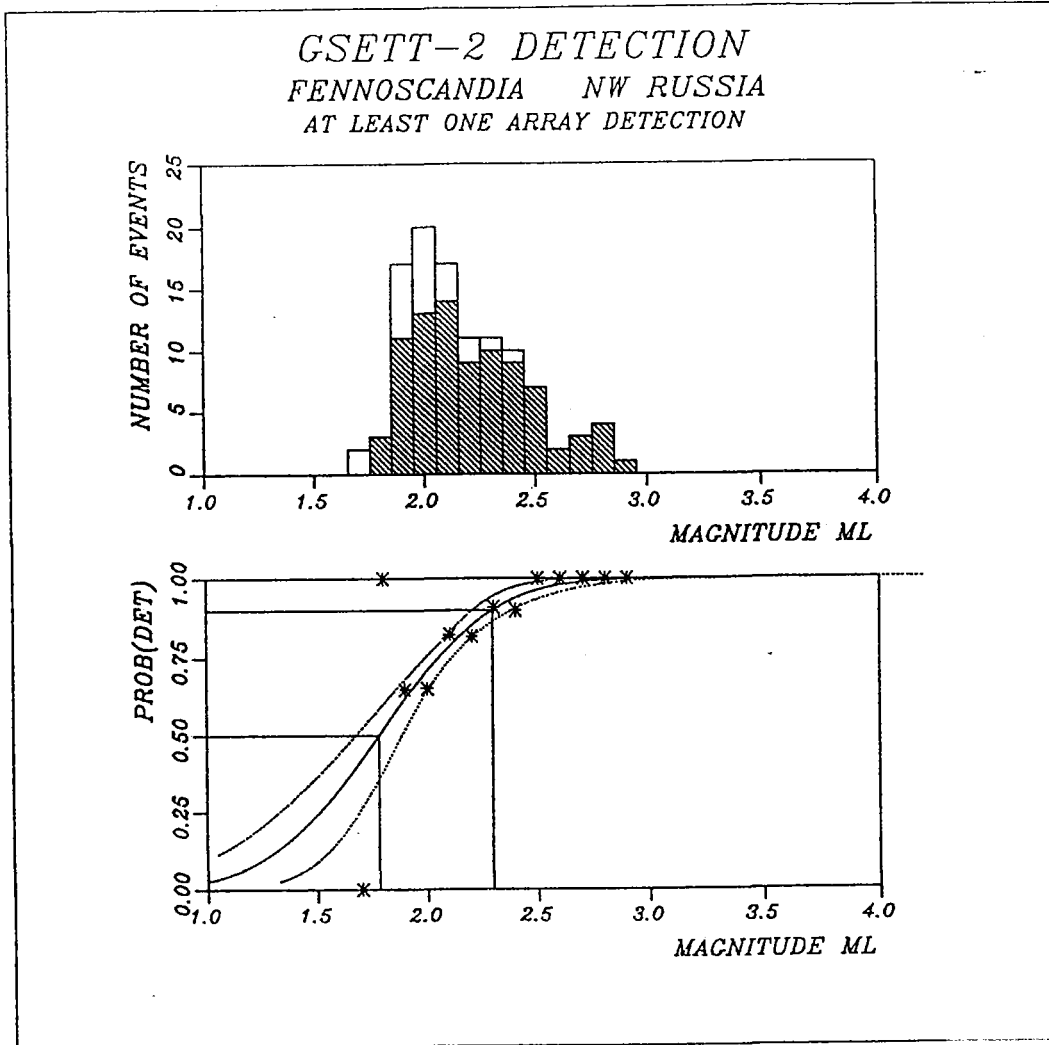


Fig. 7.2.1. Maximum likelihood detectability estimation for Fennoscandia-NW Russia using the Univ. of Helsinki bulletin as a reference. The upper half shows the reference event set and the number of events actually detected for each magnitude. The lower half shows the maximum likelihood detectability curve and its confidence limits. The actual percentage of detected events at each magnitude is also shown. This figure is based upon a one-array detection requirement.

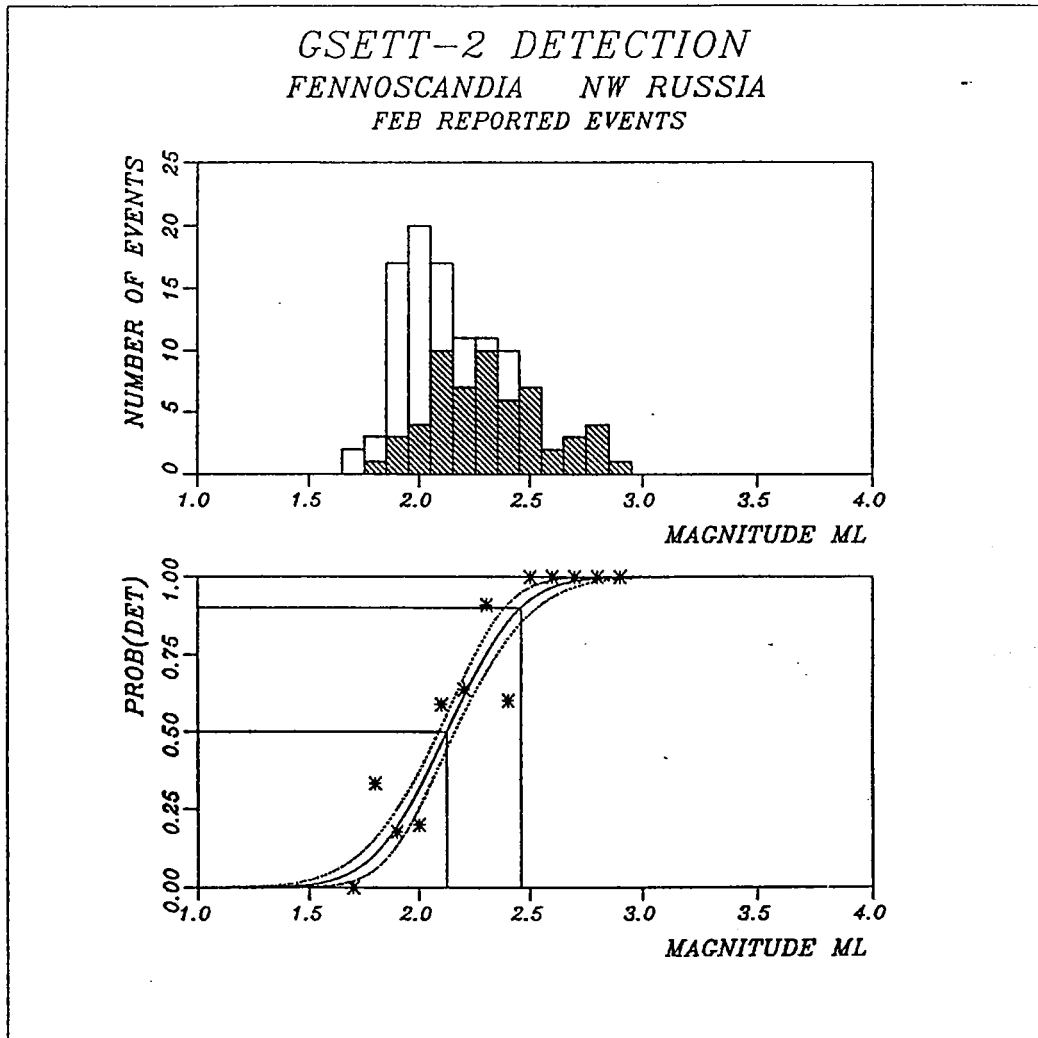


Fig. 7.2.2. Maximum likelihood detectability estimation for Fennoscandia-NW Russia using the Univ. of Helsinki bulletin as a reference. The upper half shows the reference event set and the number of events actually detected for each magnitude. The lower half shows the maximum likelihood detectability curve and its confidence limits. The actual percentage of detected events at each magnitude is also shown. This figure is based upon FEB reported events as discussed in the text.

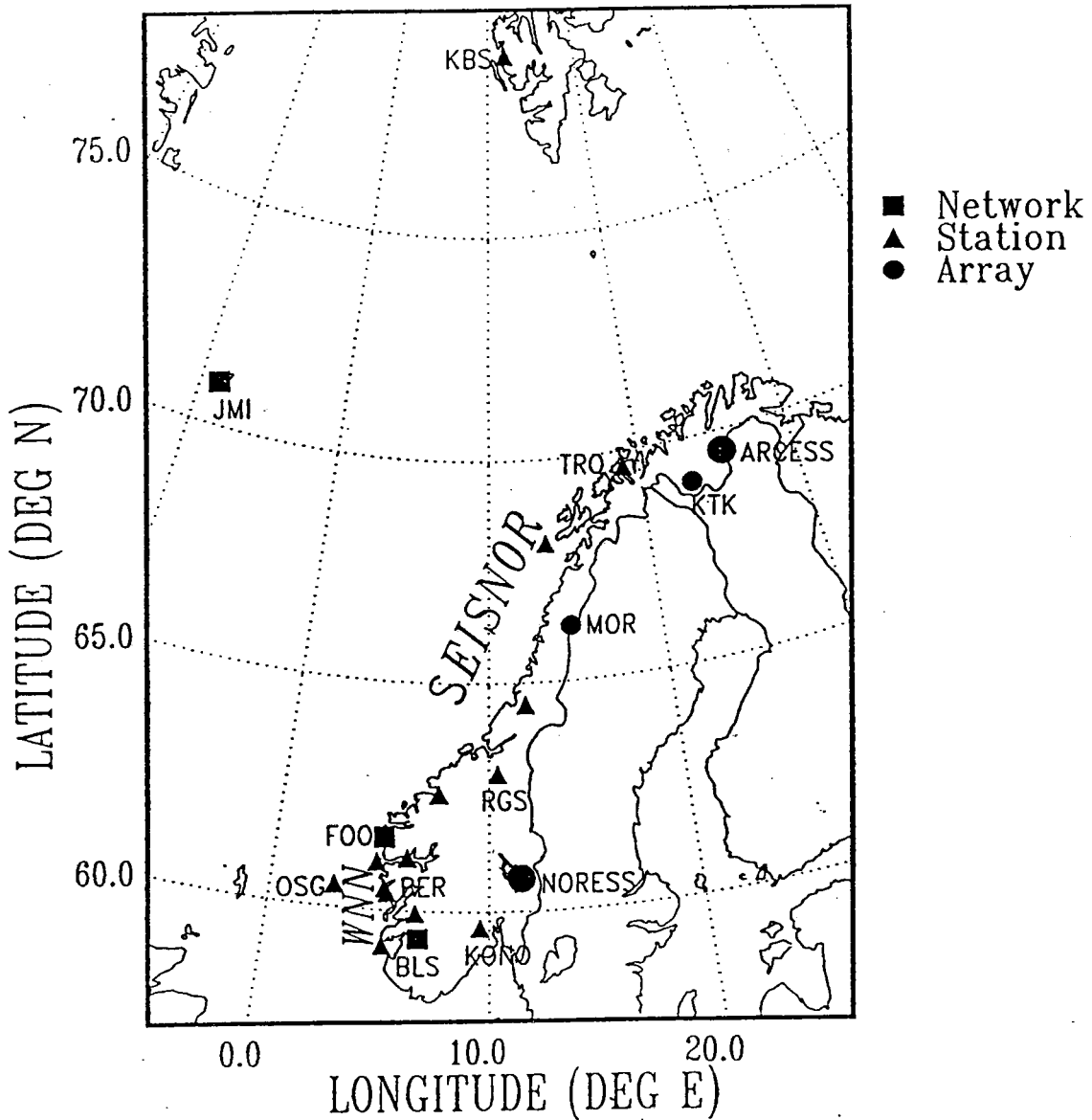


Fig. 7.2.3. The map shows the stations of the WWN and SEISNOR networks operated by the University of Bergen and used in their bulletin work. Note that BLS, FOO and JMI are small networks comprising 4, 3 and 2 stations, respectively, and that MOR and KTK are small-aperture (0.5 km) 6-element arrays. The locations of NORESS and ARCESS are also shown.

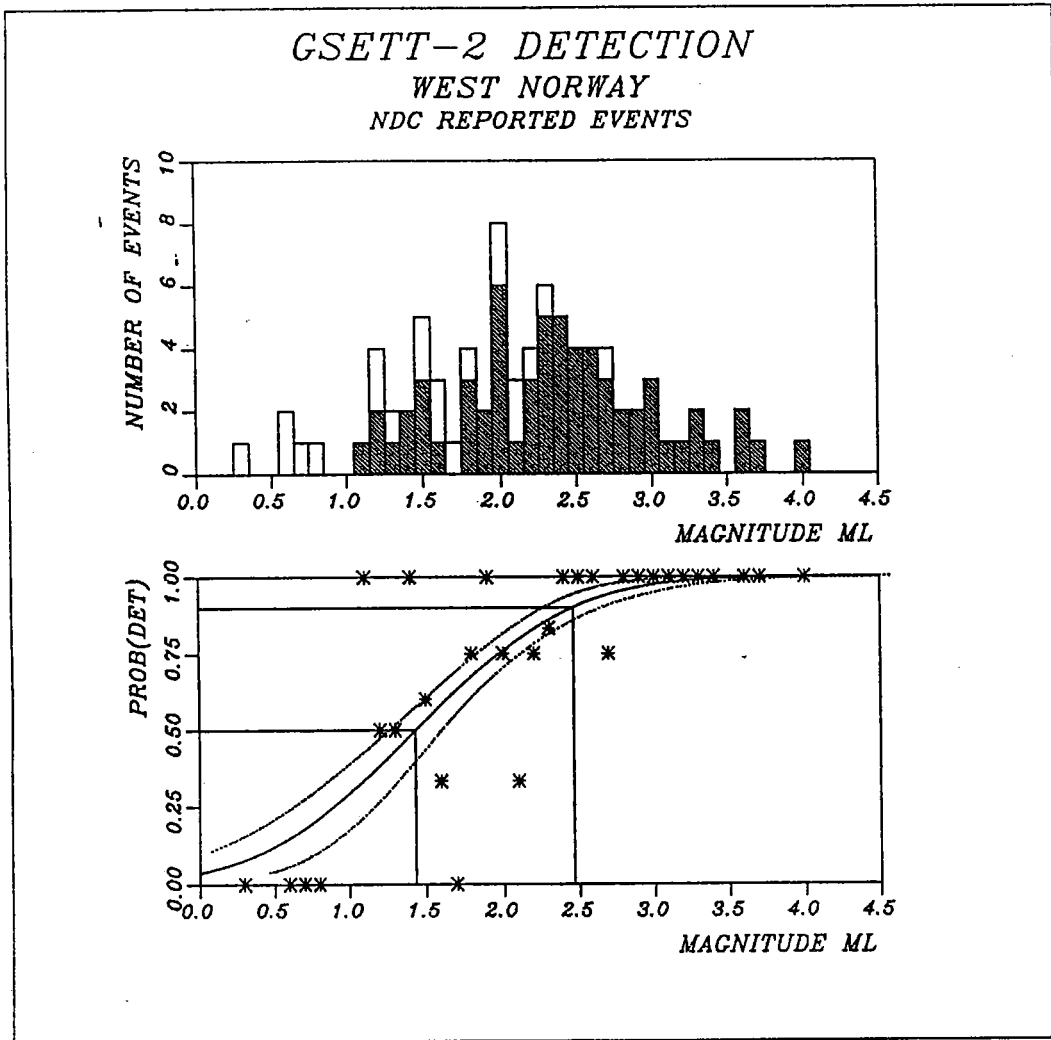


Fig. 7.2.4. Maximum likelihood detectability estimation for western Norway using the Univ. of Bergen bulletin as a reference. The upper half shows the reference event set and the number of events actually detected for each magnitude. The lower half shows the maximum likelihood detectability curve and its confidence limits. The actual percentage of detected events at each magnitude is also shown. This figure is based upon a one-array detection requirement.

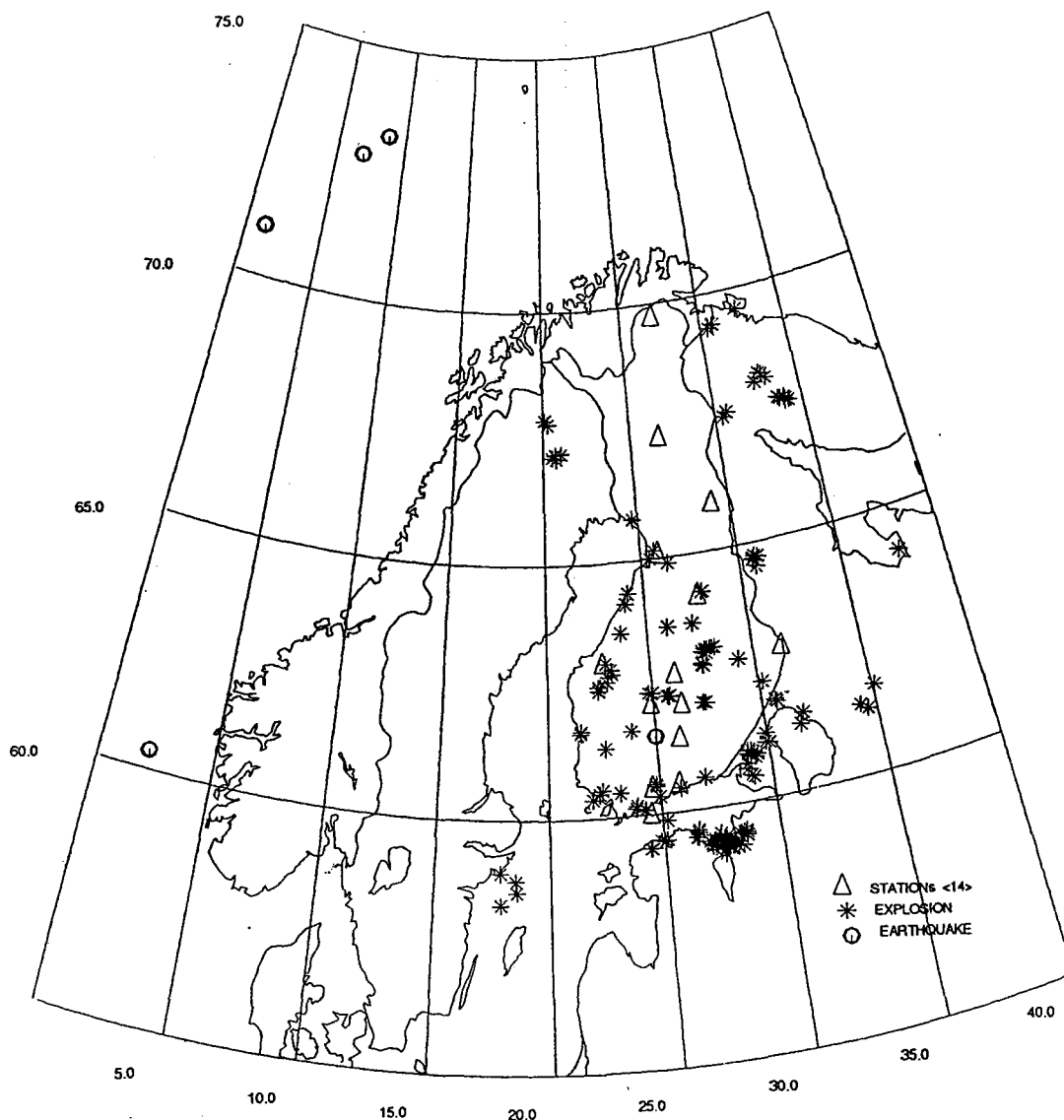


Fig. 7.2.5. Epicenters of the 257 reference events common to the Helsinki bulletin and the FEBs, and stations of the Finnish Seismograph Network. One earthquake (79.89°N , 24.23°E) lies outside the range of the map.

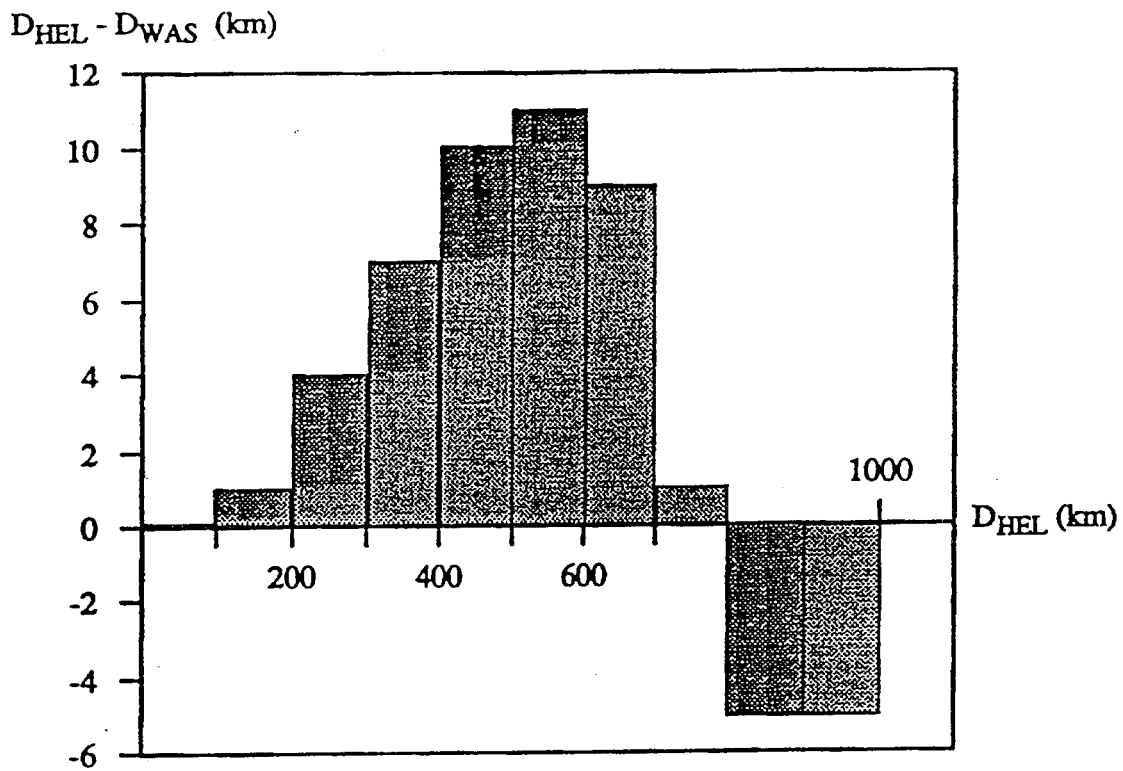


Fig. 7.2.6. The difference between the epicentral distances D_{HEL} and D_{WAS} plotted versus D_{HEL} . D_{HEL} is a distance calculated from the Helsinki velocity model using the travel-time difference of the first arriving P- and S-pair. D_{WAS} is the corresponding distance obtained from the WAS EIDC velocity model.

7.3 GSETT-2 Evaluation: Detection of aftershocks from the W. Caucasus earthquake of 29 April 1991

Introduction

On 29 April 1991 a large earthquake ($M_s = 7.3$) occurred in western Caucasus, with coordinates 42.453N, 43.673E, $h = 17$ km (NEIC).

The earthquake was followed by a large number of aftershocks. According to the catalogue of Starovoi et al (1992), 114 aftershocks were recorded on the day of the main shock (29 April) and 360 aftershocks had been recorded by the end of May.

The earthquake occurred early during GSETT-2 (main phase), and caused a considerable load at the NDCs as well as EIDCs. The day 29 April has been selected as one of the days for which reprocessing will be made at EIDCs. Consequently, this day is useful for studying the performance of the experimental global system during a day of particularly high seismic activity.

Method

In this paper we address the detection capability of the system in place during GSETT-2, and compare with NEIC bulletins. We use the method of Ringdal (1975), whereby the system to be evaluated is compared with an independent reference system. The reference is in this case provided by the catalogue of Starovoi et al (1992). The event sizes in that catalogue are quoted in terms of the K-value of each event. The K-value is related to M_s by the formula

$$K = M_s \cdot 1.8 + 4.0 \quad (1)$$

We have converted all K-values to M_s using (1) prior to applying the maximum-likelihood estimation technique.

Data

Table 7.3.1 summarizes the number of detected events by the various systems. We note that the two EIDCs for which we had data (reprocessed CELs from Stockholm and Washington) had a very similar performance, and reported about half of the events in the reference catalogue. NEIC reported only one third of the reference events in their monthly bulletin. The rapid QED service (Quick Epicenter Determination) reported very few of the events.

Note that the QED follows approximately the same time schedule as the CELs and FEB. Therefore, a comparison between the QED and the final CEL is of interest. We note, however, that the revised CELs were compiled with a delay of many months.

Detectability

The results of the detectability study are summarized in Figs. 7.3.1-6.3.4 and Table 7.3.2.

Figs. 7.3.1-7.3.2 show the detectability estimates for the GSETT-2 revised CEL (STOIDC) and NEIC. The data cover aftershocks during the day 29 April. The detectability of GSETT-2 is better than NEIC by at least one half magnitude unit. However, it is noteworthy that almost all of the "larger" events missed by either system were earthquakes within 3 hours of the main shock.

In light of this observation, we also computed detectability statistics for the time interval 12-24 GMT on 29 April, i.e., excluding the first 3 hours after the main shock. The results are shown in Figs. 7.3.3-7.3.4, and show improvements for both systems. In particular, the improvement is significant for NEIC.

Conclusion

The detectability of the GSETT-2 system for the W. Caucasus earthquake sequence is better than that of NEIC. The difference is particularly significant during the first 3 hours after the main shock.

It appears that a main reason for this good GSETT-2 performance is the reporting by sensitive regional arrays. It was also helpful to have a local station (KIV) at only 2 degrees distance, but it appears that almost all of the events would have been reported even without KIV data. However, the KIV data undoubtedly contributed to improving the location accuracy of the GSETT-2 reportings.

F. Ringdal

References

- Ringdal, F. (1975): On the estimation of seismic detection thresholds, *Bull. Seism. Soc. Am.*, 65, 1631-1642.
- Starovoit et al (1992): Catalog of aftershocks of the West Caucasus earthquake of 29 April 1991.

	Number of Events
Starovoit et al catalogue	115
Stockholm CEL (revised)	63
Washington CEL (revised)	57
NEIC monthly list	35
QED list	6

Table 7.3.1. Earthquakes reported for 29 April 1991, Caucasus sequence. For the two CELs in the table, only events confirmed by the Starovoit et al catalogue have been counted.

	μ	σ	μ_{90}
All events on 29 April:			
GSETT-2 revised CEL	3.62	0.28	3.98
NEIC	4.07	0.37	4.55
Events during 1200-2400 on 29 April:			
GSETT-2 revised CEL	3.58	0.22	3.86
NEIC	3.86	0.10	3.99

Table 7.3.2. Detectability estimates for Caucasus sequence, in terms of M_s computed from Starovoit et al (1992). Note that μ is the 50% incremental detection threshold, and μ_{90} is the 90% threshold

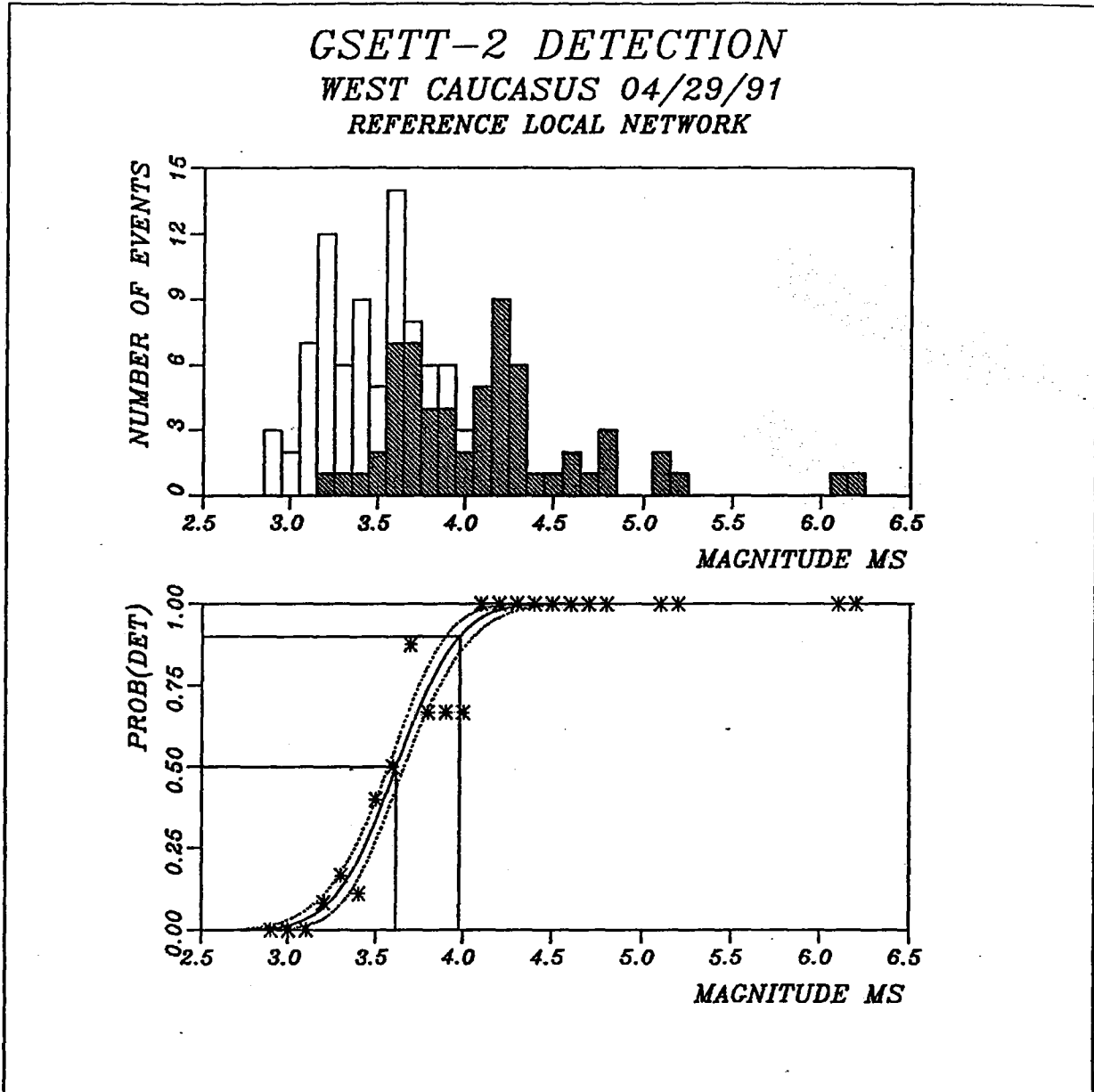


Fig. 7.3.1. Detectability results for GSETT-2 revised CEL; 29 April: Detectability estimate for W. Caucasus aftershocks using the catalogue of Starovoit et al (1992) as reference. The upper part shows the number of reference events at each magnitude, with the hatched columns indicating the number of detections. The lower part is a maximum likelihood detection curve.

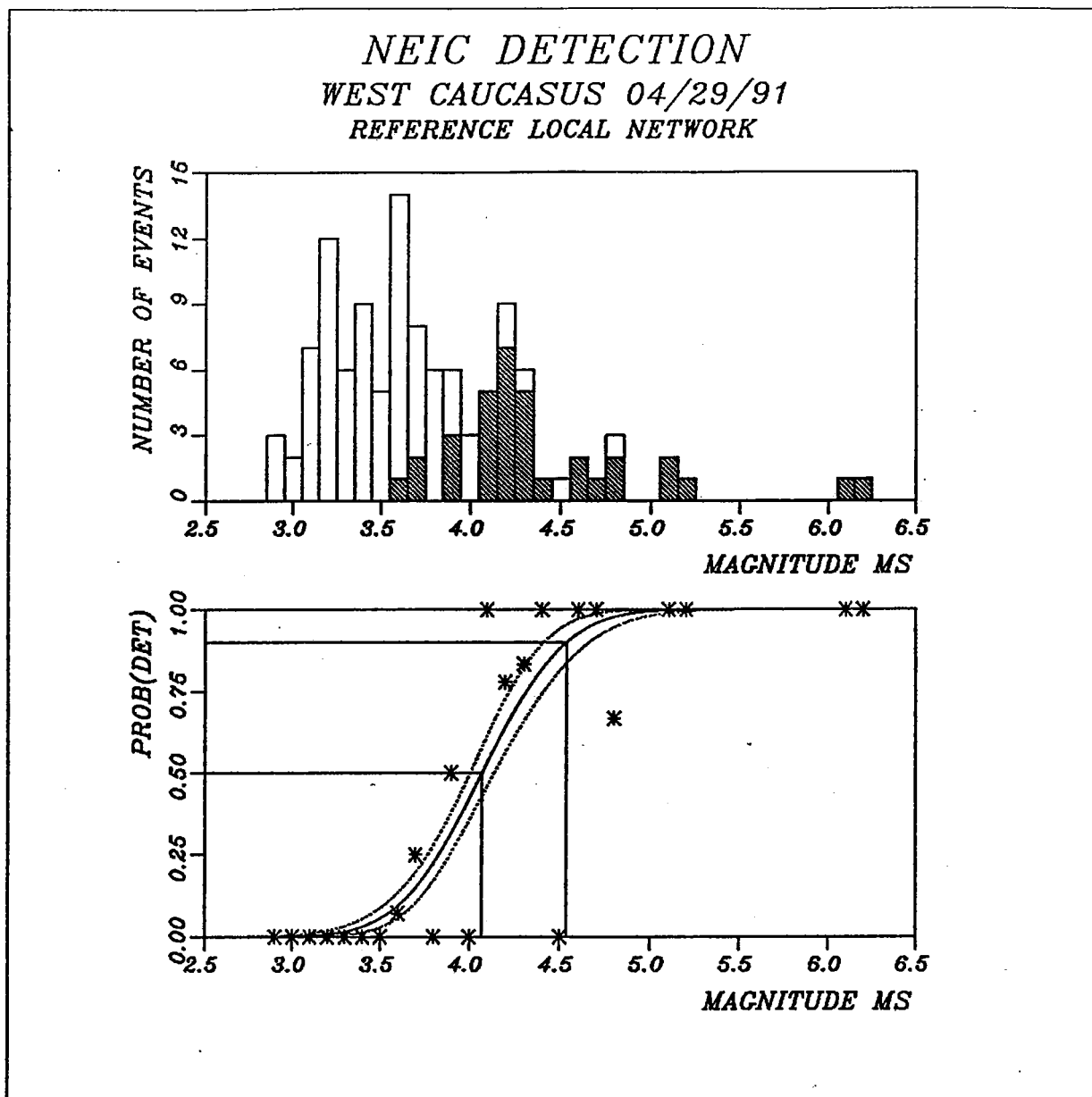


Fig. 7.3.2. Detectability results for NEIC bulletin; 29 April: Detectability estimate for W. Caucasus aftershocks using the catalogue of Starovoi et al (1992) as reference. The upper part shows the number of reference events at each magnitude, with the hatched columns indicating the number of detections. The lower part is a maximum likelihood detection curve.

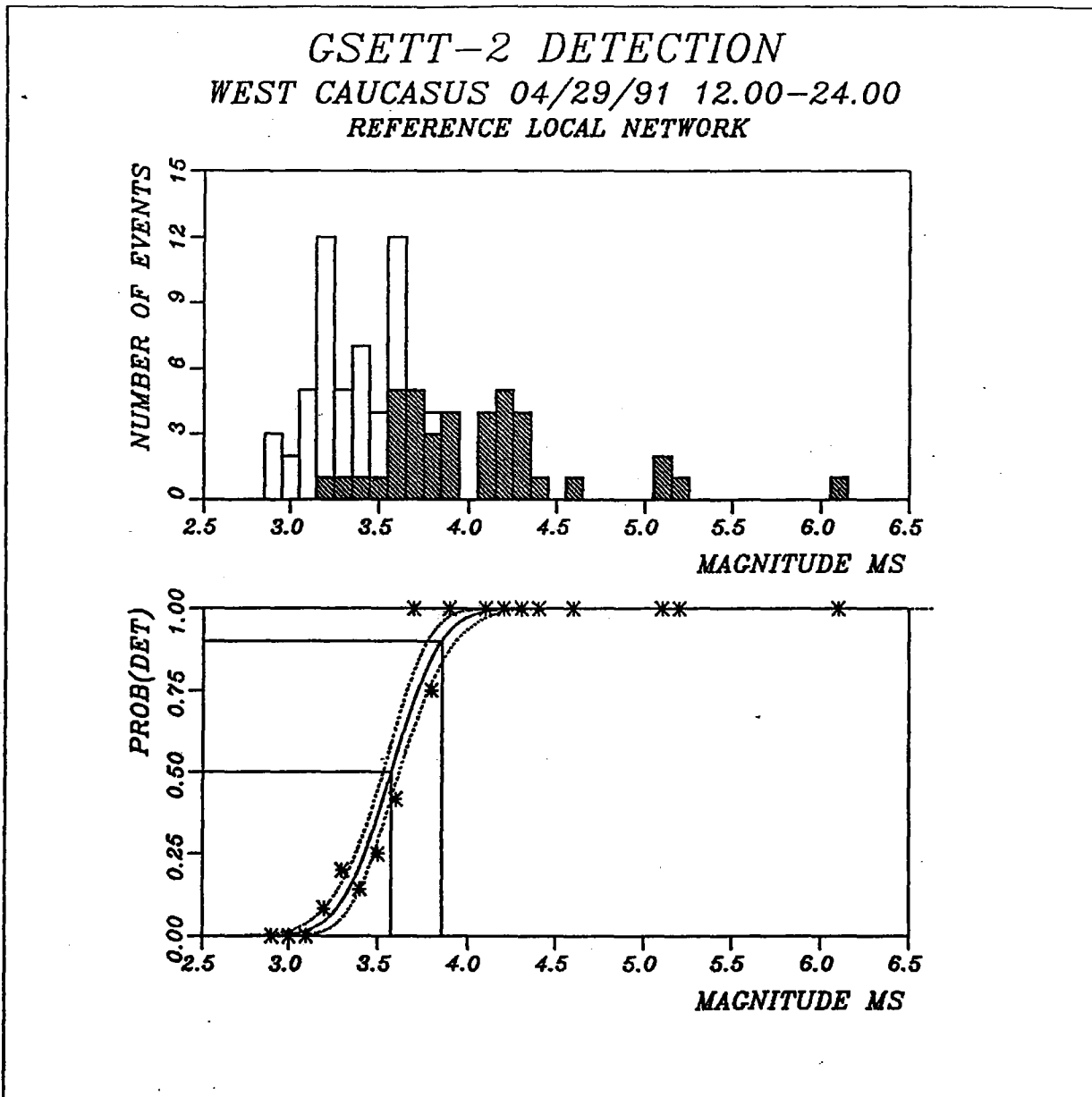


Fig. 7.3.3. Detectability results for GSETT-2 revised CEL; 29 April 1200-2400: Detectability estimate for W. Caucasus aftershocks using the catalogue of Starovoit et al (1992) as reference. The upper part shows the number of reference events at each magnitude, with the hatched columns indicating the number of detections. The lower part is a maximum likelihood detection curve.

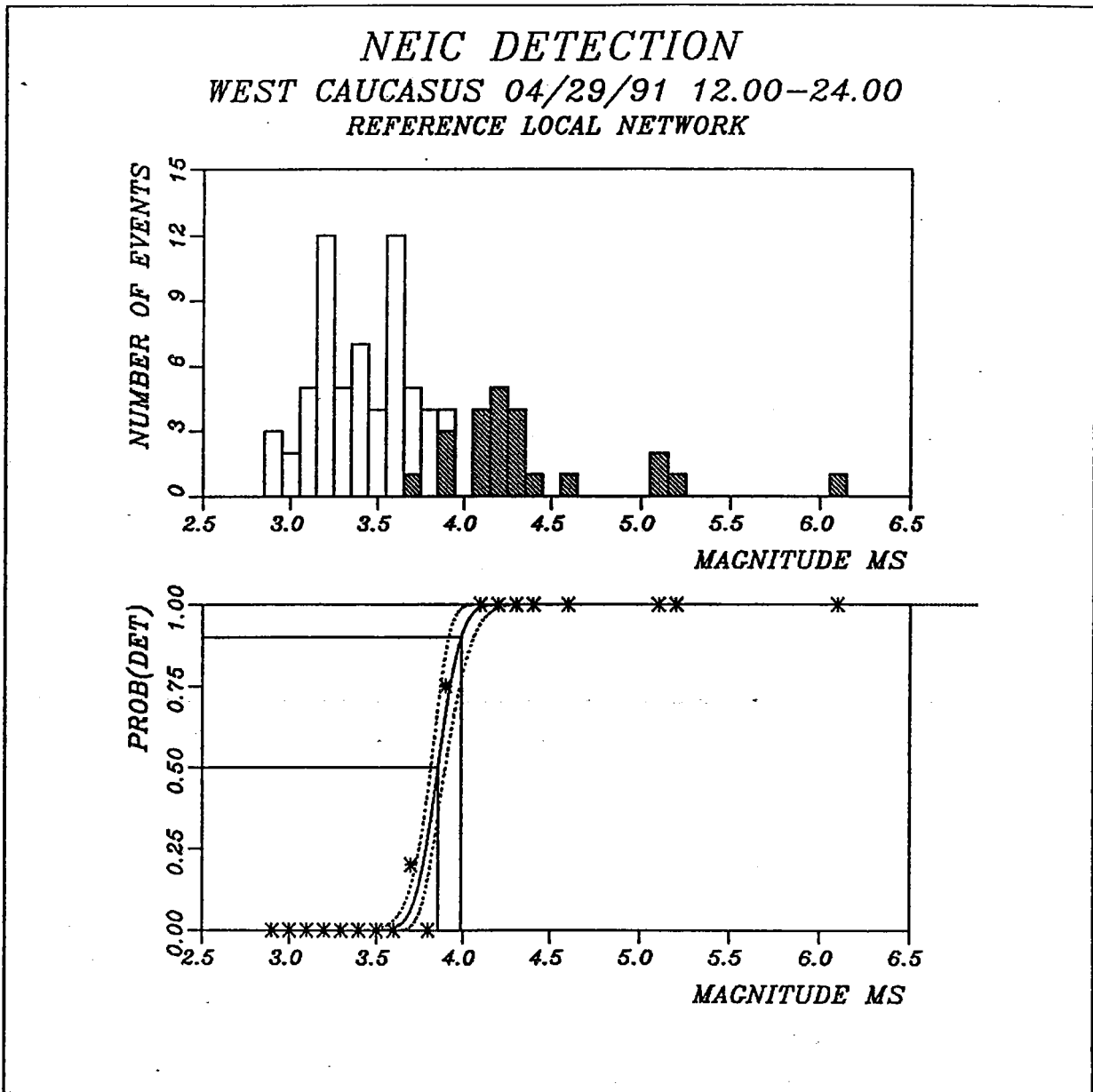


Fig. 7.3.4. Detectability results for NEIC bulletin; 29 April 1200-2400: Detectability estimate for W. Caucasus aftershocks using the catalogue of Starovoit et al (1992) as reference. The upper part shows the number of reference events at each magnitude, with the hatched columns indicating the number of detections. The lower part is a maximum likelihood detection curve.

7.4 Travel time corrections for a 3-D velocity model beneath the NORSAR array

Introduction

For the purpose of improving the event location capability of the NORSAR array, Berteussen (1974) constructed a time correction table from average arrival time residuals for 94 different incident P-wave directions, and Berteussen (1976) concluded that almost all of the observed time residuals across the array can be corrected for by using this table, and therefore the residuals have their origin in the upper mantle and crust beneath the array. Time corrections are computed from this table by linear interpolation between nodes in incident slowness space, and this table is the one most frequently used for time corrections at NORSAR. Due to the very nonuniform distribution of earthquakes, interpolation is unavoidable in this kind of correction procedure. However, if the observed residuals could be explained in terms of subsurface structures, another type of correction table could be made by forward modeling the effects of such structures.

In one of the first applications of travel time tomography in seismology, Aki et al (1977) inverted the time residuals of the NORSAR time correction table for P-wave velocity perturbations beneath the array, and a similar experiment has been done with a slightly different and larger data set. Systematic analysis of this data set revealed the significant influence of diffraction effects like focusing and defocusing from low and high velocity zones, and diffraction effects have been taken into account, in a first-order approximation, using a reformulation of diffraction tomography (Ødegaard and Doornbos, 1992). Synthetic data have been computed for the velocity models produced by ordinary seismic tomography and by diffraction tomography, and from these data correction tables have been constructed. There is no further need for interpolation when using these correction tables. Some results concerning these tables are presented.

Tomography

The basis of ordinary seismic tomography (ST) is the simple relation:

$$\delta\tau = \int_{ray} \delta s \cdot d\sigma \quad (1)$$

This equation states that a change in travel time is due to a slowness perturbation $\delta s = -v^{-2}\delta v$ along the ray, and it predicts a time shift of a reference pulse u_0 :

$$\mathbf{u}(\mathbf{x}, t) = \mathbf{u}_0(\mathbf{x}, t - \delta\tau) \quad (2)$$

Eq. (2) can be viewed as a smooth approximation since it is a valid expression if the slowness perturbation δs varies smoothly within the medium. The reformulation of diffraction tomography (DT), as derived by Doornbos (1992), predicts a diffraction term as a perturbation to the time-shifted reference pulse (which is the smooth approximation of ST):

$$\mathbf{u}(\mathbf{x}, t) = \mathbf{u}_0(\mathbf{x}, t - \delta\tau) + \int_V \mathbf{B} \cdot \nabla \cdot \delta s \cdot dV \quad (3)$$

This reformulation alleviates some of the fundamental problems of both seismic and diffraction tomography. The velocity structure beneath the NORSAR array has been modeled down to a depth of 129 km using ST, Eq. (1), and using DT in the frequency domain with short-period (SP) subarray phase and amplitude residuals from 115 events, and long-period (LP) phase residuals from 31 events. Synthetic data can be computed after forward modeling using Eq. (1) (ray travel times) and Eq. (3) (synthetic wave recordings). Further details concerning these methods are given by Ødegaard and Doornbos (1992).

Correction tables

SP P-wave time correction tables have been constructed for the ST model, using Eq. (1) (ray travel time), and the DT model, after using Eq. (3) with a 1 Hz damped sine reference pulse and iterative correlation between the synthetic array beams and subarray beams for 1.5 s time windows. The two low-pass filtered time correction tables for subarray 01A are plotted in Figs. 7.4.1 and 7.4.2, for slowness values less than 0.08 s/km, corresponding to epicenter distances greater than 30°. Figs. 7.4.3 and 7.4.4 display the predicted time residuals versus the observed time residuals for the two time correction tables and the 115 events. The ray travel time table constructed from the ST model predicts the observed time residuals slightly better than the DT correction table; the normalized squared error is 12% for the ST table and 19% for the DT table, and the correlation coefficient is 0.94 for the ST table and 0.91 for the DT model. For the purpose of constructing a time correction table, the ST model provides the best results. The ST model is given in Table 7.4.1. However, the DT model predicts the phase and amplitude spectra of the data significantly better than the ST model; the normalized squared error for the phase spectra is 20% for the ST model and 10% for the DT model, and the normalized squared error for the amplitude spectra is 75% for the ST model and 55% for the DT model (Ødegaard and Doornbos, 1992).

E. Ødegaard, Univ. of Oslo

References

- Aki, K., A. Christoffersson and E.S. Husebye (1977): Determination of the three-dimensional structure of the lithosphere, *J. Geophys. Res.*, 82, 277-296.
- Berteussen, K.-A. (1974): NORSAR location calibrations and time delay corrections. *Sci. Rep. 2-73/74*, NTNF/NORSAR, Kjeller, Norway.
- Berteussen, K.-A. (1976): The origin of slowness and azimuth anomalies at large arrays, *Bull. Seism. Soc. Am.*, 66, 719-741.
- Doornbos, D.J. (1992): Diffraction and seismic tomography, *Geophys. J. Int.*, 108, 256-266.
- Ødegaard, E. and D.J. Doornbos (1992): Seismic diffraction tomography of array data, *J. Geophys. Res.*, in press.

Layer 1 (0-15km)				$v_0 = 6.2 \text{ km/s}$																		
=	=	=	=	=	=	=	=	=	=	=	=	=	=	=	=	=	=	=	=	=	=	=
=	=	=	=	=	=	=	=	=	=	=	=	=	=	=	=	=	=	=	=	=	=	=
=	=	=	=	=	0.8	-1.7	=	-0.4	=	=	=	=	=	=	=	=	=	=	=	=	=	=
=	=	=	=	0.5	-3.2	-0.9	=	-3.4	-0.2	=	=	=	=	=	=	=	=	=	=	=	=	=
=	=	0.4	-3.5	-4.5	=	3.5	0.1	0.9	1.1	0.2	=	=	=	=	=	=	=	=	=	=	=	=
=	=	-0.7	-4.9	-3.4	-1.5	-0.1	1.6	3.7	0.4	-1.5	=	=	=	=	=	=	=	=	=	=	=	=
=	=	=	-6.3	1.7	-1.0	1.8	0.9	0.6	-1.0	0.0	=	=	=	=	=	=	=	=	=	=	=	=
=	=	=	-3.2	2.3	4.1	4.7	3.0	1.9	-0.1	=	=	=	=	=	=	=	=	=	=	=	=	=
=	=	=	=	-3.9	0.7	3.6	1.5	-0.6	1.0	=	=	=	=	=	=	=	=	=	=	=	=	=
=	=	=	=	2.0	4.3	2.1	1.1	-0.1	-1.0	=	=	=	=	=	=	=	=	=	=	=	=	=
=	=	=	=	=	=	=	=	=	=	=	=	=	=	=	=	=	=	=	=	=	=	=
=	=	=	=	=	=	=	=	=	=	=	=	=	=	=	=	=	=	=	=	=	=	=
=	=	=	=	=	=	=	=	=	=	=	=	=	=	=	=	=	=	=	=	=	=	=
=	=	=	=	=	=	=	=	=	=	=	=	=	=	=	=	=	=	=	=	=	=	=
Layer 2 (15-34km)				$v_0 = 6.9 \text{ km/s}$																		
=	=	=	=	=	=	=	=	=	=	=	=	=	=	=	=	=	=	=	=	=	=	=
=	=	=	=	=	0.1	-0.8	=	=	=	=	=	=	=	=	=	=	=	=	=	=	=	=
=	=	=	=	-0.9	-1.9	0.1	-1.9	1.0	-0.5	=	=	=	=	=	=	=	=	=	=	=	=	=
=	=	0.4	-1.2	-2.7	0.6	-0.2	2.8	0.7	3.0	0.8	=	=	=	=	=	=	=	=	=	=	=	=
=	=	-1.2	-3.3	-2.4	0.3	-0.1	1.0	1.1	-0.2	2.5	=	=	=	=	=	=	=	=	=	=	=	=
=	=	-4.8	-6.8	0.5	2.2	0.9	-0.8	-0.7	-1.8	0.2	-1.1	=	=	=	=	=	=	=	=	=	=	=
=	=	1.6	-1.7	0.0	0.5	1.0	0.3	-0.5	-1.5	4.0	=	=	=	=	=	=	=	=	=	=	=	=
=	=	1.0	-3.2	-3.3	-2.2	2.7	0.7	-0.2	3.7	=	=	=	=	=	=	=	=	=	=	=	=	=
=	=	=	0.2	2.5	0.2	1.0	2.7	-1.6	0.5	0.1	=	=	=	=	=	=	=	=	=	=	=	=
=	=	=	0.7	-0.4	-1.2	1.2	4.6	-0.3	1.8	0.2	=	=	=	=	=	=	=	=	=	=	=	=
=	=	=	=	0.1	-1.7	3.2	=	-0.4	1.3	=	=	=	=	=	=	=	=	=	=	=	=	=
=	=	=	=	=	=	=	=	=	=	=	=	=	=	=	=	=	=	=	=	=	=	=
=	=	=	=	=	=	=	=	=	=	=	=	=	=	=	=	=	=	=	=	=	=	=
Layer 3 (34-54km)				$v_0 = 8.1 \text{ km/s}$																		
=	=	=	=	=	=	=	=	=	=	=	=	=	=	=	=	=	=	=	=	=	=	=
=	=	=	=	5.6	-0.5	-2.6	-2.1	0.5	-4.3	=	=	=	=	=	=	=	=	=	=	=	=	=
=	=	=	1.7	-1.2	-1.1	1.1	1.5	2.0	4.2	-2.8	=	=	=	=	=	=	=	=	=	=	=	=
=	=	1.0	-0.1	-4.8	-2.1	-2.0	-1.5	-0.8	2.9	-0.3	-2.5	=	=	=	=	=	=	=	=	=	=	=
=	0.1	0.4	-2.7	0.8	0.5	-2.9	-2.2	-2.5	1.5	-0.3	-3.9	=	=	=	=	=	=	=	=	=	=	=
=	4.4	-1.2	1.8	-0.3	-4.5	0.0	0.9	1.6	0.7	2.1	3.4	-1.3	=	=	=	=	=	=	=	=	=	=
=	-0.2	-0.1	0.8	-0.9	0.1	-2.1	1.2	0.7	4.5	-0.1	4.1	=	=	=	=	=	=	=	=	=	=	=
=	3.5	-0.4	0.4	-0.3	-1.8	-3.6	-1.1	0.8	0.6	-2.9	0.0	=	=	=	=	=	=	=	=	=	=	=
=	=	1.3	-2.9	-0.7	0.2	0.1	-1.7	1.8	4.5	-0.9	=	=	=	=	=	=	=	=	=	=	=	=
=	=	-0.1	-5.6	-0.7	1.9	0.5	1.2	3.3	2.9	4.5	=	=	=	=	=	=	=	=	=	=	=	=
=	=	=	0.2	-2.5	-3.3	-1.5	-1.0	2.6	5.6	2.2	=	=	=	=	=	=	=	=	=	=	=	=
=	=	=	=	=	0.4	1.6	0.3	=	=	0.4	=	=	=	=	=	=	=	=	=	=	=	=
=	=	=	=	=	=	=	=	=	=	=	=	=	=	=	=	=	=	=	=	=	=	=

Table 7.4.1. The ST model. The depth interval and initial P-wave velocity v_0 for each layer are given. Each value represents the velocity perturbation in %, relative to the initial value in a box with horizontal dimensions $15.4 \times 15.4 \text{ km}^2$. “=” denotes no coverage. Subarray 01A is situated at the center of the grid. (Page 1 of 2)

Layer 4 (54-79km) $v_0 = 8.1$ km/s

=	=	=	=	-0.4	0.1	-1.2	-4.2	1.7	-3.6	-0.5	=	=
=	=	=	-0.5	1.6	0.8	-0.3	-1.4	-1.2	0.4	2.4	=	=
=	0.2	0.9	-0.9	1.3	1.4	-2.1	1.1	0.8	-1.4	-2.6	-1.6	-0.3
=	2.4	-1.0	-0.2	-2.3	-2.0	-0.2	0.5	0.0	1.4	-1.5	-2.3	-6.0
1.3	-2.0	0.4	-3.0	-3.4	0.6	-0.6	-1.7	-0.3	0.6	2.2	2.2	-3.3
3.9	-4.0	-1.0	-0.9	0.9	3.8	1.2	-0.1	-2.1	-0.4	3.0	5.1	-2.7
0.3	-1.7	-0.3	-1.3	0.0	1.2	0.3	-1.3	-0.5	0.4	0.2	5.2	2.1
2.0	-0.3	-1.3	-2.6	0.2	0.5	-1.5	-0.5	1.5	0.0	0.1	5.9	-0.4
2.0	1.8	-1.5	-3.2	-2.6	-2.2	0.7	3.3	1.5	1.8	-1.3	4.0	0.4
=	-2.0	1.9	-2.7	-5.2	-3.6	-2.0	1.3	5.4	3.4	-1.4	3.2	1.3
=	-0.3	-0.7	-4.0	-1.3	-2.4	-3.8	2.6	6.8	1.4	3.5	5.8	=
=	=	=	-0.2	0.7	1.2	2.5	-0.1	-2.3	2.2	4.6	0.7	=
=	=	=	=	=	0.5	=	2.2	=	=	1.1	=	=

Layer 5 (79-104km) $v_0 = 8.1$ km/s

=	=	0.0	-0.4	-1.1	-0.5	0.4	-0.1	-1.5	-1.4	-1.5	=	=
=	-0.3	-0.4	4.6	3.8	0.8	-1.7	-0.3	-1.9	-1.8	-1.8	-1.6	=
0.7	0.4	1.5	1.0	2.8	-1.6	0.2	-0.6	0.8	0.4	-1.1	-0.2	-1.5
=	2.2	-0.3	0.3	0.5	-2.4	-1.2	0.6	3.1	0.3	1.1	0.7	-3.4
1.2	1.2	-1.0	-1.5	-1.8	-2.4	-1.3	0.4	2.5	3.7	4.1	1.7	-1.2
2.2	-1.8	-3.1	-0.5	-3.3	-3.2	-2.9	-0.5	2.3	6.4	5.4	5.1	-1.1
-2.6	-2.2	-3.6	-2.3	0.6	-2.4	-2.8	-1.7	0.9	5.0	3.4	4.8	-0.2
-2.0	-6.7	-3.5	-2.5	-0.9	-2.5	-2.7	0.4	0.7	0.7	4.9	3.8	3.0
0.0	0.2	-3.3	-1.2	-1.7	-1.0	-2.3	-1.4	-0.1	2.0	3.6	3.4	8.2
0.9	-0.9	-0.5	0.2	1.2	-2.6	-1.5	-0.6	0.9	-3.3	1.9	3.6	7.7
-0.2	-3.2	-2.1	2.6	0.5	-0.2	0.5	0.0	-2.0	-2.1	-0.2	2.8	3.1
=	-1.3	0.3	-0.2	1.8	1.7	3.0	0.7	-4.2	-5.0	1.1	0.3	3.6
=	=	=	-1.3	0.1	2.5	-0.6	-0.6	1.1	-0.4	3.3	2.5	=

Layer 6 (104-129km) $v_0 = 8.1$ km/s

=	1.0	-0.6	2.6	0.0	0.5	0.3	-2.0	-0.7	-3.3	-0.4	0.1	-0.8
=	5.8	9.2	-1.1	1.8	3.3	1.7	0.3	-0.4	-1.6	-0.9	2.0	0.0
2.1	5.0	2.9	3.3	0.4	4.9	5.8	3.6	0.4	2.1	1.0	0.7	0.8
0.8	3.9	5.4	0.7	2.2	1.5	2.6	3.1	2.8	3.1	3.6	2.1	-0.1
1.0	0.7	-3.8	-3.5	-1.4	-1.6	-2.6	0.2	3.7	6.1	5.4	3.2	1.2
0.3	-2.4	-4.6	-4.7	-5.7	-3.7	-5.3	-3.0	3.0	6.1	6.0	4.7	-0.1
-0.8	-2.7	-5.1	-9.6	-8.3	-3.6	-7.4	-3.4	-0.6	4.9	6.3	4.5	3.2
-1.0	-3.7	-2.6	-6.2	-3.4	-4.1	-1.6	-3.2	-0.5	2.0	3.2	2.8	5.9
0.1	-0.8	0.1	-2.8	-3.0	-1.6	1.7	-1.1	-1.7	-2.5	1.2	3.7	5.4
-2.5	-1.6	-0.2	-0.6	0.7	5.5	3.8	-1.4	-3.9	-4.3	-0.9	2.6	4.4
-3.2	0.2	-1.1	2.4	2.7	6.8	2.6	-1.3	-4.4	-7.9	-2.5	2.7	3.3
-1.9	0.1	1.2	1.7	3.3	7.8	2.1	-3.3	-4.9	-5.2	-1.5	-0.1	4.1
=	0.0	0.2	0.5	4.4	1.4	3.7	-0.6	-2.6	-3.9	-2.0	0.0	1.8

Table 7.4.1 (cont.) (Page 2 of 2).

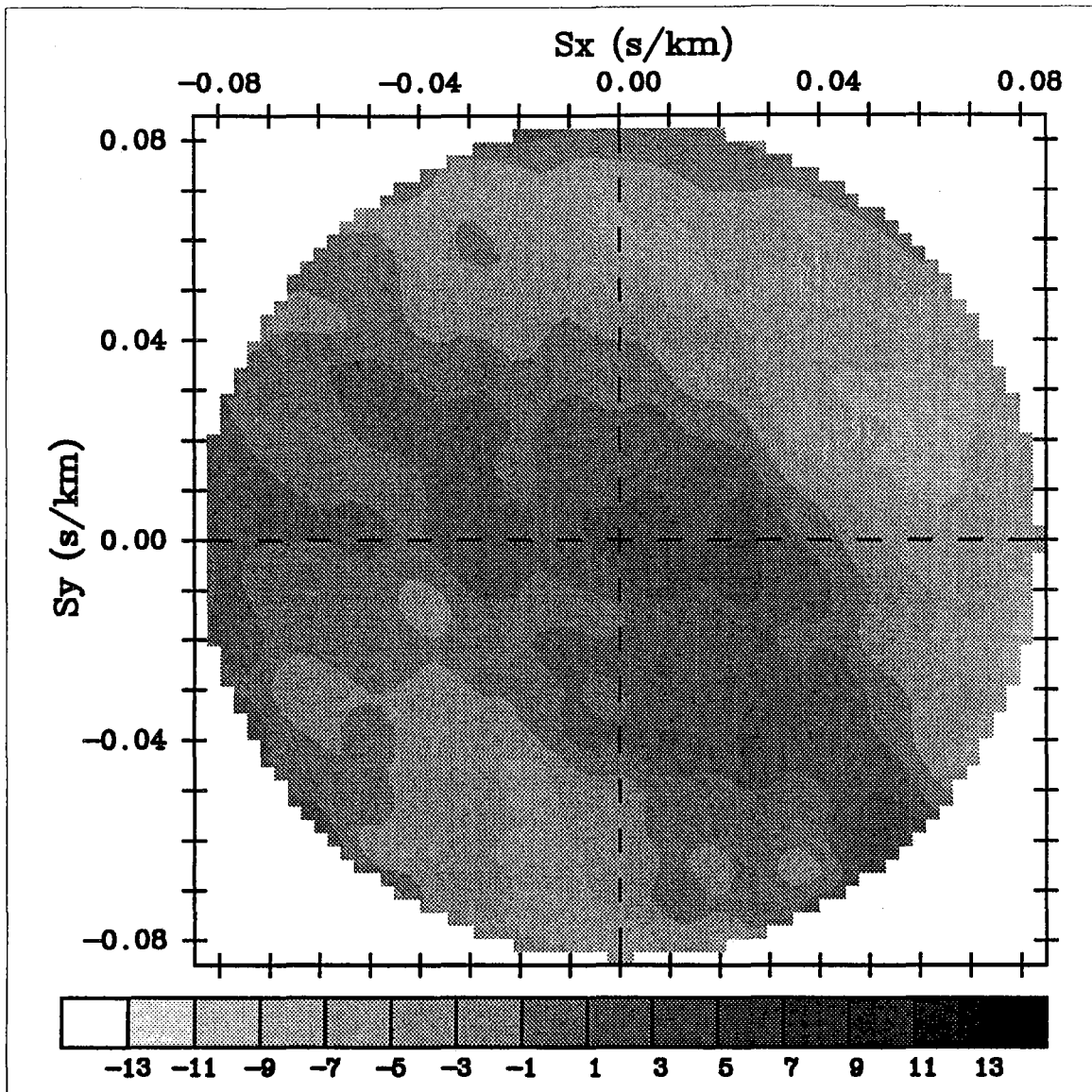


Fig. 7.4.1. The low-pass filtered SP P-wave ray travel time corrections at subarray 01A, for the ST model (given in Table 7.4.1) and for slowness values less than 0.08 s/km. The SP sampling rate is 20 Hz, and the time delay is given in units of 0.05 s.

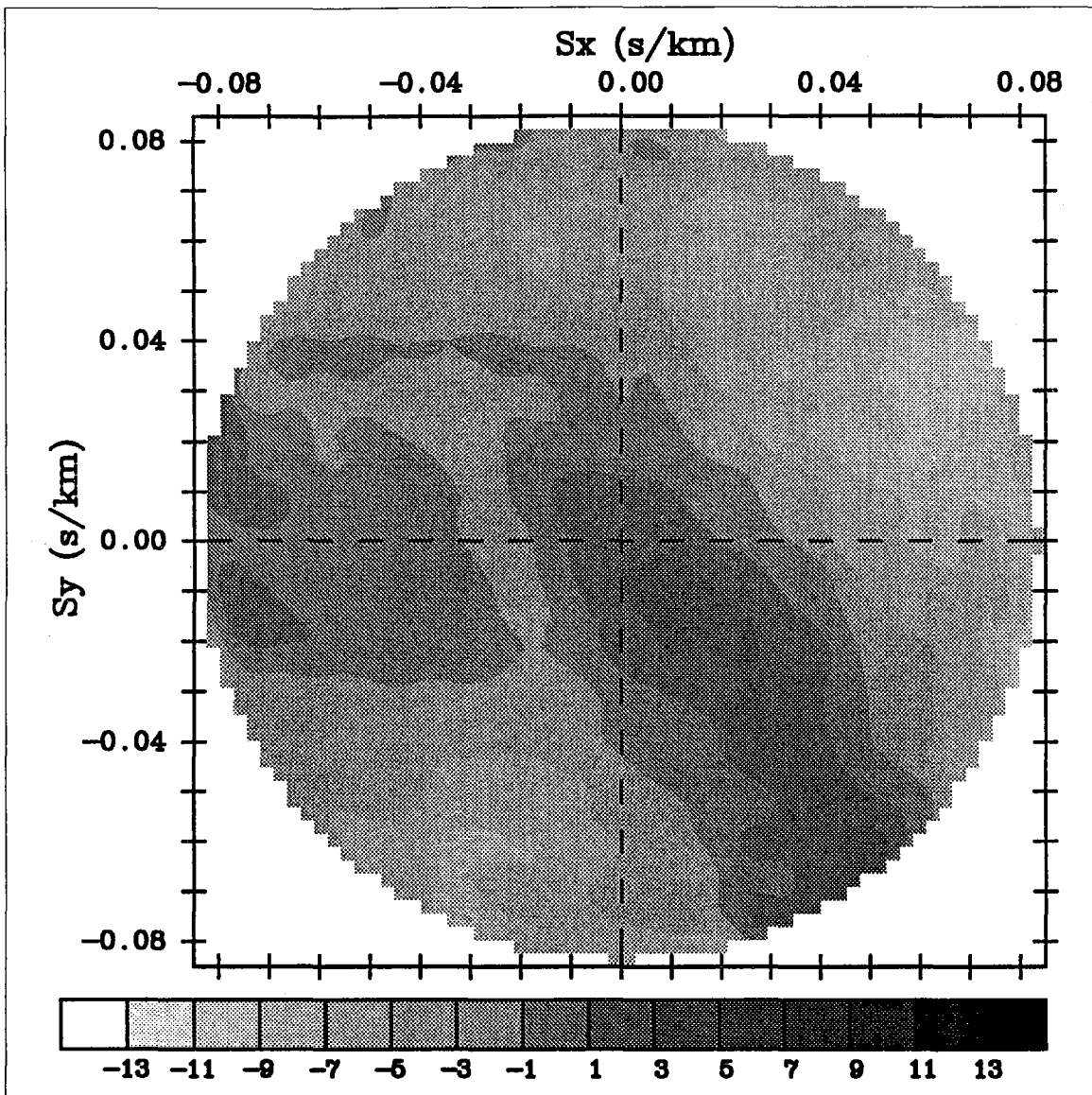


Fig. 7.4.2. The low-pass filtered SP P-wave time corrections at subarray 01A for the DT model and a 1 Hz damped sine reference pulse.

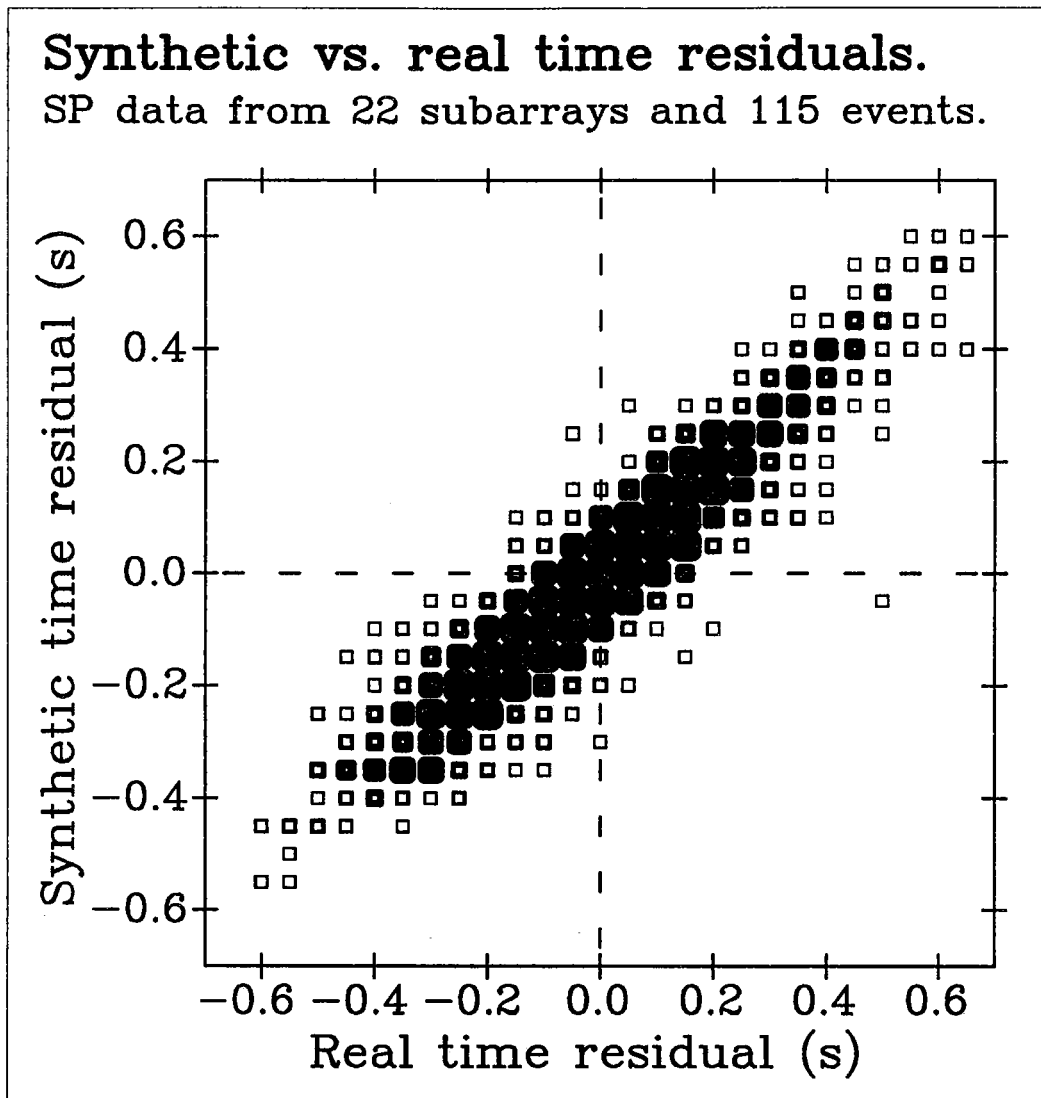


Fig. 7.4.3. Predicted SP P-wave ray travel time residuals versus observed time residuals for the ST model. Symbol size is proportional to number of data.

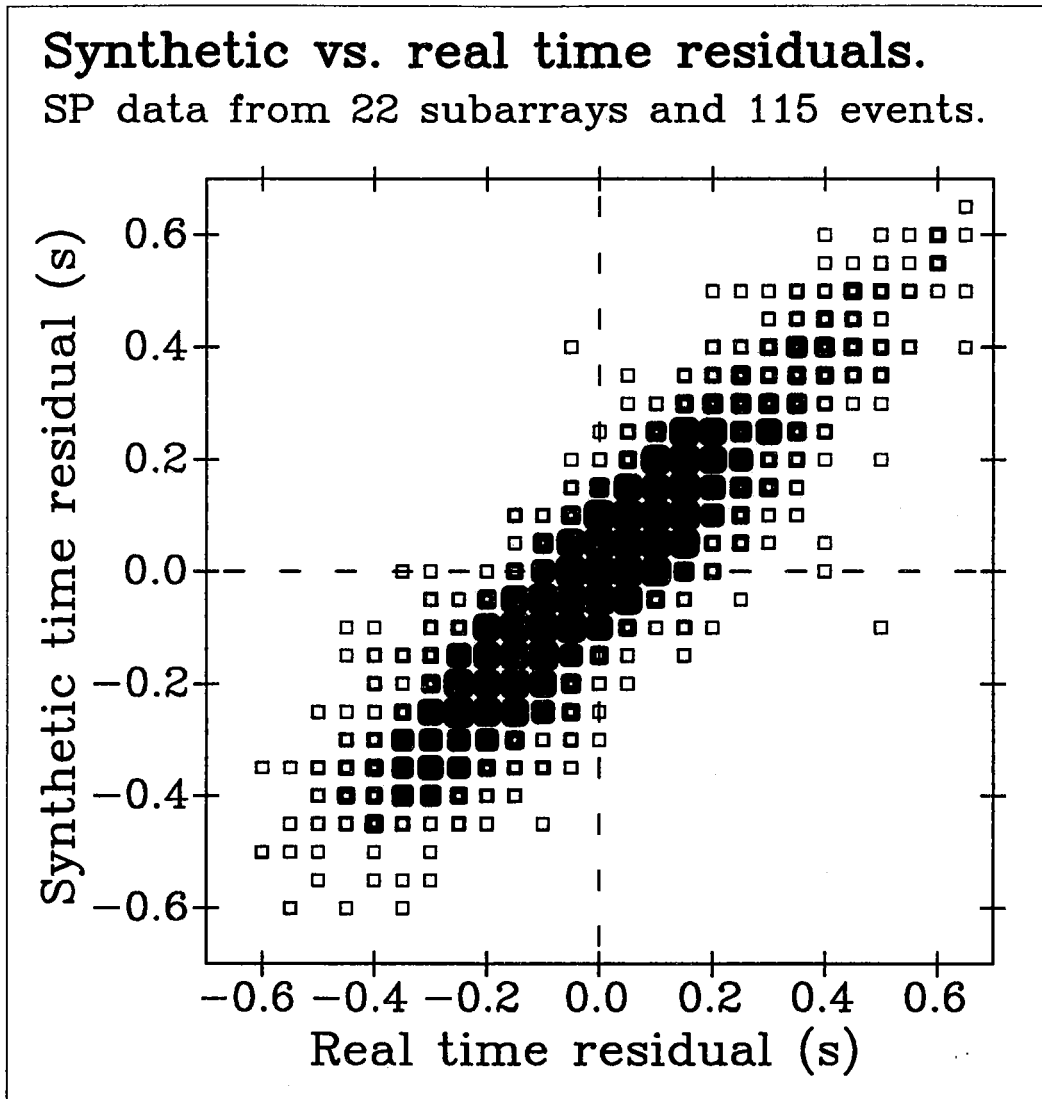


Fig. 7.4.4. Predicted SP P-wave time residuals versus observed time residuals for the DT model and a 1 Hz damped sine reference pulse.

7.5 Automatic phase association and event location using data from a network of seismic microarrays

Introduction

As the number of digital seismic stations around the world increases, it becomes more and more important to automate the data processing. Traditionally, the data processing has consisted of the following steps:

- Detection of phases at the individual stations.
- Extraction of parameters of the detected phases.
- Association of phases at the different stations to form events.
- Event location.

To be able to conduct automatic phase association and event location, initial identification and azimuth estimation of the detected phases are essential.

Using three-component data from NORESS and ARCESS, Suteau-Henson (1991) showed that P- and S-phases could be correctly classified from polarization attributes with a success rate of 82% for NORESS and 89% for ARCESS. P-wave azimuths at both stations were estimated with a standard deviation of 7-11°. At ARCESS, the S-wave azimuths had a standard deviation of 18-19°, although with a 180° ambiguity, whereas the scatter in the S-wave azimuths at NORESS were significantly larger (a standard deviation of 25° for L_g and 42° for S_n).

Riviere-Barbier et al. (1992) conducted a similar study using three-component data from the IRIS/IDA stations in the former USSR. The results obtained from analysis of these 4 stations did not quite match the results obtained for NORESS and ARCESS, mainly due to more complex geology near the receivers. In both studies referenced above, the large differences in the wave propagation characteristics between the different regions required that the phase identification criteria be developed individually for each three-component station.

Despite the documented performance of different three-component processing schemes, there are to our knowledge no sparse three-component network where phase detection, phase association and event location are conducted in a completely automatic mode. It has, however, been demonstrated that the information provided by individual seismic arrays permits automatic phase association and event location using a network of array stations. The precise azimuth and apparent velocity estimates provided by f-k analysis of the array sensors constrain the use of the detected phases in the phase association procedure. Utilizing this information, the ESAL algorithm of the Intelligent Monitoring System (IMS) (Bache et al., 1990) produces routinely both regional and teleseismic event locations, using data from the 4 regional arrays in northern Europe (ARCESS, FINESA, GER-ESS and NORESS). Based on a somewhat different approach, the generalized beamforming method (GBF) (Ringdal and Kväerna, 1989) produces automatically a regional bulletin using the same detection data.

A study of data recorded at the NORESS array (Kværna and Ringdal, 1992) showed that by supplementing a three-component station with a very small vertical sensor three-element array with a typical aperture of 300 meters, reliable phase identification could be obtained. The quite stable apparent velocity and azimuth estimates produced by f-k analysis of the 4 vertical sensors of this microarray, indicates that data from a network of such microarrays can be processed using existing phase association and event location algorithms.

In this contribution we will first evaluate the performance of microarrays at the ARCESS and FINESA sites. Although a separate study has been conducted at NORESS (Kværna and Ringdal, 1992), we will for comparison reevaluate the performance of a microarray at NORESS. Secondly, we will conduct network phase association and event location applying the GBF method to microarray data from ARCESS, FINESA and NORESS, see Fig. 7.5.1.

Microarrays

For all three microarrays we conducted automatic detection processing and post-detection analysis for a period of 12 days (9-20 April 1992). The detection processing was similar to that used in the study of Kværna and Ringdal (1992).

The post-detection processing included broadband f-k array analysis (Esmersoy et al., 1985; Kværna and Doornbos, 1986) of each detected signal using the 4 vertical-component sensors of the microarrays. For the f-k analysis, we used a 5 sec. long data interval starting 0.5 sec. before the estimated onset time, and a frequency band similar to the filter band of the detecting beam.

To obtain a data base against which to evaluate our results, we extracted all seismic phases detected by the three full arrays and associated with regional events for the 12-day period. Results from the generalized beamforming procedure (GBF) (Ringdal and Kværna, 1989) were used in order to validate these reference events. *P*-coda detections and multiple *S*-phases were ignored, so that each event provided a maximum of 3 phases (*P*, *S* and *L_g*). These phases were then matched to the detection lists produced by the microarrays, and the apparent velocity and azimuth estimates were compared.

The problem of false alarms is inevitably encountered when a detector is operated at a low detection threshold. In conducting automatic phase association and location it is critical to identify these false alarms. When processing the full arrays, phases with low apparent velocities (< 3.0 km/s) are generally discarded from further analysis. As the final step in the analysis of the individual microarrays, we evaluated their capability to identify phases with low apparent velocities. This was done by matching all detections of the microarray (both associated and unassociated phases) to the full array detection list, using the apparent velocity estimates of the full array as the reference.

ARCESS

The geometry of the ARCESS microarray is given in Fig. 7.5. 2. The center instrument A0 is three-component, whereas A1-A3 are vertical only. The aperture is about 300 meters.

Fig. 7.5.3 shows the apparent velocity estimates derived from vertical sensors of the microarray for *P* phases (circles) and *S* phases (asterisks) for the reference data set of phases associated with regional events. Of the 303 phases analyzed, 79.2% were correctly classified as *P* or *S* when an apparent velocity of 5.8 km/s was used to separate the two classes. These results are not as good as those earlier published for the NORESS site (Kværna and Ringdal, 1992), where a success rate exceeding 95% was found. It is particularly significant that for epicentral distances less than 600 km, several *P*-phases have *S*-type apparent velocities on the microarray. It is most likely that this phenomenon is due to the near-receiver structure, although no studies have been conducted to map the structure in any detail.

We have attempted to improve the initial phase identification by adding an additional constraint on the parameter data. We have observed that due to the preceding *P*-coda, the *S*-phases have seldom a high signal-to-noise ratio (SNR), whereas many of the *P* phases have high SNR. Based in these observations the following rule was introduced:

Phases with SNR > 10 and apparent velocity > 4.5 km/s are P-phases.

This improved the percentage of correctly classified phases to 84.8%.

In this study we have not attempted to include any three-component polarization attributes in the initial phase identification, but tried to evaluate what can be achieved using only f-k analysis of the 4 vertical sensors. As mentioned in the introduction, Suteau-Henson (1991) showed that by using three-component data from ARCESS, *P*- and *S*-phases could be correctly classified with a success rate of 89%. This indicates that if we combine the polarization attributes derived from the three-component instrument of the microarray with the attributes derived by f-k analysis of the 4 vertical sensors, there may be a significant improvement in the number of correctly classified phases.

Figs. 7.5.4 and 7.5.5 show a comparison between the azimuth estimates computed by f-k analysis of the microarray and the azimuth to the epicenters of the reference data set (computed by the GBF algorithm), for *P* and *S*-phases, respectively. For the *P*-phases of Fig. 7.5.4 the median error is 10.4° and for the *S*-phases of Fig. 7.5.5 the median error is 6.8° . These results show that azimuth constraints can be actively used in the phase association and event location procedure.

As the final step in the evaluation of the ARCESS microarray we estimated its capability to identify noise detections (false alarms). The reference data here were all detections of the full array where the f-k spectra showed typical signal behavior with a pronounced peak. The results are presented in Table 7.5.1a. From this table it is seen that 75.4% of the evaluated detections were correctly classified applying broadband f-k analysis to the microarray data.

For the 303 phases verified to be associated with regional events, a similar statistics is given in Table 7.5.1b. The important information in this table is that no associated phases are interpreted by the microarray as noise-detections (an apparent velocity of 3.2 km/s is used to determine the upper bound on the class of noise detections). From Tables 1a and 1b it can thus be concluded that for the data set considered, 36.3% of all microarray detections at ARCESS can be discarded from the automatic phase association and event location processing without classifying any verified regional phases as noise.

FINESA

The geometry of the FINESA microarray is given in Fig. 7.5.6. The sensors A1-A3 make an aperture of about 500 meters. The vertical component instrument A0 is not located at the center of the triangle, but is still the only candidate for a center instrument in the microarray. The three-component instrument is located at A1.

Fig. 7.5.7 shows the apparent velocity estimates derived from the four vertical sensors of the microarray or *P* phases (circles) and *S* phases (asterisks) for the reference data set of phases associated with regional events. Of the 355 phases analyzed, 78.6% were correctly classified as *P* or *S* when an apparent velocity of 5.8 km/s was used to separate the two classes. This is close to the success rate obtained for the ARCESS microarray. The majority of the events in the reference data base are found in the active mining areas in Estonia and western Russia, in a distance range between 150 and 250 km from the FINESA site. This is clearly seen on Fig. 7.5.7.

Another feature of Fig. 7.5.7 is the occurrence of *P*-phases with very low apparent velocities in the same 150-250 km distance range. By comparing Figs. 7.5.6 and 7.5.2 we find that the aperture of the FINESA microarray is about 200 meters larger than the aperture of the ARCESS microarray. When processing local and regional phases with high dominant frequencies at the FINESA microarray, broad-band f-k analysis will suffer from spatial aliasing and the lack of coherency between the sensors, and some *P*-phases will therefore come out with low apparent velocities. We can overcome this problem by lowering the frequency band for f-k analysis or alternatively reduce the sensor spacing, but such steps have not been taken in this study. Note that for distances exceeding 400 km, the separation between *P* and *S*-phases are excellent.

Fig. 7.5.8 and Fig. 7.5.9 show a comparison between the azimuth estimates computed by f-k analysis of the microarray and the azimuth to the epicenters of the reference data set (computed by the GBF algorithm), for *P* and *S*-phases, respectively. For the *P*-phases of Fig. 7.5.8 the median error is 13.4° and for the *S*-phases of Fig. 7.5.9 the median error is 8.5° . This is more than observed at the ARCESS array. The apparent alignment of *P*-wave azimuth estimates at about 150° (see Fig. 7.5.8) is also related to the problem with the lack of coherency and spatial aliasing at high frequencies. For such phases the f-k analysis often results in a low apparent velocity and an azimuth close to 150° .

In Table 7.5.2a we present results from analysis of all detections at the FINESA microarray for the 12-day period. As for ARCESS we used the all full array detections where the f-k spectra showed typical signal behavior with a pronounced peak. 70.1% of the microar-

ray detections were correctly classified, which is less than at ARCESS. For the 355 phases verified to be associated with regional events a statistics similar to that of Table 7.2.1b is given in Table 7.5.2b. Both Tables 7.5.2a and 7.5.2b show that a significant number of *P*- and *S*-phases obtain low apparent velocities from f-k analysis of the microarray. This implies that if we were to discard detections with low apparent velocities from further analysis, we would also miss some of the real *P*- and *S*-phases, and that the total benefit from discarding the low-velocity detections in the case of FINESA is very moderate.

NORESS

Although the performance of a microarray at NORESS has been evaluated in a separate study (Kværna and Ringdal, 1992), we will for comparison reevaluate its capability using the common 12-day data set. Fig. 7.5.10 shows the geometry of the NORESS microarray, which is similar to that of ARCESS.

Fig. 7.5.11 shows the apparent velocity estimates derived from the 4 vertical sensors of the microarray for *P* phases (circles) and *S* phases (asterisks) for the reference data set of phases associated with regional events. Of the 164 phases analyzed, 93.3 % were correctly classified as *P* or *S* when an apparent velocity of 6.0 km/s was used to separate the two classes. This confirms the results of the study of (Kværna and Ringdal, 1992).

Figs. 7.5.12 and 7.5.13 show a comparison between the azimuth estimates computed by f-k analysis of the microarray and the azimuth to the epicenters of the reference data set (computed by the GBF algorithm), for *P* and *S*-phases, respectively. For the *P*-phases of Fig. 7.5.12 the median error is 14.0° and for the *S*-phases of Fig. 7.5.13 the median error is 6.5° .

Table 7.5.3a gives results from analysis of all detections at the NORESS microarray for the 12-day period. 77.0% of the microarray detections were correctly classified, which is somewhat less than the percentage obtained by Kværna and Ringdal (1992). 11.2% of the detections were classified as noise which is significantly less than the percentage obtained by Kværna and Ringdal (1992). This difference can be explained by a difference in the noise field, as there are time intervals at NORESS when the number of detections with low apparent velocity increases substantially due to increased water flow and industrial activity in the nearby regions (Kværna, 1990). As was done for the other two microarrays we also computed a statistics for the phases verified to be associated with regional events. We find from Table 7.5.3b that only one of the associated phases is interpreted as noise when an apparent velocity of 3.2 km/s is used as the upper bound on the class of noise detections.

Summary

We have found that seismic microarrays at the ARCESS and FINESA sites do not match the NORESS microarray performance in separating *P*- and *S*-phases based on the apparent velocity estimates. The percentage of correctly classified regional phases were for ARCESS 79.2%, for FINESA 78.6% and for NORESS 93.3%. The success rate for ARCESS was increased to 84.8% when an additional constraint based on SNR and apparent velocity was placed on the definition of *P*-phases. No attempt has been made to

include three-component data or context-sensitive information in the initial phase identification, although the potential for improvement is significant (Suteau-Henson, 1991, Riviere-Barbier et al., 1992).

A summary of the different success rates and median errors is given in Table 4. For direct comparison with the results of Riviere-Barbier et al. (1992), we have also included the percentage of phases with azimuth differences within 25° .

The simple procedure of using apparent velocity estimates to classify *P*- and *S*-phases is very different from the complex classification criteria used at three-component stations (Suteau-Henson, 1991, Riviere-Barbier et al., 1992). For the three microarrays analyzed, almost the same classification criterion could be applied to each site. The only difference was that at NORESS an apparent velocity of 6.0 km/s was used to separate *P* and *S*, whereas at ARCESS and FINESA 5.8 km/s was used. This indicates that at microarrays, very little data and data analysis is required to make initial phase identification work properly. In the two studies of three-component data referenced above it was found that the polarization characteristics of seismic phases were strongly site dependent, and that consequently an extensive data set had to be collected at each station in order to find usable criteria for initial phase identification.

The topic for the next section is to test whether the results presented above are of sufficient merit to allow reliable, automatic phase association and event location using data from a network of microarrays.

Phase association and event location using microarray data

We will in this work apply the generalized beamforming (GBF) method (Ringdal and Kværna, 1989) for associating phases and locating regional events using the detections from the three microarrays. The method is currently in routine use at NORSAR for processing data from the 4 regional arrays in northern Europe (ARCESS, FINESA, GERESS and NORESS), and our attempt will be to process the microarray data without introducing major changes in the processing parameters of the now operational version of the GBF algorithm. For details on the method we refer to a documentation report now in progress. However, we will in the following briefly outline the basic principles.

The GBF algorithm

The basic idea behind the GBF method is to associate detected phases to form seismic events by counting the number of phases that match a hypothetical event at a given target (beam) location at a given origin time. In order to avoid interfering phases that do not belong to the event in question, we impose constraints as part of the phase matching process. The most important constraints of the current operational GBF method are the following:

- Constraint on phase type (*P*, *S* and *noise*) based on apparent velocity estimates.
- Constraint on azimuth to epicenter from actual phase azimuth estimates.

- Constraint on distance to epicenter inferred from values of apparent velocity and dominant frequency.
- Constraint on the allowable phase type based on the pattern of phase and coda detections for local and regional events.
- Constraint on distance to epicenter from the pattern of *P*- and *S*-phases for local and regional events.

When processing the microarrays with the GBF method, we only introduced one single modification to the current operational GBF parameters. This was by adding the possibility of redefining *S*-phases to *P*- phases at ARCESS (see section on the ARCESS microarray). We might as well have tuned the GBF parameters more specifically towards processing microarrays, but as one of our intentions was to check the robustness of the GBF algorithm, we initially avoided such fine tuning.

Reference events

The events declared by the GBF algorithm from processing of the full regional arrays ARCESS, FINESA and NORESS were used as a reference data base for the 12 day period (9-20 April 1992). The GBF output was manually checked for inconsistencies, and false events were removed. This resulted in 428 reference events, and those with magnitude above 1.5 are shown on the map of Fig. 7.5.14. Note the large number of mining explosions on the Kola peninsula and in Estonia. The magnitudes M_L were computed using the formula of Båth (1981), and in the cases where several arrays detected *S*-phases, the magnitudes were averaged.

The reference locations should be used with caution, as the event waveforms have not been interactively analyzed.

Event detectability

As a definition of a reference event found by GBF processing of the microarray network we have used the following criterion:

If the difference in event location is less than 400 km and the difference in origin time is less than 120 seconds, the event is declared as detected by the microarray network.

The motivation behind using such wide acceptance limits is that all of these events will be flagged as candidates for subsequent interactive analysis, such that errors in phase association and timing of the detected phases can be corrected by the analyst.

Fig. 7.5.15 illustrates the event detectability as a function of distance to the closest array. Detected events are marked as stars, whereas non-detected events are shown by circles. A total number of 261 events (61%) were found by the microarray network. It is seen that beyond 600 km, no event with magnitude less than 2.0 is detected, whereas just below this distance limit events close to magnitude 1.0 are detected. We will therefore in the following proceed with a detectability study for events within 600 km of the closest array. Having the the map of Fig. 7.5.14 in mind, this constitute a geographical region covering a

triangle with the three microarrays in the corners extended by a circle sector of 600 km radius around each microarray. An area as defined above will also be the typical size of a region of interest for possible future microarrays.

A maximum likelihood estimation of event detectability (Ringdal, 1975) of the region defined above is presented in Fig. 7.5.16. From the number of detections/no detections at each magnitude, the 50% and 90% incremental detection thresholds are inferred. The 90% threshold is about $M_L = 1.8$, whereas the 50% threshold is found to be about $M_L = 0.8$. These numbers are further confirmed by comparing with the seismic bulletin of the University of Helsinki, Finland.

For an event to be defined by the GBF algorithm, a minimum of two defining phases are required. This might be, for example, a *P* and an *S* at one array or two *P*-phases at two arrays. In the previous section discussing the performance of each microarray, we found that a significant number of seismic phases were discarded from GBF processing due to erroneous estimates of apparent velocity and azimuth. In such cases where the azimuth or apparent velocity estimates fall outside the allowable range for GBF processing, it will often happen that a coda detection is used as a defining phase. This exploitation of redundant detections is one of the strong features of the GBF algorithm leading to the good event detectability of the microarray network, although the phase associations and the corresponding event location will not always be perfect.

Location differences

For 249 microarray events located within 600 km of the closest array, a histogram of the location difference between the microarray network and the full array network is given in Fig. 7.5.17. The median difference of the population is 47.4 km. The causes of the location differences can be divided into three types:

1. Differences in estimates of phase arrival times.
2. Use of coda phases as defining phases.
3. Occasionally, erroneous phase association.

Type 1 and 2 will in most cases result in minor to modest location differences, whereas type 3 often will cause large deviations.

By dividing the population into events with the same number of associated phases (microarray network), we obtain the distribution of Table 5. It is seen that the differences are generally reduced when the number of associated phases increase. This is due to the fact that the likelihood of erroneous phase association (type 3) is reduced when the number of associated phases increase.

False events

In practical operation of any phase association and event location algorithm, it is essential that the number of false events is kept at a moderate level. Our experience with the GBF algorithm applied to the full array network is that the number of false events is rather low.

A false alarm rate of 26% is found for the automatic GBF algorithm applied to the microarray network (see Table 7.5.6), which is a number that does not present a problem in an analyst review situation. No event with more than 3 associated phases (irrespective of number of arrays) were false (see Table 7.5.7), and the vast majority of the false events were one-array events with two defining phases (a *P* and an *S*-phase). From Table 7.5.8 it is clearly seen that most of the false 1-array events were found at the FINESA array. This is in accordance with our finding that the FINESA microarray had the lowest success rate in classifying *P* and *S*- phases from apparent velocity estimates.

Summary

It has been demonstrated that information derived from a sparse network of seismic microarrays (interstation distance ~ 1000 km) permits successful automatic phase association and regional event location using the GBF algorithm. The apparent velocity and azimuth estimates of the detected phases found by f-k analysis of the 4 vertical-component sensors of each microarray place strong constraints on the use of the detected phases. This enables subsequent GBF processing of the detection data to be performed with good event detectability combined with a low number of false events.

Although the initial phase identification based on the apparent velocity estimates from time to time resulted in mis-classification of the phases, the robustness of the GBF algorithm prevented events from being missed. The robustness was also accentuated by the fact that except for one change, the microarray network could be processed with the same parameter settings as the full array network.

For 249 events located within 600 km of the closest array, the median difference between automatic locations by the full array network and by the microarray network was only 47.4 km.

Information from the three-component sensors of the microarrays has not been used in this study, but the work of Suteau-Henson (1991) and Riviere-Barbier et al. (1992), indicate that further improvements in event detectability, correctness of phase association and consequently in event location can be achieved if this information is utilized.

Out of the 353 events formed after automatic GBF processing of the microarray network, only 92 (26%) were found to be false, a number that is easily handled in an analyst review situation. All events with 4 or more defining phases were real. The vast majority of the false events were associated with detections at the FINESA array.

In order to handle the large data volumes produced by modern digital seismic networks, a high degree of automated processing is essential. We have in this work shown that in Fennoscandia a sparse network of microarrays allows for such automated processing. Very little data collection and data analysis needs to be done to tune the parameters for the

algorithms for automatic phase association and event location. The Fennoscandian Shield constitutes a rather simple and homogeneous geological province, and it would therefore be of interest to investigate microarray performances in more complex geological environments.

T. Kværna

References

- Bache, T., S. R. Bratt, J. Wang, R.M. Fung, C. Kobryn and J. W. Given (1990), The Intelligent Monitoring System, *Bull. Seism. Soc. Am.*, 80, Part B, 1833-1851.
- Båth, M. (1981): Local magnitude-recent research and current trends, *Earth-Science Rev.*, 17, 315-398.
- Esmersoy, L., V. F. Cormier and M. N. Toksöz (1985). Three component array processing, In The VELA Program, A. U. Kerr, Editor, Defence Advanced Research Projects Agency, Executive Graphics Services.
- Kværna, T. (1990): Sources of short-term fluctuations in the seismic noise level at NOR-ESS, *Phys. Earth. Planet. Inter.*, 63, 269-276.
- Kværna, T. and D.J. Doornbos (1986): An integrated approach to slowness analysis with arrays and three-component stations, *Semiann. Tech. Summary*, 1 October 1985-31 March 1986, NORSAR Sci. Rep. No 2- 85/86, Kjeller, Norway.
- Kværna, T. and F. Ringdal (1992): Integrated array and three-component processing using a seismic microarray, *Bull. Seism. Soc. Am.*, 82, 870-882.
- Ringdal, F. and T. Kværna (1989): A multi-channel processing approach to real-time network detection, phase association, and threshold monitoring, *Bull. Seism. Soc. Am.*, 79, 1927-1940.
- Ringdal, F. (1975): On the estimation of seismic detection thresholds, *Bull. Seism. Soc. Am.*, 65, 1631-1642.
- Riviere-Barbier, F., A. Suteau-Henson, V.Z. Ryaboy and J.A. Carter (1992): Analysis of three-component data from IRIS/IDA stations in USSR, *Bull. Seism. Soc. Am.*, 82, 192-220.
- Suteau-Henson, A. (1991): Three-component analysis of regional phases at NORESS and ARCESS: Polarization and phase identification, *Bull. Seism. Soc. Am.*, 81, 2419-2440.

Correct phase id (full array)	Classified as:		
	P (vel>5.8m/s)	S or Lg (3.2<vel≤5.8 km/s)	Noise (vel≤3.2 km/s)
P (vel>5.8)	343 (22.6%)	118 (7.8%)	58 (3.8%)
S or Lg (3.0<vel≤5.8 km/s)	109 (7.2%)	365 (24.0%)	55 (3.6%)
Noise (vel≤3.0 km/s)	6 (0.4%)	28 (1.8%)	439 (28.9%)

Total number of microarray detections evaluated: 1521

Total number of phases correctly classified: 1147 (75.4%)

Table 7.5.1a. All detections of the ARCESS microarray have been used as the basis for this statistics. The detections are classified based on estimated apparent velocities applying broadband f-k analysis to the vertical components of the microarray and "correct" phase identification is based on f-k results from the full ARCESS array.

Correct phase id	Classified as:		
	P (vel>5.8m/s)	S or Lg (3.2<vel≤5.8 km/s)	Noise (vel≤3.2 km/s)
P (from GBF)	86 (28.4%)	47 (15.5%)	0 (0.0%)
S or Lg (from GBF)	16 (5.3%)	154 (50.8%)	0 (0.0%)
Noise (none)	0 (0.0%)	0 (0.0%)	0 (0.0%)

Total number of phases evaluated: 303

Total number of phases correctly classified: 240 (79.2%)

Table 7.5.1b. In this table we have used the phases (*P*, *S* or *L_g*) verified to be associated with regional events as the "correct" phase identification, and the phases were classified based on estimated apparent velocities applying broadband f-k analysis to the vertical components of the ARCESS microarray.

Correct phase id (full array)	Classified as:		
	P (vel>5.8m/s)	S or Lg (3.2<vel≤5.8 km/s)	Noise (vel≤3.2 km/s)
P (vel>5.8)	385 (31.4%)	70 (5.7%)	42 (3.4%)
S or Lg (3.0<vel≤5.8 km/s)	42 (3.4%)	370 (30.2%)	172 (14.0%)
Noise (vel≤3.0 km/s)	5 (0.4%)	35 (2.9%)	104 (8.5%)

Total number of microarray detections evaluated: 1225

Total number of phases correctly classified: 920 (70.1%)

Table 7.5.2a. All detections of the FINESA microarray have been used as the basis for this statistics. The detections are classified based on estimated apparent velocities applying broadband f-k analysis to the vertical components of the microarray and "correct" phase identification is based on f-k results from the full FINESA array.

Correct phase id	Classified as:		
	P (vel>5.8m/s)	S or Lg (3.2<vel≤5.8 km/s)	Noise (vel≤3.2 km/s)
P (from GBF)	121 (34.1%)	16 (4.5%)	23 (6.5%)
S or Lg (from GBF)	12 (3.4%)	158 (44.5%)	25 (7.0%)
Noise (none)	0 (0.0%)	0 (0.0%)	0 (0.0%)

Total number of phases evaluated: 355

Total number of phases correctly classified: 279 (78.6%)

Table 7.5.2b. In this table we have used the phases (*P*, *S* or *L_g*) verified to be associated with regional events as the "correct" phase identification, and the phases were classified based on estimated apparent velocities applying broadband f-k analysis to the vertical components of the FINESA microarray.

Correct phase id (full array)	Classified as:		
	P (vel>6.0m/s)	S or Lg (3.2<vel≤6.0 km/s)	Noise (vel≤3.2 km/s)
P (vel>6.0)	260 (39.9%)	13 (2.0%)	9 (1.4%)
S or Lg (3.0<vel≤6.0 km/s)	51 (7.8%)	185 (28.4%)	7 (1.1%)
Noise (vel≤3.0 km/s)	12 (1.8%)	58 (8.9%)	57 (8.7%)

Total number of microarray detections evaluated: 652

Total number of phases correctly classified: 502 (77.0%)

Table 7.5.3a. All detections of the NORESS microarray have been used as the basis for this statistics. The detections are classified based on estimated apparent velocities applying broadband f-k analysis to the vertical components of the microarray and "correct" phase identification is based on f-k results from the full NORESS array.

Correct phase id	Classified as:		
	P (vel>6.0m/s)	S or Lg (3.2<vel≤6.0 km/s)	Noise (vel≤3.2 km/s)
P (from GBF)	70 (42.7%)	2 (1.2%)	0 (6.5%)
S or Lg (from GBF)	8 (4.9%)	83 (50.6%)	1 (0.6%)
Noise (none)	0 (0.0%)	0 (0.0%)	0 (0.0%)

Total number of phases evaluated: 164

Total number of phases correctly classified: 153 (93.3%)

Table 7.5.3b. In this table we have used the phases (P , S or L_g) verified to be associated with regional events as the "correct" phase identification, and the phases were classified based on estimated apparent velocities applying broadband f-k analysis to the vertical components of the NORESS microarray.

	ARCESS	FINESA	NORESS
Percentage of correctly classified phases	79.2% (84.8%)	78.6%	93.3%
Median azimuth error for <i>P</i> -phases	10.4°	13.4°	14.0°
Percentage of <i>P</i> -phases within 25°	78.5%	73.0%	86.1%
Median azimuth error for <i>S</i> -phases	6.8°	8.5°	6.5°
Percentage of <i>S</i> -phases within 25°	98.2%	88.0%	94.6%
Percentage of all detections classified as noise	36.3%	26.0%	11.2%
Percentage of verified phases classified as noise	0.0%	13.5%	0.6%

Table 7.5.4. This table contain a summary of the success rates for initial phase identification and the median errors in the azimuth estimates of the three microarrays considered. We have also included the percentage of *P* and *S*-phases with azimuth differences within 25° of the reference azimuth. Note that f-k analysis of the 4 vertical sensors of the microarrays is the only method being used to obtain these results.

	Number of defining phases (microarray network)						
	2	3	4	5	6	7	8
Number of events	144	53	23	14	9	3	3
Median location difference (km)	55.3	47.4	47.3	33.7	45.3	37.6	0.0
Median magnitude M_L	1.17	1.47	2.10	2.33	2.26	2.53	2.50

Table 7.5.5. After dividing the events into classes based on the number of defining phases, we give for each class the number of events, median location difference to the full network location and the median magnitude. Note that the location differences are generally reduced when the number of associated phases increase.

Declared events	Real events	False events
353	261 (74.0%)	92 (26.0%)

Table 7.5.6. Distribution of real and false events for the 353 events declared after GBF processing of the microarray network.

	1 array	2 arrays	3 arrays
2 associated phases	62	18	-
3 associated phases	3	7	2

Table 7.5.7. Distribution of detecting arrays and the number of associated phases for the false events. No events with more than three defining phases were false.

	ARCESS	FINESA	NORESS
	12	45	8

Table 7.5.8. Distribution of detecting arrays for false one-array events.

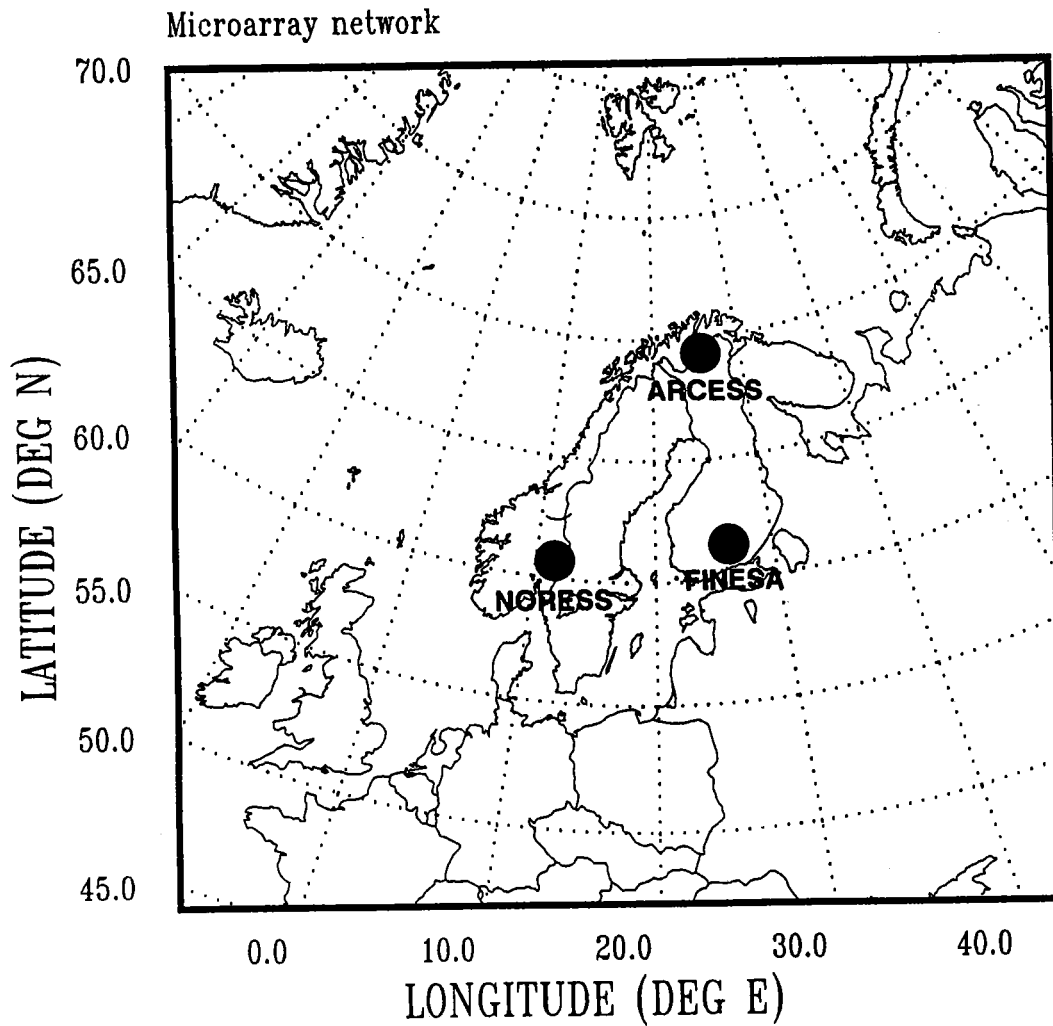


Fig. 7.5.1. Map showing the location of the three Fennoscandian arrays (ARCESS, FINESA and NORESS). The microarray configurations analyzed in this paper are subsets of these arrays.

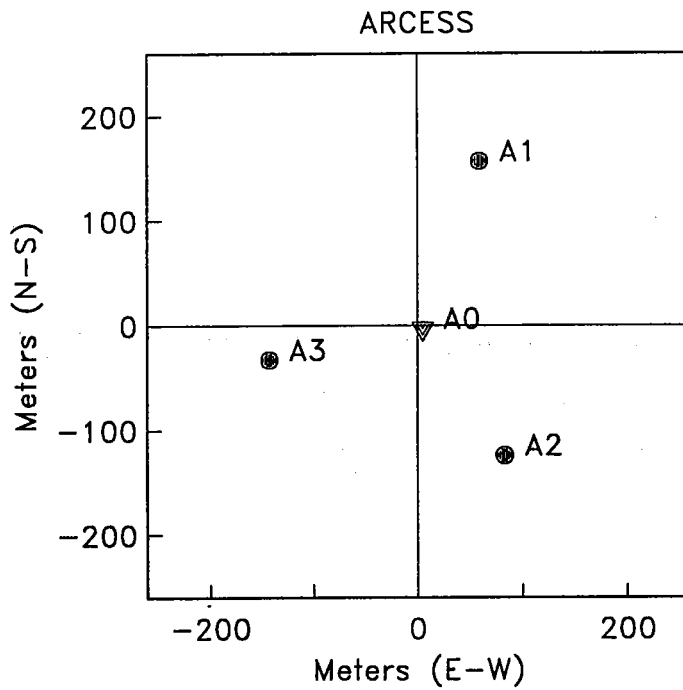


Fig. 7.5.2. This figure gives the locations of the sensors of the ARCESS microarray. The vertical-component sensors are indicated by filled circles, whereas the filled delta symbol represent the 3-component sensor.

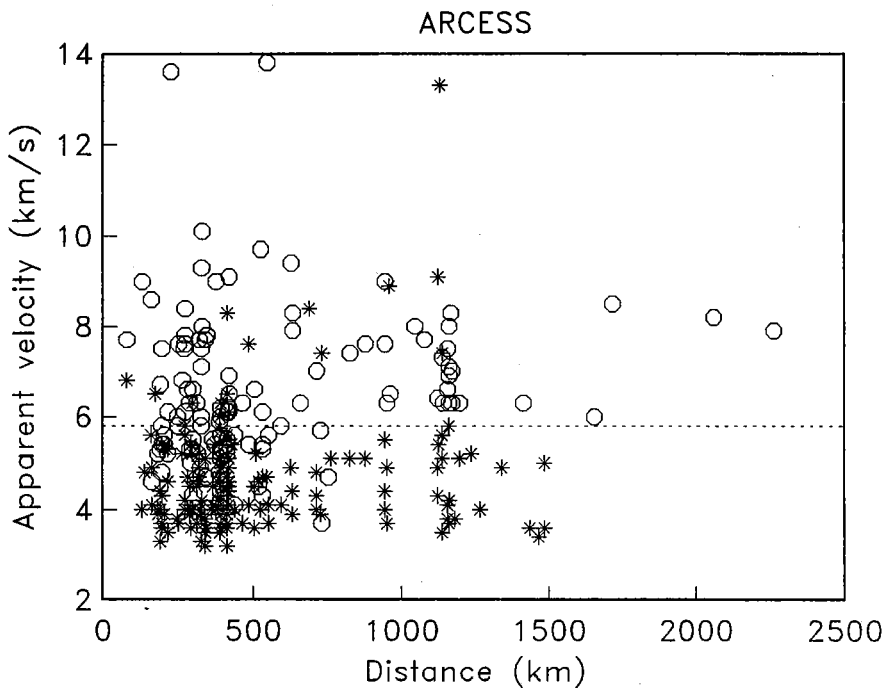


Fig. 7.5.3. Estimated apparent velocities from applying broadband f-k analysis to the vertical components of the ARCESS microarray for P phases (circles) and S phases (asterisks). An apparent velocity of 5.8 km/s (dashed line) has been used to classify the phases as P or S. The success rate is 79.2%.

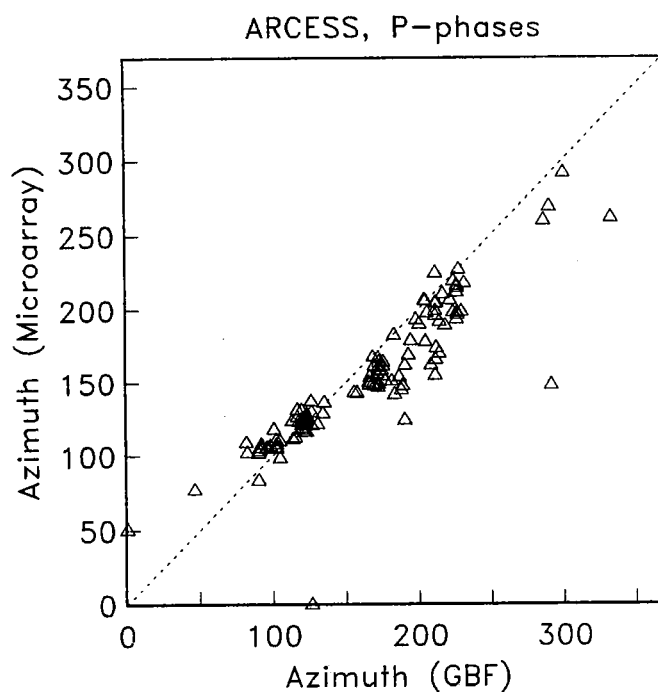


Fig. 7.5.4. Comparison of estimated azimuths of *P* phases using the full ARCESS array and the four vertical components of the ARCESS microarray. The median difference is 10.4° .

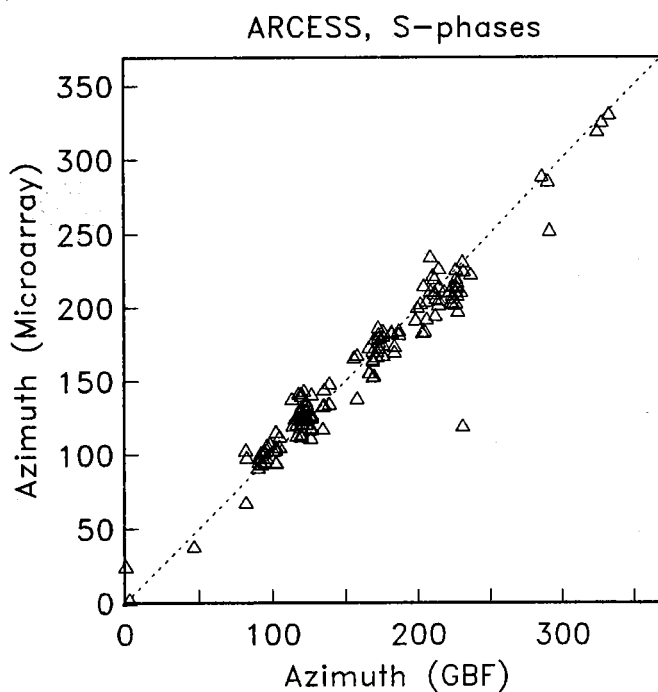


Fig. 7.5.5. Comparison of estimated azimuths of *S* phases using the full ARCESS array and the four vertical components of the ARCESS microarray. The median difference is 6.8° .

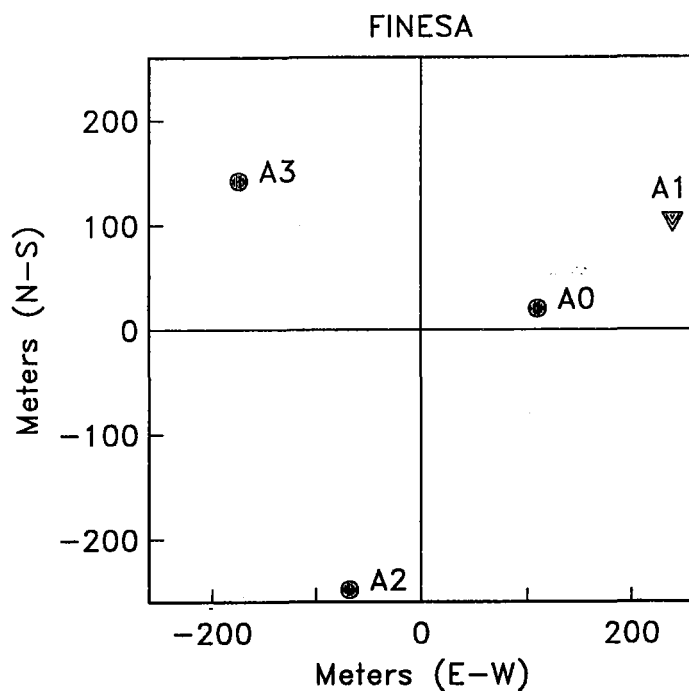


Fig. 7.5.6. This figure gives the locations of the sensors of the FINESA microarray. The vertical-component sensors are indicated by filled circles, whereas the filled delta symbol represent the 3-component sensor.

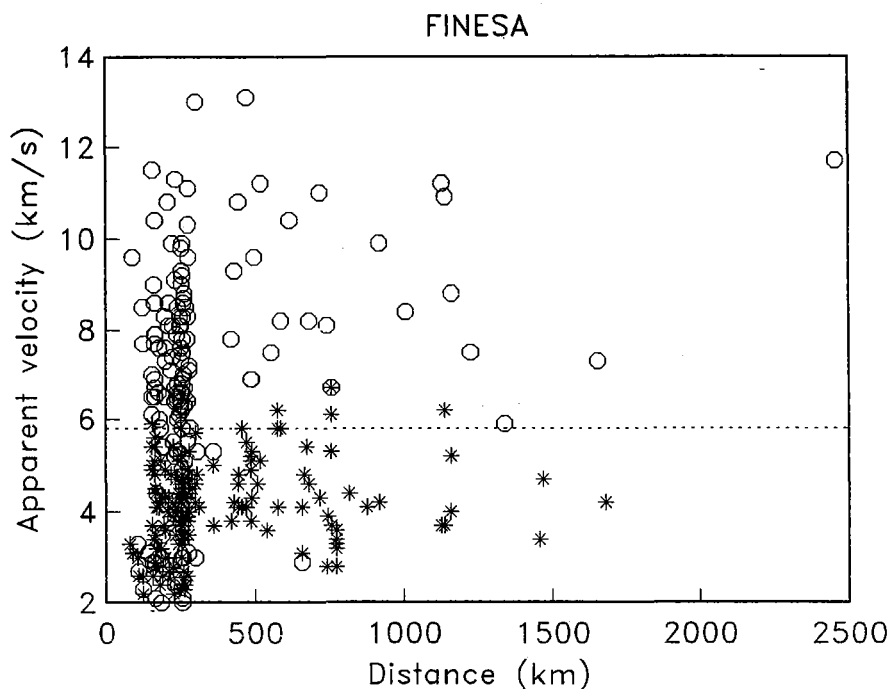


Fig. 7.5.7. Estimated apparent velocities from applying broadband f-k analysis to the vertical components of the FINESA microarray for *P* phases (circles) and *S* phases (asterisks). An apparent velocity of 5.8 km/s (dashed line) has been used to classify the phases as *P* or *S*. The success rate is 78.6%.

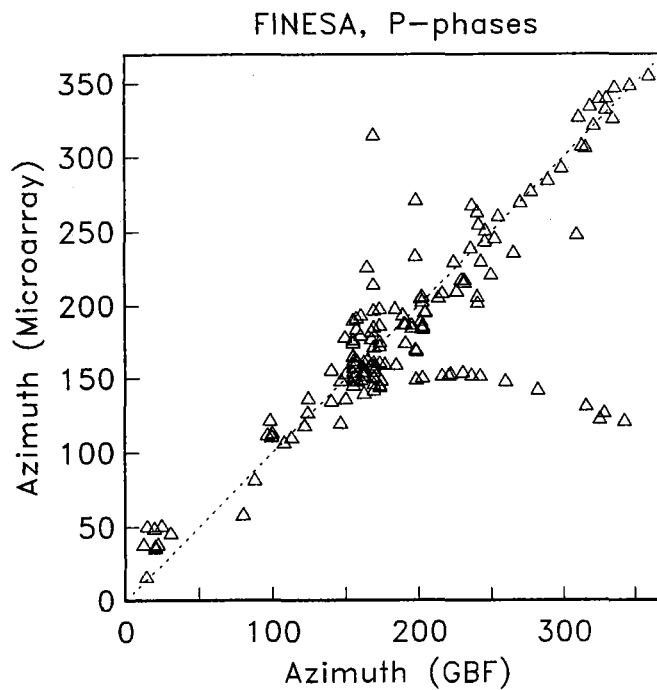


Fig. 7.5.8. Comparison of estimated azimuths of *P* phases using the full FINESA array and the four vertical components of the FINESA microarray. The median difference is 13.4° . Due to the large aperture of the FINESA microarray in comparison with the ARCESS microarray (see Figs. 7.5.2 and 7.5.6) there were some problems with lack of coherency and spatial aliasing at high frequencies. This is the reason for the apparent alignment of *P*-wave azimuth estimates at about 150° .

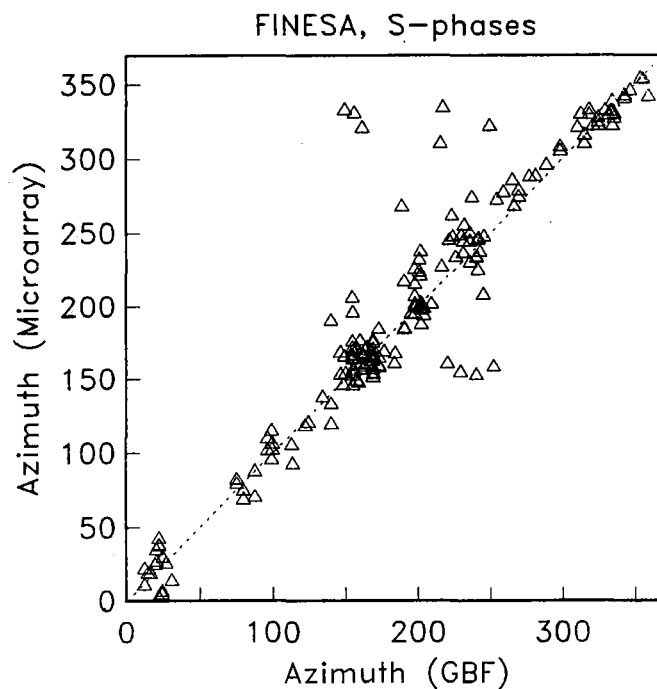


Fig. 7.5.9. Comparison of estimated azimuths of *S* phases using the full FINESA array and the four vertical components of the FINESA microarray. The median difference is 8.5° .

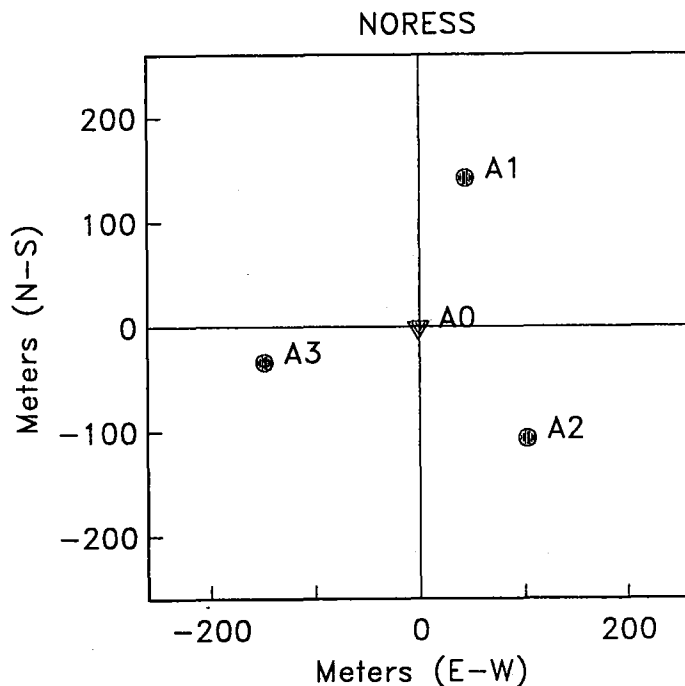


Fig. 7.5.10. This figure gives the locations of the sensors of the NORESS microarray. The vertical-component sensors are indicated by filled circles, whereas the filled delta symbol represent the 3-component sensor.

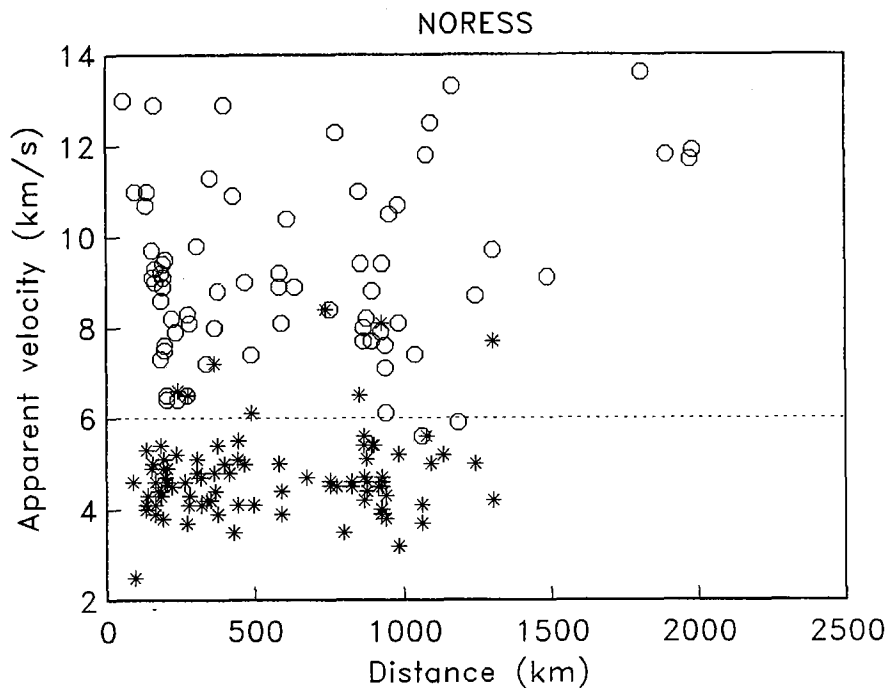


Fig. 7.5.11. Estimated apparent velocities from applying broadband f-k analysis to the vertical components of the NORESS microarray for *P* phases (circles) and *S* phases (asterisks). An apparent velocity of 5.8 km/s (dashed line) has been used to classify the phases as *P* or *S*. The success rate is 93.3%.

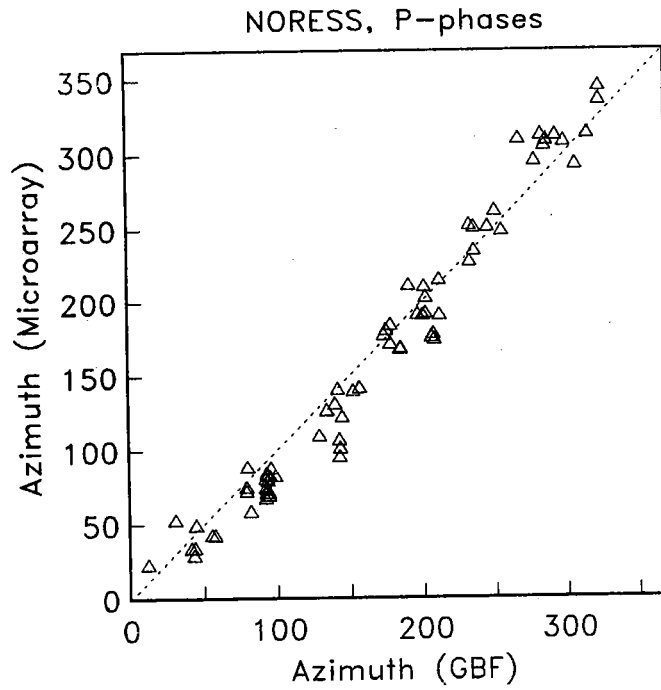


Fig. 7.5.12. Comparison of estimated azimuths of *P* phases using the full NORESS array and the four vertical components of the NORESS microarray. The median difference is 14.0° .

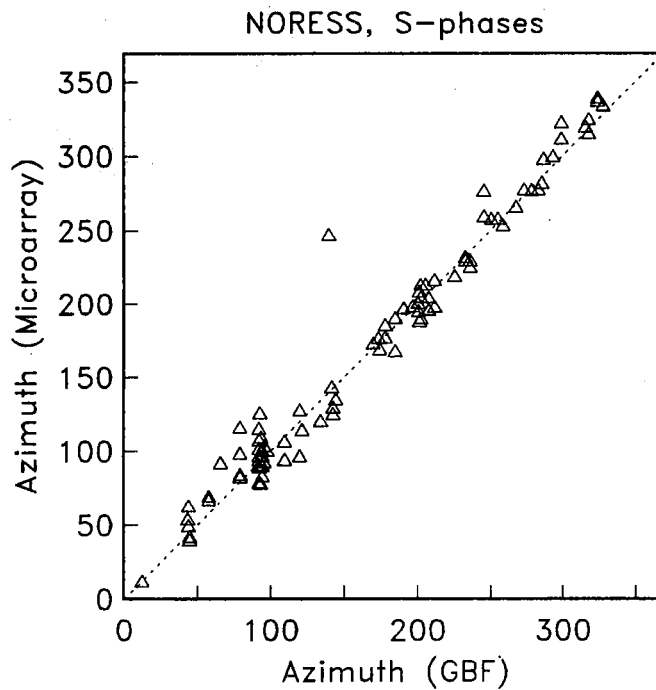


Fig. 7.5.13. Comparison of estimated azimuths of *S* phases using the full NORESS array and the four vertical components of the NORESS microarray. The median difference is 6.5° .

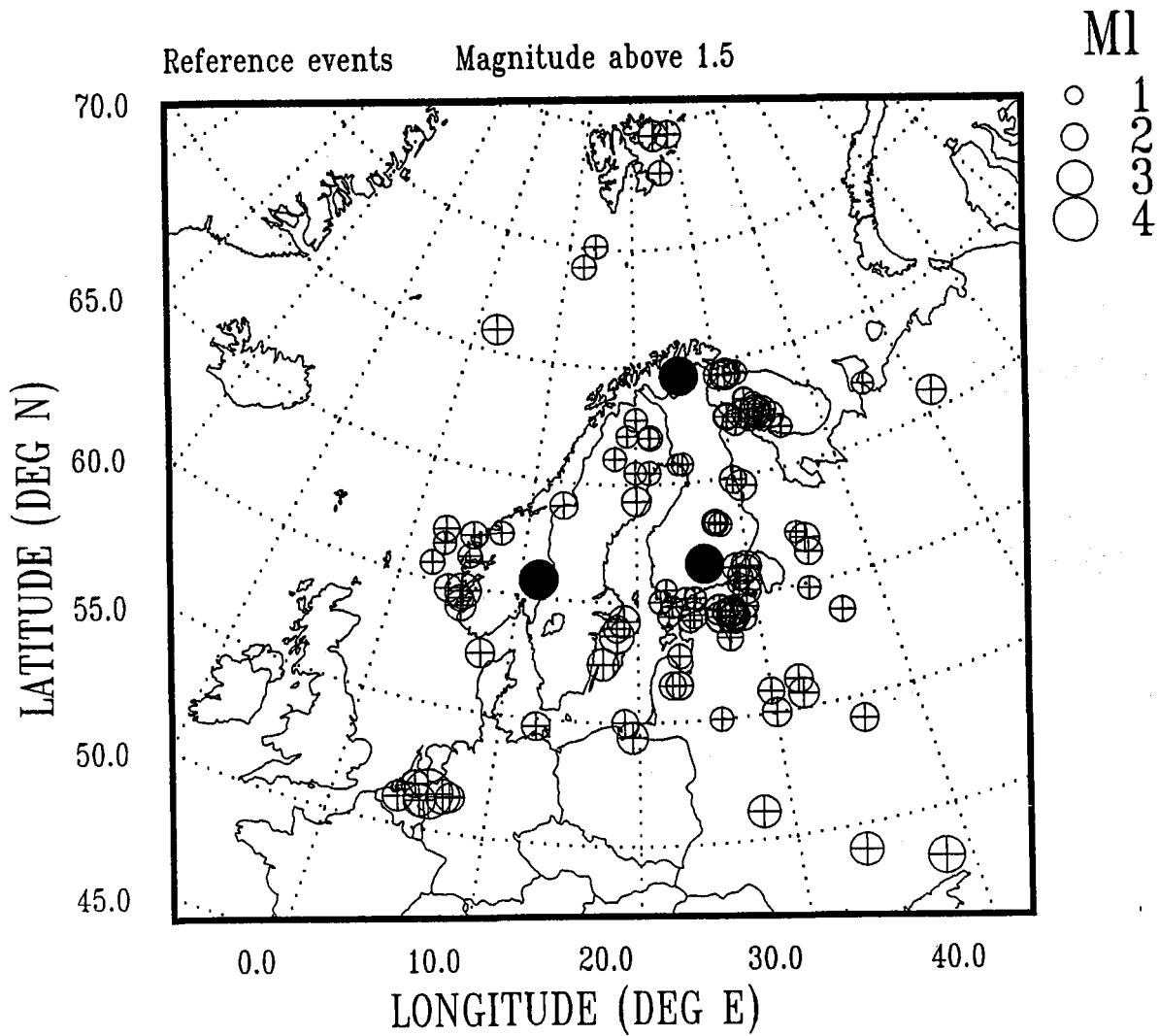


Fig. 7.5.14. Map with reference events with magnitude above 1.5. Note the large number of events (mining explosions) on the Kola peninsula and in Estonia.

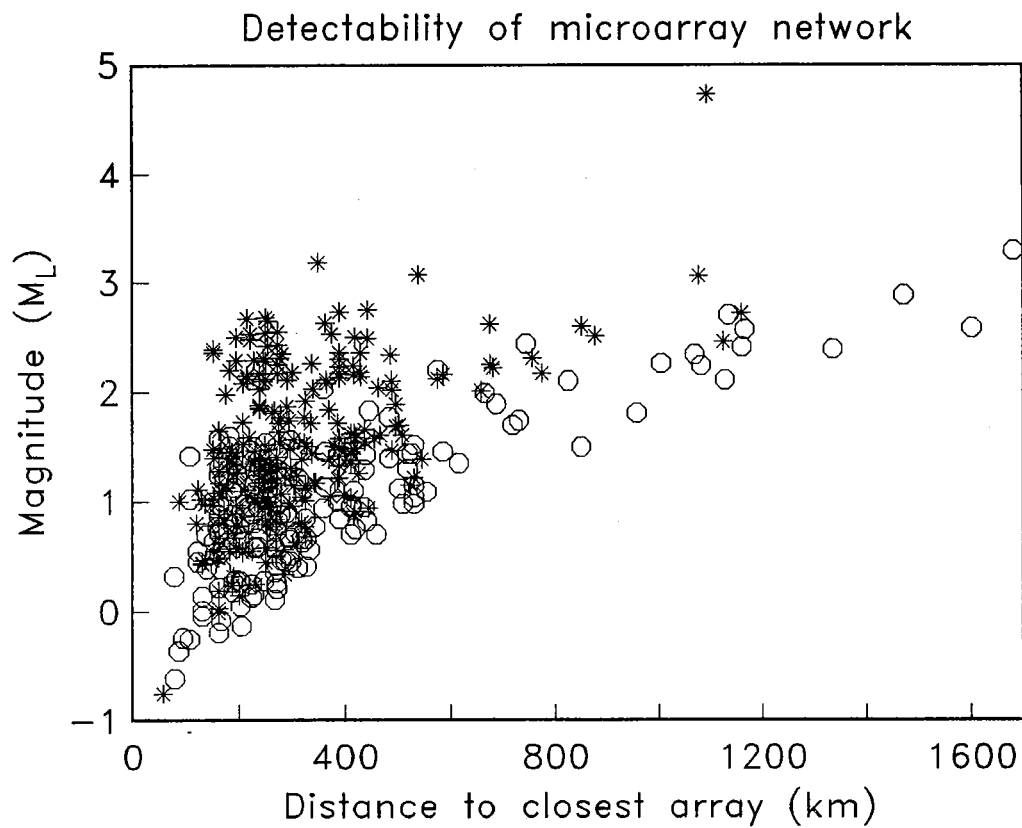


Fig. 7.5.15. Magnitude of reference events versus distance to the closest array. Events found after GBF processing of the microarray network are marked by stars, whereas missed events are marked by circles.

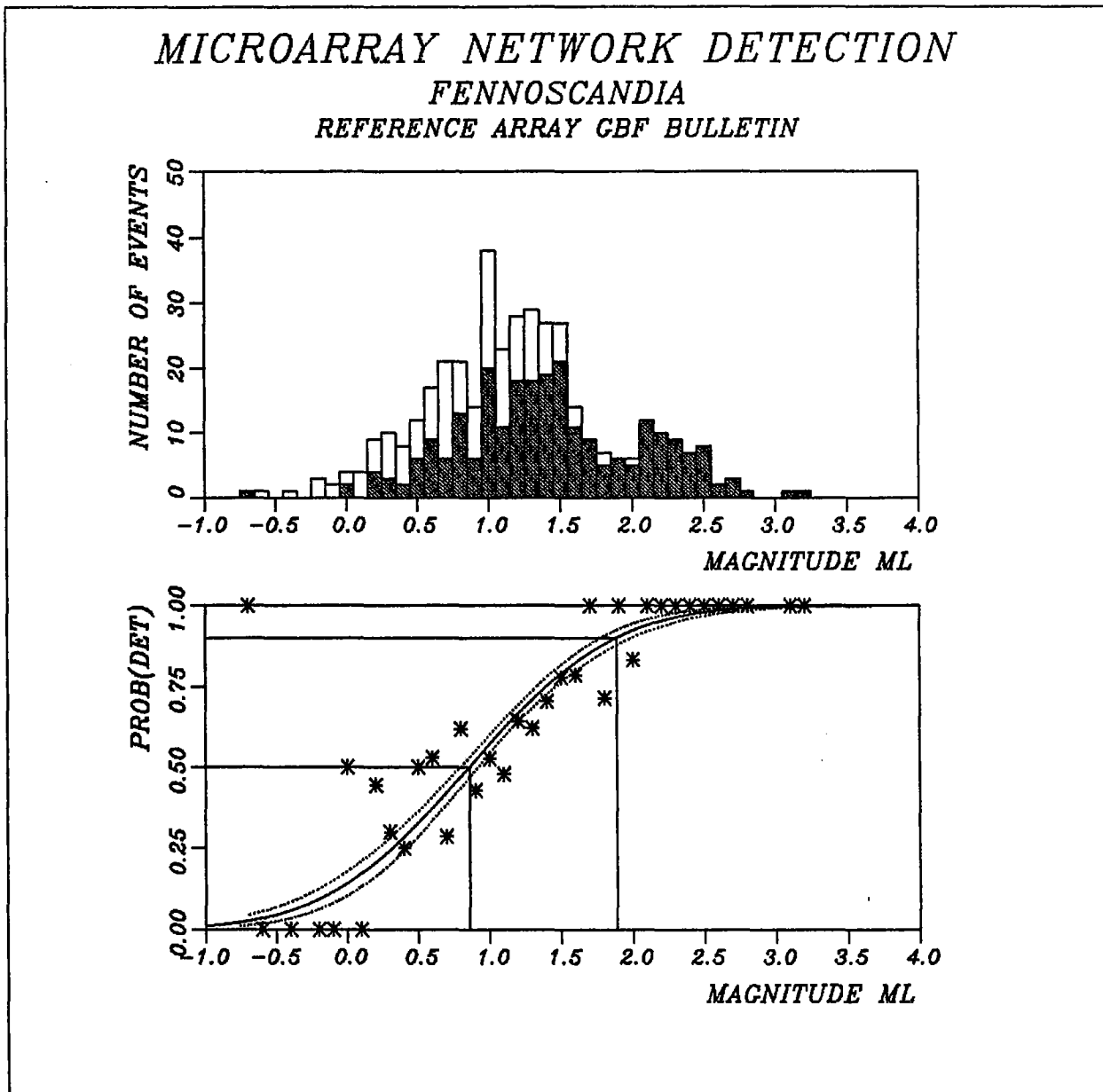


Fig. 7.5.16. Maximum likelihood detectability estimation of the microarray network for Fennoscandia-NW Russia using the GBF bulletin as a reference. The upper half shows the reference set and the number of events found by the microarray network for each magnitude. The lower half shows the maximum likelihood detectability curve and its confidence limits. The actual percentage of detected events at each magnitude is also shown.

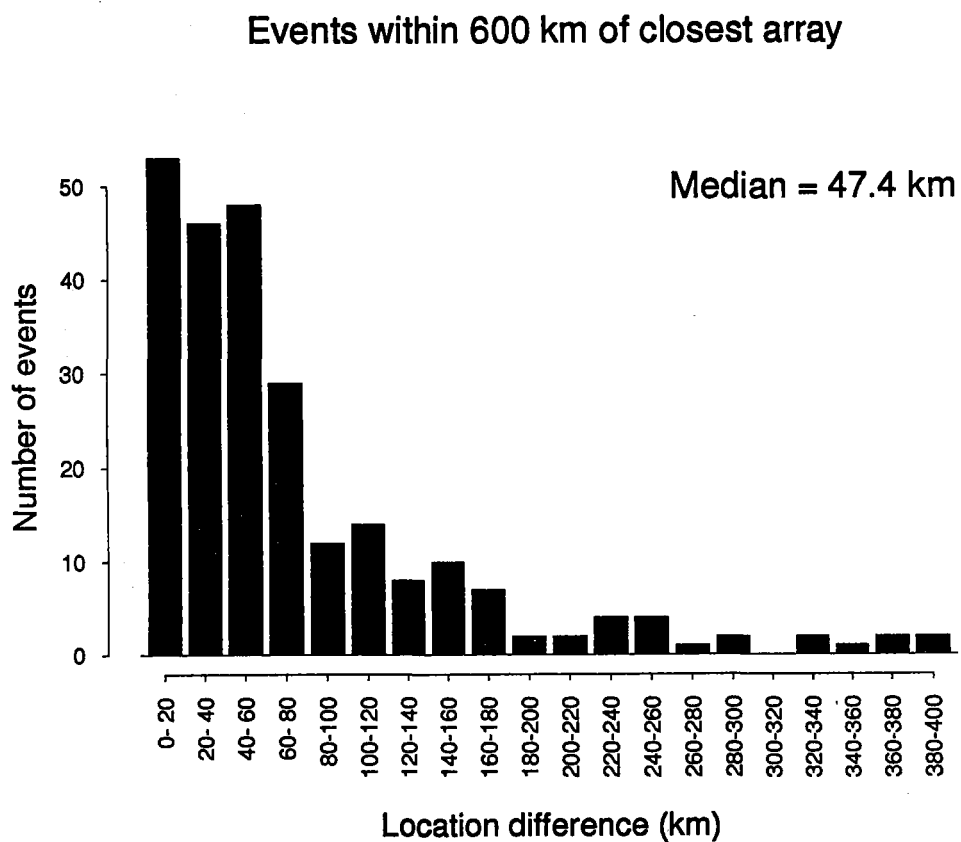


Fig. 7.5.17. This histogram shows the location difference between the microarray network and the full array network for the 249 events located within 600 km of the closest array. The median difference of the population is 47.4 km.

7.6 Distribution in slowness space of regional array detections

One of the main features of advanced regional arrays is their ability to reliably determine the slowness vector of incoming signal energy. This is important for seismic phase identification, and can be used to characterize detected phases as teleseismic P or PKP, regional P, S, Lg or Rg (Mykkeltveit et al. 1990). As shown, e.g., by Kvaerna (1990), this ability can also be used to identify the origin of various seismic noise sources, many of which show very consistent azimuth, frequency and velocity characteristics.

This report summarizes statistics on the number of detections versus apparent slowness vector for the four regional arrays NORESS, ARCESS, GERESS and FINESA. In a series of 3-D plots, we display all of the detections reported by each individual array for the six-month period October 91 - March 92. We also show a figure with the slowness distribution for those detections that have been associated to an event in the IMS analysis.

Figs. 7.6.1 - 7.6.4 show number of detections versus slowness for each of the arrays. The slowness space corresponds to the same grid of 51 by 51 points used in the on-line broadband *fk*-analysis. The slownesses range from -0.4 to 0.4 s/km. This corresponds to apparent velocities ranging from 1.78 km/s to infinity.

The X-axis (left-right) corresponds to eastward direction. The Y-axis (front-back) correspond to northward direction. Each figure is separated into two parts. The upper part shows detections with estimated signal frequency below 6.0 Hz. The lower part shows detections with estimated signal frequency above 6.0 Hz.

Fig. 7.6.1 shows NORESS detections. There are dominant peaks in the center for high velocities and a ridge towards east-north for velocities around 3.0 km/s. The 3.0 km/s peaks have been documented as seismic Rayleigh waves from an industrial area and from the large river Glomma running north-south about 20 km east of NORESS (Kvaerna, 1990).

Fig. 7.6.2 shows ARCESS detections. Dominant peaks are found corresponding to P and S velocities from the Kola mines (azimuth 100-130 degrees). A large number of detections with direction from north and velocities around 6.0 km/sec have not been identified. The high frequency detections towards west may be noise from a main road passing the west side of the array.

Note that when the source is very close, or within the array, the slowness estimate may be wrong. See also section 7.9 for a report on correlation between number of detections and temperature fall (ice cracks) in the ARCESS array.

Fig. 7.6.3 shows FINESA detections. Dominant peaks are found corresponding to P, Lg and Rg velocities from the mines in Estonia. In addition, there is a large number of very low velocity detections from the north. The origin of these detections is unknown.

Fig. 7.6.4 shows GERESS detections. Here, the low frequency detections are concentrated to relatively high apparent velocities. The high frequency detections are spread well out in slowness space, but a typical ring of Pn velocities can be identified.

When evaluating the statistics given above, it must be taken into account that the f-k analysis can fail to give the correct estimate in some cases. From our experience, this can happen in particular if the signal frequency is high, or if the noise source is located within or very close to an array. Data spikes or segments of bad data quality may of course also produce erroneous results.

In sections 3.5 and 3.6 of this Semiannual report, we noted that the percentage of detections associated to events by either the Intelligent Monitoring System (IMS) or the Generalized Beamforming process (GBF) was in the range 11 to 20%. These low figures are obviously due to the fact that most of the detections have slowness estimates outside the range permitting the detections to be attributed to seismic phases such as Pn or Lg. A natural question is whether these phases actually belong to seismic events, and this may be answered by investigating the results of analyst review of the regional array bulletins.

Fig. 7.6.5 shows the number of detections versus slowness for phases automatically associated to events by IMS (upper part) and estimated slowness for phases accepted or associated by analyst (lower part). (Note that vertical scale is now 500 as opposed to 1000 for Figs. 7.6.1-7.6.4). These figures include detections for all of the four arrays. Detections should normally correspond to certain "seismic" slownesses, since the slowness parameter is used for event association rules. But in the lower figure, the analyst has all detections available regardless of slowness. A seismic phase may be associated and slowness overruled to include the arrival time as a defining parameter for the event solution.

We note from the lower figure that the number of very slow phases is about the same as in the upper figure. This indicates that the estimated slowness parameter is mostly consistent with the solution as accepted by the analyst.

J. Fyen

References

- Kvaerna, T. (1990): Sources of short-term fluctuations in the seismic noise level at NOR-ESS), *Phys. Earth Planet. Int.*, 63, 269-276,
- Mykkeltveit, S., F. Ringdal, T. Kværna & R.W. Alewine (1990): Application of regional arrays in seismic verification, *Bull. Seism. Soc. Am.*, special issue, 80, 1777-1800.

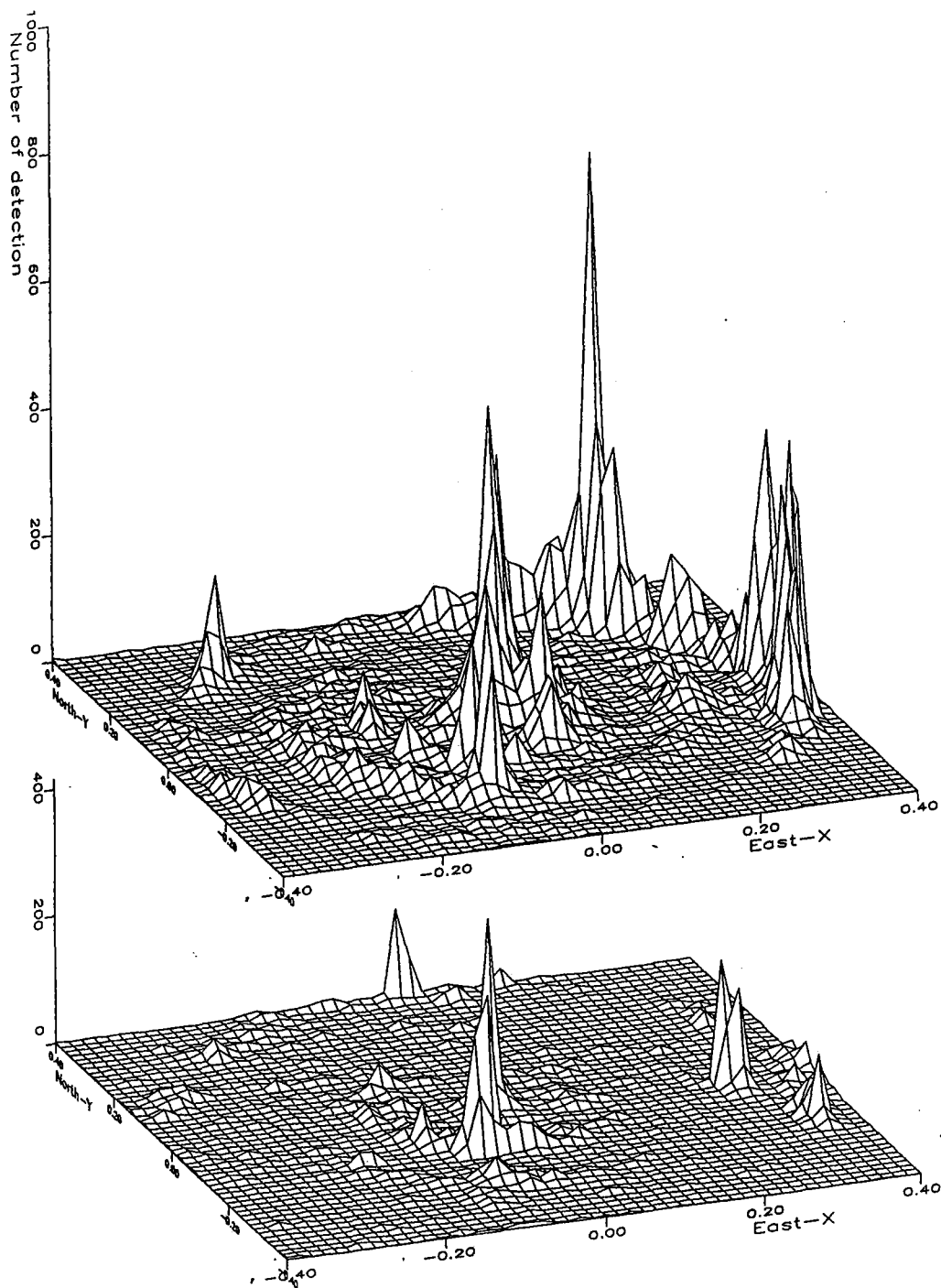


Fig. 7.6.1. Number of NORESS detections versus apparent slowness vector for the 6-month period October 1991 - March 1992. The X-axis (left-right) corresponds to eastward direction with 51 slowness points ranging from -0.4 to 0.4 sec/km. The Y-axis (front-back) correspond to northward direction with 51 slowness points ranging from -0.4 to 0.4 sec/km. The upper part shows detections with estimated signal frequency below 6.0 hz. The lower part shows detections with estimated signal frequency above 6.0 hz.

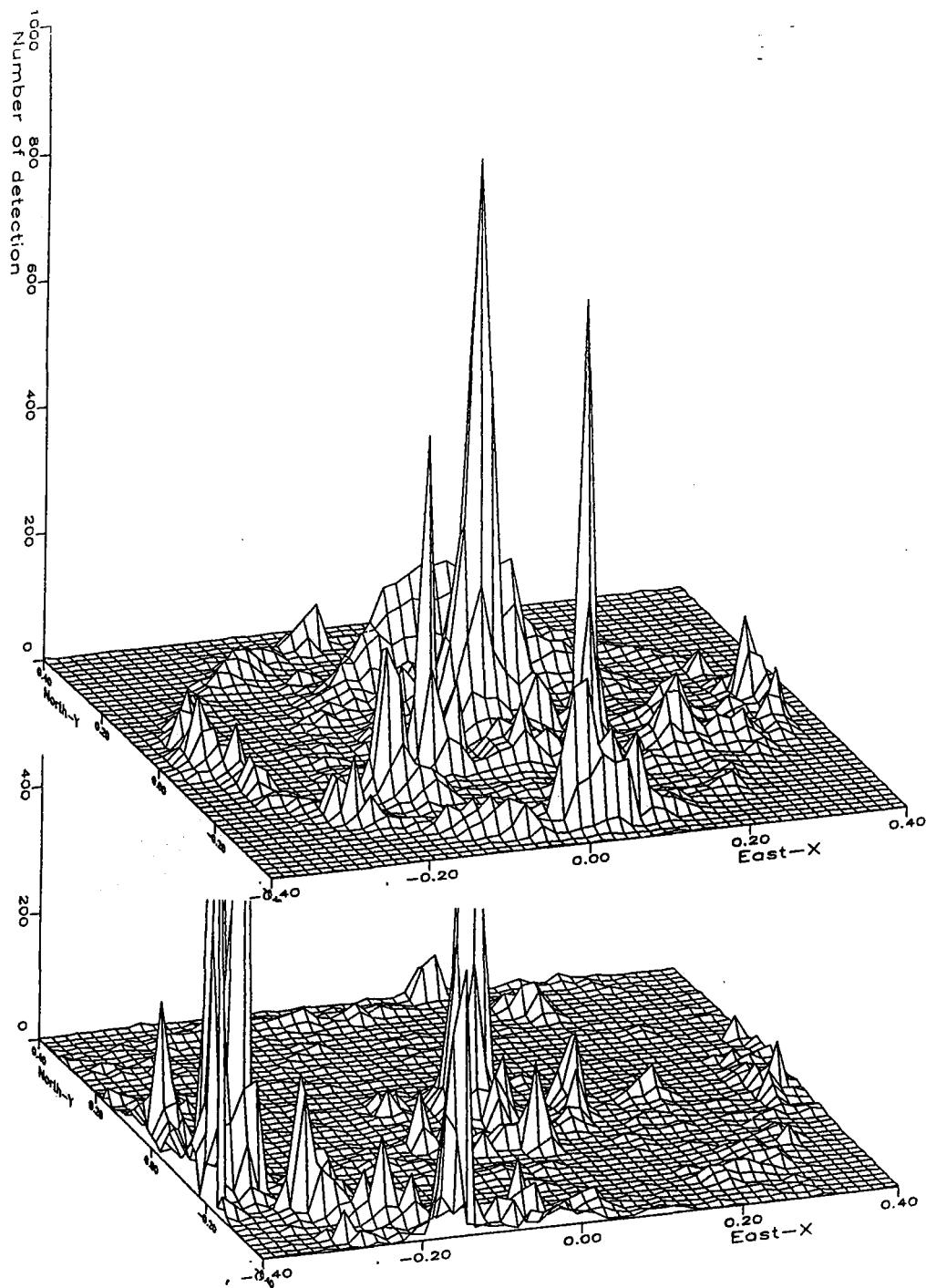


Fig. 7.6.2. Number of ARCESS detections versus apparent slowness vector for the 6-month period October 1991 - March 1992. The X-axis (left-right) corresponds to eastward direction with 51 slowness points ranging from -0.4 to 0.4 sec/km. The Y-axis (front-back) correspond to northward direction with 51 slowness points ranging from -0.4 to 0.4 sec/km. The upper part shows detections with estimated signal frequency below 6.0 hz. The lower part shows detections with estimated signal frequency above 6.0 hz. The lower figure has been clipped.

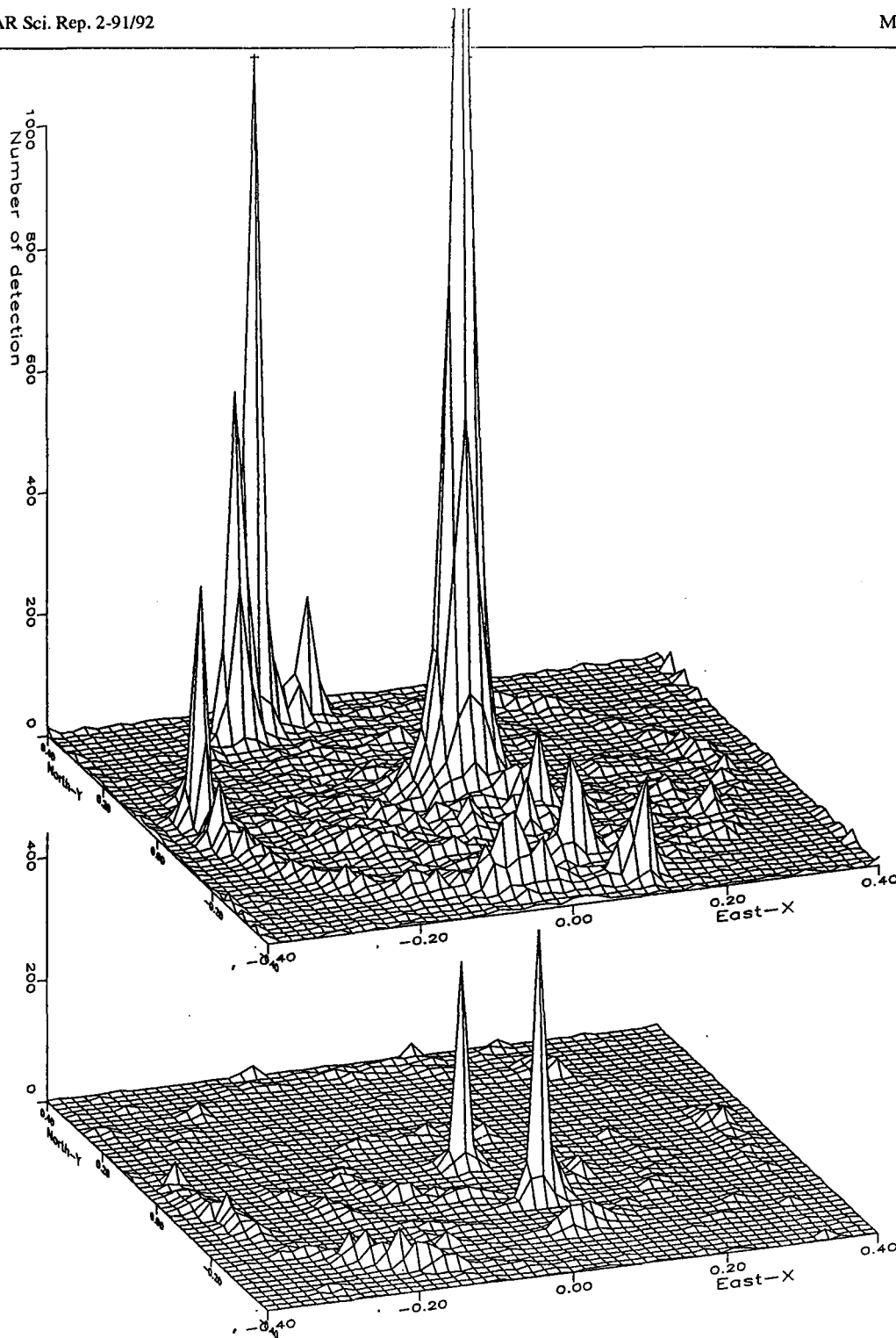


Fig. 7.6.3. Number of FINESA detections versus apparent slowness vector for the 6-month period October 1991 - March 1992. The X-axis (left-right) corresponds to eastward direction with 51 slowness points ranging from -0.4 to 0.4 sec/km. The Y-axis (front-back) correspond to northward direction with 51 slowness points ranging from -0.4 to 0.4 sec/km. The upper part shows detections with estimated signal frequency below 6.0 hz. The lower part shows detections with estimated signal frequency above 6.0 hz.

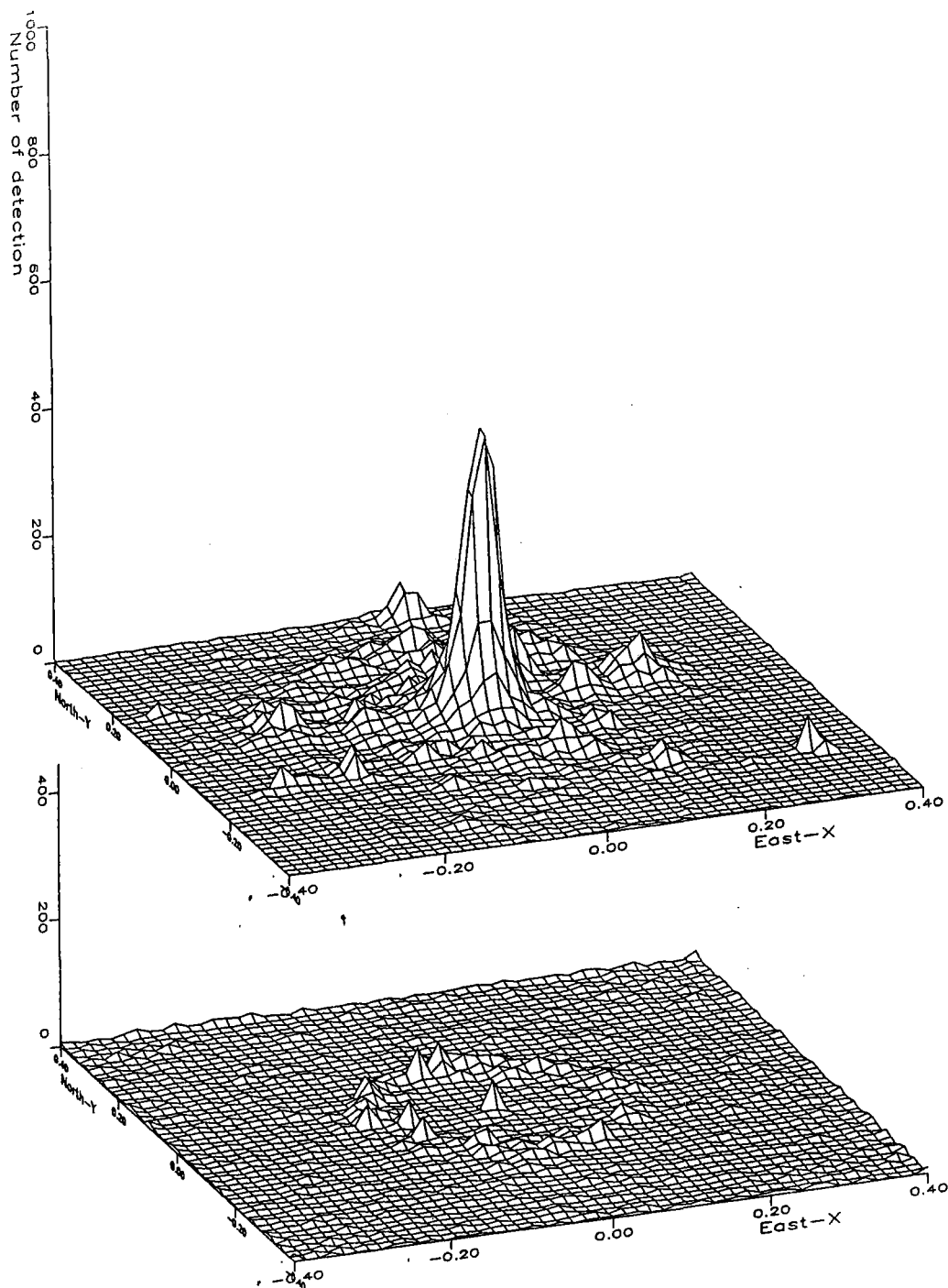


Fig. 7.6.4. Number of GERESS detections versus apparent slowness vector for the 6-month period October 1991 - March 1992. The X-axis (left-right) corresponds to eastward direction with 51 slowness points ranging from -0.4 to 0.4 sec/km. The Y-axis (front-back) correspond to northward direction with 51 slowness points ranging from -0.4 to 0.4 sec/km. The upper part shows detections with estimated signal frequency below 6.0 hz. The lower part shows detections with estimated signal frequency above 6.0 hz.

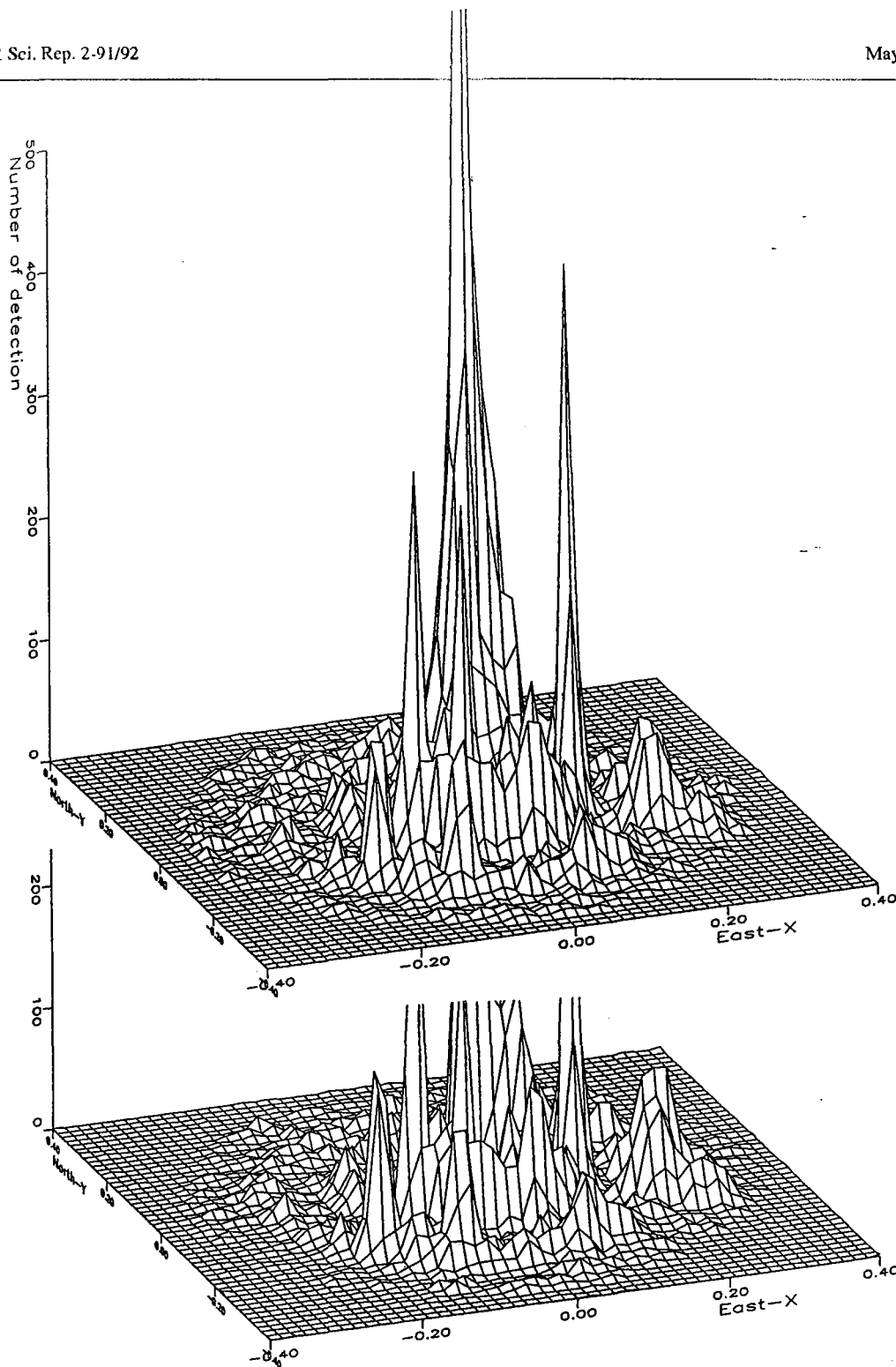


Fig. 7.6.5. The upper part shows number of detections versus apparent slowness vector for the 6-month period October 1991 - March 1992, for detections automatically associated to events by IMS. (All arrays). The X-axis (left-right) corresponds to eastward direction with 51 slowness points ranging from -0.4 to 0.4 sec/km. The Y-axis (front-back) correspond to northward direction with 51 slowness points ranging from -0.4 to 0.4 sec/km. The lower part shows number of detections associated to events that was accepted by analyst review.

7.7 NORAC: A new array controller

Introduction

NORSAR personnel have long experience in operating and maintaining arrays and other types of seismic stations, and have over the years also actively participated in array installation work jointly with other organizations. A typical such deployment comprises co-located sensors and digitizers, transmission of data to a central site within the array, and an array controller that performs synchronization, time tagging and transfer of data to a remote data processing facility. Work at NORSAR has traditionally concentrated on development of software for acquisition and processing of data, rather than development of equipment for the field installation. An exception here is the array controller at the FINESA array site, which was largely designed and developed by NORSAR personnel.

We embarked during the spring of 1991 on a new in-house development project aimed at designing a general-purpose array controller that would accept data from various vendors of digitizers, and prototyping of such a unit, named NORAC (NORSAR ARray Controller), started during the summer of 1991. The main design idea has been to develop a simple unit that can handle input data from many digitizers. Data processing options and graphics displays would not be part of the array controller design, as these functions can more easily be performed by a Unix workstation on site or at a remote data center. A prototype unit was installed in December 1991 at the NORESS array site and acquired data from one instrument for a period of two months, with real time data transmission to Kjeller. The synchronization and time tagging functions of NORAC have also been tested successfully.

Our current plan is to consider the NORAC unit for use in three different projects now underway, namely, the new high-frequency arrays in Apatity, Russia, and on Spitsbergen, and the NORSAR refurbishment. The exact configuration for these three systems will be different, and the flexibility of NORAC in allowing for different types of communication and also different systems for reception of timing signals is essential.

The following paragraphs offer descriptions of NORAC design requirements, NORAC hardware configuration, NORAC software configuration and a description of how NORAC interfaces to Sun workstations.

NORAC design requirements

At the outset of this development project, the following design requirements were specified for the NORAC unit:

- drivers to different manufacturers of digitizers
- timing of data in the field and support for different clocks such as GPS, Omega and radio clocks
- synchronization of several digitizers from external clock source
- standardized hardware from a vendor represented in several countries
- integration with local or remotely located Unix-based computers

-
- flexible configurations ranging from 3-component stations to arrays
 - option for local recording and archiving of data
 - configurable in the field
 - communication with remote computer using either asynchronous communication, synchronized communication (SDLC) or Ethernet (TCP protocol and sockets)
 - watchdog for automatic restart
 - all programs in EPROM/PROM
 - should be capable of handling data from up to 32 digitizers

These requirements were largely based on our experience with array controllers at NORSAR, NORESS, ARCESS, FINESA and GERESS.

NORAC hardware configuration

The NORAC unit is based on Motorola VME boards. All boards are standard boards that may be acquired from any Motorola distributor. This subsection describes the different boards and their function in the NORAC unit. The NORAC unit is composed of the following boards:

- Collection board
- Communication board
- Digitizer interface board
- Clock interface board

A system may comprise 1 to 4 boards, depending on the configuration.

Collection board

This board is the main board of the NORAC system. The collection board hosts all programs in EPROM/PROM and typically has 4Mb of memory on board. The configuration of NORAC is stored in BBRAM (Battery Backup RAM) on the collection board. The following functions may be performed by this board:

- time stamp data from digitizers
- synchronize data from different digitizers
- collect statistics
- record data on locally attached disk
- transmit data to a computer using asynchronous protocol
- transmit data to a computer using Ethernet and socket communication
- archive data on tape and disk
- input of timing information using the asynchronous port

A minimum configuration can run on the collection board only. This configuration will contain 1 or 2 digitizers, external time received on the RS232 port and asynchronous communication or Ethernet communication to a local or remote host.

Digitizer interface board

The digitizer interface board has 8 ports for digitizers, its own buffer and CPU. Each port is asynchronous and can run at a speed of 38.4 Kbits/s at the maximum. A NORAC unit may contain as many as 4 digitizer interface boards, thus allowing up to 32 digitizers total.

Communication board

This board is used for performing the SDLC communication. The transmission speed is controlled by the external modem. The board has been tested at speeds from 2.4 to 64 Kbits/s. Data can optionally be compressed.

Clock interface board

We have implemented several options for timing of the data stream. Time information can be retrieved through a special board or from an asynchronous port. The following are the different timing options:

- an ASCII-coded data stream received once a second
- a BCD-formatted word received on a parallel interface
- timing information received directly from the VME bus

There are several different types of clocks (e.g., GPS, Omega and radio based) that deliver time information in one of the three different ways mentioned above.

A system based on an ASCII-coded data stream does not need a special clock board. This time information is read from the collection board as mentioned above.

The BCD-formatted stream on a parallel interface requires a digital input board in the NORAC unit. There are drivers for both Data Translation DT1417 and Acromag avme9460.

We have developed a driver for a VME clock board from Bancom. This board is based on the GPS system.

NORAC software configuration

The NORAC software is designed as a modular system where each task has a dedicated function. All programs are written in C and use functions from SVIDlib. SVIDlib is available through the VMEexec development environment offered by Motorola. All programming (including compiling and loading) is done on a Unix computer running Unix System V. The final system is burned into EPROMs. The following is a list of tasks running on NORAC:

- collect
- todisk
- tosdlc
- toasync
- toether
- fromport
- status

Collect task

Collect is the main task in NORAC. This task synchronizes all other tasks and formats one-second data blocks from all digitizers. Collect updates several statistics and creates all queues used in the system. Tasks such as todisk, tosdlc, toasync and toether retrieve data from a structure in the collect task. Tasks that need statistical information retrieve this from a structure in the collect task.

Todisk task

Todisk writes data onto a local disk loop using the FFS (Fast File System). Todisk can also write data directly on a Unix file system if a Unix CPU is configured into the same system.

Tosdlc task

Tosdlc transmits data on a synchronous communication port using the SDLC protocol. Tosdlc has an option for data compression.

Toasync task

This task uses an asynchronous port for transmitting data. The maximum speed on the asynchronous port is 38.4 Kbits/s. Data can optionally be compressed.

Toether task

This task uses the Ethernet as the communication medium. Sockets are used for establishing a connection between the toether task in NORAC and a task in another computer on the network. The protocol used is TCP/IP for which most Unix computers have support.

Fromport task

Fromport is the controlling task for all ports connected to external digitizers. Fromport has one subroutine for each type of digitizer connected to the system. The following are the digitizers currently supported:

- RD3 from Nanometrics
- RDAS-300P from Teledyne Geotech

- 72A series from Refraction Technology, Inc.

Fromport creates one task for each port with a digitizer connected. Each task is responsible for one digitizer at one specific port. Each task time stamps data from that digitizer as soon as data are received, and transmits data to the collection task which synchronizes data from all ports together in a one-second block.

Other digitizers can easily be interfaced to the system. The only work that needs to be done is writing a subroutine specific for that digitizer in the fromport program. Collect knows from the parameter area in BBRAM what type of digitizer is connected to each port.

Status task

The main function for status is to display statistics, transmit commands to digitizers and configure NORAC. There are also some diagnostic commands available in status. Status is operated from the asynchronous console port on the collect board.

Interfacing to Sun workstations

We have developed all necessary software for interfacing data from the NORAC unit. Data may be received in three ways:

- as an asynchronous data stream. This is not recommended for systems with more than 4 channels
- as a synchronized data stream using the SDLC protocol. An SBUS SDLC board is used as the hardware interface in the Sun workstation.
- as packets on the Ethernet. The Sun workstation is on the same LAN/WAN.

We have developed drivers to all data streams mentioned above. Data are written onto a circular disk loop and archived on Exabyte cassettes. Both the acquisition software and the archiving software are the same as NORSAR is using today for recording and archiving of all existing array data.

R. Paulsen

7.8 Continuous seismic threshold monitoring of the northern Novaya Zemlya test site; long-term operational characteristics

Introduction

This paper is a summary of a comprehensive report (Kværna, 1992) giving a detailed analysis of the performance of the continuous threshold monitoring technique applied to the northern Novaya Zemlya test site for a full one-month period.

The theoretical background for and applications of the continuous seismic threshold monitoring method (CSTM) have been described in several articles. The approach was introduced by Ringdal and Kværna (1989), who showed that by continuously monitoring the seismic amplitude level at several seismic stations or arrays, one can at any time obtain an instant network-based magnitude threshold for a given target region. The magnitude threshold can be interpreted as the maximum magnitude of a possible clandestine explosion, given a predefined level of confidence. In the context of a comprehensive or threshold test ban treaty, the continuous assessment of the magnitude thresholds makes it possible to focus attention upon those specific time intervals when realistic evasion opportunities exist, while retaining confidence that no treaty violation has occurred at other times.

Kværna and Ringdal (1990) presented results from a one-week experiment of continuously monitoring the northern Novaya Zemlya test site. Data from the Fennoscandian regional array network (ARCESS, FINESA, and NORESS), see Fig. 7.8.1, were used to calculate the magnitude thresholds. It was found that the test site could be consistently monitored at a very low magnitude level (typically $m_b = 2.5$). In fact, every occurrence of the threshold exceeding $m_b = 2.5$ could be explained as resulting from an identified interfering event signal either at teleseismic or regional distance.

The excellent capability of the Fennoscandian regional array network to monitor the northern Novaya Zemlya test site was further confirmed by an experiment where recordings of the Novaya Zemlya nuclear test of October 24, 1990 were downscaled to $m_b = 2.6$ and superimposed on different noise intervals (Kværna, 1991).

In the context of using CSTM as a tool in routine monitoring, it is important to determine how the method will work under different conditions. Variability in the seismic noise level, occurrences of large earthquakes and aftershock sequences, station downtimes and data quality problems are all factors that will influence the performance of CSTM. Again focusing on the northern Novaya Zemlya test site, using data from the Fennoscandian regional array network, we have analyzed one month of magnitude threshold data (February, 1992) for the purpose of evaluating the long-term operational characteristics of CSTM.

Analysis of network threshold peaks

Our monitoring experiment was conducted in the same way and with the same parameter settings as used by Kværna and Ringdal (1990). In Kværna (1992) the monitoring results

were presented in terms of plots covering one data day each. In Figs. A-1 to A-29 of the Appendix of that report, each covering one day of February, 1992, all time periods where the network magnitude thresholds at the 90% confidence level exceeded $m_b = 2.6$ have been identified.

For the remainder of this paper, the term magnitude threshold implies the magnitude threshold at the 90% confidence level.

From investigation of the distribution of all network CSTM data (totally 696 hours for February, 1992), we found that the network magnitude threshold exceeded $m_b = 2.6$ for about 50 minutes, see Fig. 7.8.2. This is only 0.12% of the total time, and we found $m_b = 2.6$ to be a suitable magnitude limit, in the sense that we were able to identify all interfering event signals causing the threshold to exceed this limit. One might of course argue that we should instead attempt to explain all peaks exceeding $m_b = 2.5$, but with reference to the actual CSTM data, we found that there were several intervals with m_b between 2.5 and 2.6, which we were not able to account for by signals from identified events. These intervals were all characterized either by a high background noise level at ARCESS, or with gaps in the ARCESS recordings.

Figs. 7.8.3 and 7.8.4 show two typical examples of a one-day plot (February 1 and 21). The upper three traces of each figure represent the magnitude thresholds obtained from the three individual arrays, whereas the bottom trace illustrates the network threshold. Typically, the individual array traces have a number of significant peaks for each 24-hour period, due to signals from interfering events (regional or teleseismic). On the network trace, the number and sizes of these peaks are significantly reduced, because an interfering event usually will not provide matching signals at all stations. From probabilistic considerations, it can in such cases be inferred that the actual network threshold is lower than these individual peaks might indicate.

The arrows on the one-day threshold plots indicate peaks with network magnitude threshold exceeding $m_b = 2.6$. A **T** at the arrow indicates that the peak is caused by signals from a teleseismic event, whereas an **R** indicates signals from a regional or local event. On three different occasions during February the threshold slightly exceeded 2.6 due to gap in the ARCESS recordings. These peaks were indicated by a **G** at the arrows.

A summary of the threshold peaks and the events causing the peaks is given in Table 7.8.1 covering the entire month of February 1992. Following the definition of the CSTM peaks (i.e., date, time, magnitude threshold, and number of seconds with the threshold exceeding $m_b = 2.6$), there is a bulletin of the events causing the peaks in the magnitude threshold traces. From Table 7.8.1 it can be seen that in some cases more than one event is contributing to the same peak in the threshold trace.

During the first half of February, there were several large teleseismic events causing increases in the network threshold (see events reported by the Quick Epicenter Determinations (QED) of the USGS), whereas during the second half of February, almost all CSTM peaks were caused by regional events. The regional events were all processed and located by the Intelligent Monitoring System (IMS) (Bache et al., 1990). The epicenters of the

regional events of Table 1 are plotted on the map of Fig. 7.8.5. Except for one felt earthquake in southern Norway ($M_L = 3.26$), the events are most likely mining explosions, as their epicenters coincide with known mining sites. Within the context of practical monitoring, it is interesting that for a 5-day period (February 23 through 27) there were no threshold peaks exceeding $m_b = 2.6$.

Continuous thresholds during noise conditions

For the purpose of analyzing the long-term fluctuations of the magnitude thresholds, we have for every 4-hour interval computed the median thresholds. The robust median estimator has been chosen to ensure that we are minimizing the influence of the short-term event peaks. These statistics have been computed for the network and for each array separately. The thresholds are all derived from filtered array beams, and thereby reflect the noise fluctuations within the applied frequency bands. The frequency filters used for ARCESS, FINESA and NORESS are 3.0-5.0 Hz, 2.0-4.0 Hz and 1.5-3.5 Hz, respectively.

Fig. 7.8.6a illustrates the results for each array for the month of February. It is clearly seen that ARCESS (the lower dashed line) has the best average capability for monitoring the northern Novaya Zemlya test site. Except for a few short time intervals, ARCESS has on the average lower magnitude thresholds than any of the other two arrays (NORESS - solid line, FINESA - upper dashed line). The ARCESS threshold curve has five pronounced peaks during the month, and shows internal variations of more than $0.5 m_b$ units. During quiet noise conditions, the median magnitude thresholds fluctuate around $m_b = 2.0$, but during the high-noise periods the thresholds approaches $m_b = 2.5$. Two of the peaks have been verified to correlate with severe wind and weather conditions in the ARCESS region, and it is also likely that the other three peaks are weather generated.

Compared to ARCESS, the NORESS magnitude thresholds show rather small variations, and fluctuate between m_b 2.4 and 2.5 during the entire period, see Fig. 7.8.6a. The small diurnal variations (of the order of $0.1 m_b$ units), are consistent with the findings of Fyen (1990). He found that for frequencies below 2 Hz, there was little difference between daytime and nighttime noise levels, whereas at higher frequencies, the diurnal variations are more significant ($0.2-0.3 m_b$ units). It is only for a short time interval on February 6 that NORESS on the average has the best monitoring capability of the three arrays, but it has to be emphasized that this is not necessarily representative for time periods when seismic signals are present.

The median magnitude thresholds of FINESA, given by the top dashed line of Fig. 7.8.6a, exhibit strong weekly and diurnal variations. The diurnal variations are particularly significant on workdays. One peak for each of the five workdays are followed by a quiet weekend, reflecting the relative behavior of the background noise field in the frequency band of the P-beam steered towards Novaya Zemlya (2.0-4.0 Hz). The median thresholds during the weekends are approaching that of NORESS, whereas the workday levels are 0.2 to $0.4 m_b$ units higher. From Fig. 7.8.6a it can thus be inferred that FINESA on the average is contributing less than the other two arrays to the network monitoring capability of the northern Novaya Zemlya test site, but again, this may not be representative for time periods when seismic signals are present.

In Fig. 7.8.6b, we compare the median network performance (solid line) and the median ARCESS performance (dashed line) for monitoring the northern Novaya Zemlya test site. It is seen that when the ARCESS thresholds are low, the two curves almost coincide, implying that ARCESS alone determines the average network monitoring performance. However, during the ARCESS peak periods, the network curve is lower. This shows that even during background noise conditions, the other two arrays (FINESA and NORESS) contribute to lowering the magnitude thresholds.

We have in this section discussed the average properties of the CSTM performance of the Fennoscandian array network for monitoring the northern Novaya Zemlya test site. We have concluded that for most of the time, ARCESS is the array with the best capability, but that the other two arrays also play an important role, particularly when the ARCESS noise level is high.

Continuous thresholds during intervals with interfering signals

The dramatic improvement in the practical monitoring capability when using a network of arrays instead of a single array is illustrated in Fig. 7.8.7. We have for the month analyzed counted the number of threshold peaks exceeding a given magnitude, both for the network and for the best array (ARCESS). The barplots of Fig. 7.8.7 show that at a threshold of 2.6, the number of network threshold peaks are reduced by a factor of five in comparison to the threshold peaks at ARCESS alone (i.e., from 293 to 56). At a threshold of 3.0 the improvement is better than a factor of ten (i.e., from 41 to 3).

Conclusions

This work has documented the practical capability of the Continuous Seismic Threshold Monitoring method to monitor a specific nuclear test site at a very low threshold over an extended time period.

Specifically, we have used the Fennoscandian array network (NORESS, ARCESS and FINESA) to monitor the northern Novaya Zemlya test site for one full month (February 1992). We have shown that the magnitude threshold stays below $m_b = 2.50$, 99.72% of the total time. We have further "explained" all of the peaks exceeding $m_b = 2.6$ as resulting from one of the following three conditions: 1) a "large" identified teleseismic event, 2) a "large" identified regional event and 3) a short outage of the most important array (ARCESS).

The natural question is then as follows: Do these results imply that at the given confidence level there has been no seismic event of $m_b \geq 2.6$ at the test site during February 1992?

The answer is in practice "yes", since such an event only could have occurred during one of the time intervals when the network threshold trace exceeds 2.6. We have noted that the combined time span of such exceedances was only 50 minutes, or 0.12% of the total time. Since all the peaks were explained as resulting from known causes, it seems extremely unlikely that an event of $m_b = 2.6$ actually occurred during one of these short event intervals.

In theory, in a hypothetical monitoring situation for a comprehensive test ban treaty, there might be an "evasion" possibility if any of such high threshold periods could be predicted. But we do not consider this to be a realistic scenario. First, such predictions require exact knowledge of the configuration and the performance of the monitoring network, and second, there are a lot of practical problems involved in carrying out such a clandestine explosion so that the probability of getting detected is very high.

We have studied the relative contributions of the three arrays and found that ARCESS is clearly the most important, followed by NORESS and FINESA. During time periods when the ARCESS noise level is high, or when there are interfering events, the relative contributions of NORESS and FINESA increase significantly. The redundancy created by using several arrays is also essential during outages of one or more of the arrays.

The average magnitude thresholds at FINESA exhibit strong weekly and diurnal variations. The latter are particularly significant on workdays. The average NORESS thresholds show rather small variations, whereas at ARCESS, internal differences of more than 0.5 m_b units are observed. The peak periods at ARCESS are most likely caused by severe wind and weather conditions.

In the near future, additional array stations are planned for installation in the Arctic region. These stations would contribute to further improving the CSTM capability, both for Novaya Zemlya and on a general regional basis. This will be the subject for additional studies in the future.

T. Kværna

References

- Bache, T., S. R. Bratt, J. Wang, R.M. Fung, C. Kobryn and J. W. Given (1990), The Intelligent Monitoring System, *Bull. Seism. Soc. Am.*, 80, Part B, 1833-1851.
- Fyen, J. (1990): Diurnal and seasonal variations in the microseismic noise level observed at the NORESS array, *Phys. Earth Planet. Inter.*, 63, 252-268.
- Kværna, T. (1992): Continuous seismic threshold monitoring of the northern Novaya Zemlya test site; long-term operational characteristics, AFGL Sci. Rep. No. 12, NORSAR, Kjeller.
- Kværna, T. and F. Ringdal (1990): Continuous threshold monitoring of the Novaya Zemlya test site, *Semiannual Tech. Summary, 1 Apr - 30 Sep 1990*, NORSAR Sci. Rep. 1-90/91, NORSAR, Kjeller, Norway.
- Kværna, T (1991): Threshold monitoring of Novaya Zemlya: A scaling experiment, *Semiannual Tech. Summary, 1 Oct 1990 - 31 Mar 1991*, NORSAR Sci. Rep. 2-90/91, NORSAR, Kjeller, Norway.

Ringdal, F. and T. Kværna (1989): A multi-channel processing approach to real-time network detection, phase association, and threshold monitoring, *Bull. Seism. Soc. Am.*, 79, 1927-1940.

Date	TM peak	Mag	Sec	Ev	Or. time	Lat	Lon	Dep	Mag	Bull	Region
02/01	11.46.11	2.66	20	R	11.46.08.8	67.592	30.300	0F	2.46	IMS	European Russia
02/01	19.12.08	2.99	88	T	19.04.05.3	35.164	139.702	107	5.6	QED	S.coast of Honshu
02/02	05.04.20	2.63	12	R	05.05.01.4	67.659	33.417	0F	2.41	IMS	European Russia
02/02	17.51.03	2.65	9	T	05.05.01.4	67.659	33.417	33F	5.5	QED	Kuril Islands
02/03	13.55.17	2.69	15	R	13.54.44.6	60.836	29.220	0F	2.41	IMS	European Russia
02/05	05.40.43	2.72	15	T	05.33.11.4	45.021	150.972	33F	5.6	QED	Kuril Islands
02/05	10.56.54	2.64	2	T	10.54.38.0	44.600	150.500	33F	4.3	NORSAR	Kuril Islands
02/05	13.21.09	2.90	69	T	13.13.42.5	52.163	-170.130	48	5.4	QED	Fox Islands
02/05	23.14.43	2.65	8	T	23.10.50.9	31.407	66.825	33F	5.1	QED	Afghanistan
02/06	01.23.52	2.95	181	T	01.12.41.2	-5.609	103.271	55	6.0	QED	Southern Sumatra
02/06	03.42.24	2.71	77	T	03.35.17.2	29.511	95.635	33F	5.6	QED	Xijang-India border
02/06	04.05.32	2.63	4	T	03.54.43.7	-5.374	103.197	72	5.5	QED	Southern Sumatra
02/06	05.13.26	2.63	3	T	04.57.28.0	-33.400	-175.200	33F	3.8	NORSAR	Kermadec Islands
02/06	09.19.03	2.78	39	R	09.18.47.9	61.243	29.875	0F	2.07	IMS	Finland-Russia border
				R	09.19.55.1	68.147	32.846	0F	1.90	IMS	European Russia
02/06	12.19.03	2.61	3	R	12.21.00.0	69.344	30.570	0F	2.14	IMS	Norway-Russia border
02/06	16.27.43	2.66	9	R	16.28.20.4	67.176	20.792	0F	1.83	IMS	Sweden
02/07	00.13.59	2.88	49	T	00.06.28.6	43.140	146.611	54	5.4	QED	Kuril Islands
02/07	06.42.13	2.67	20	T	06.35.26.0	52.925	159.555	49	5.3	QED	Off east coast of Kamchatka
02/07	08.38.36	2.66	15	R	08.41.05.1	67.633	33.715	0F	2.41	IMS	European Russia
02/07	09.20.39	2.61	1	R	09.21.16.4	68.190	32.875	0F	1.98	IMS	European Russia
				R	09.23.00.4	67.969	32.870	0F	1.92	IMS	European Russia
				R	09.25.08.3	59.298	26.399	0F	1.06	IMS	European Russia
02/07	09.54.59	2.65	15	T	09.48.38.7	55.795	160.753	138	5.0	QED	Kamchatka
02/07	09.59.36	2.64	5	R	10.00.44.9	64.692	30.728	0F	2.11	IMS	Finland-Russia border
02/07	12.18.59	2.80	21	R	12.20.52.2	69.329	30.842	0F	2.40	IMS	Norway-Russia border
02/08	11.44.28	2.69	29	R	11.44.41.2	67.648	30.594	0F	2.24	IMS	European Russia
02/09	04.09.14	2.63	5	R	04.09.41.1	67.574	33.741	0F	2.35	IMS	European Russia
02/09	07.56.42	2.57	-	T	07.49.21.5	51.497	-178.364	66	5.1	QED	Andreanof Islands
02/09	22.08.59	2.84	47	T	22.01.58.4	47.982	152.979	123	5.6	QED	Kuril Islands
02/12	01.09.22	2.82	42	T	01.02.01.9	51.299	177.926	33F	5.2	QED	Rat Islands
02/13	01.45.47	2.77	70	T	01.29.17.1	-15.923	166.215	33F	6.1	QED	Vanuatu Islands
02/13	02.45.31	2.82	54	T	02.38.18.4	53.576	-165.706	44	5.5	QED	Fox Islands
02/13	23.34.08	2.72	33	R	23.35.20.5	67.720	21.067	0F	1.84	IMS	Sweden
02/14	08.23.25	2.99	136	T	08.18.27.7	53.576	-165.706	33F	5.3	QED	Lake Baykal Region
02/14	08.48.02	2.61	1	R	08.48.20.2	67.391	32.939	0F	2.31	IMS	European Russia
02/14	12.19.23	2.96	115	R	12.21.00.9	69.322	30.727	0F	2.50	IMS	Norway-Russia border
02/15	11.47.38	2.62	1	R	11.49.21.2	67.656	30.374	0F	1.87	IMS	European Russia
02/15	12.57.21	2.76	61	T	12.52.55.0	42.846	46.588	33F	4.7	QED	Eastern Caucasus
02/16	08.49.11	2.70	27	R	08.49.50.5	67.636	33.547	0F	2.54	IMS	European Russia
02/16	21.55.47	2.53	-	R	21.54.36.6	67.667	20.841	0F	1.03	IMS	Sweden
02/17	00.04.52	3.13	136	T	00.01.56.7	79.190	124.625	10	5.8	QED	East of Severnaya Zemlya
02/17	08.13.48	2.65	27	G							Gap in ARCESS recording
02/17	14.23.57	2.71	33	R	14.25.24.0	69.638	30.430	0F	1.95	IMS	Norway-Russia border
02/17	15.45.13	2.63	4	G							Gap in ARCESS recording
02/18	12.42.04	2.68	8	R	12.42.01.9	59.337	27.065	0F	2.61	IMS	European Russia
02/19	06.40.25	2.91	226	R	06.39.32.9	59.240	10.886	0F	3.26	IMS	Southern Norway
02/19	12.26.49	3.25	302	R	12.25.03.0	69.257	30.575	0F	2.09	IMS	Norway-Russia border
				R	12.26.30.0	64.722	30.553	0F	2.78	IMS	Finland-Russia border
02/19	12.42.45	2.88	33	R	12.43.59.4	67.595	33.647	0F	2.46	IMS	European Russia
02/20	20.52.21	2.55	-	T	20.35.24.3	-33.498	-179.673	48	5.9	QED	South of Kermadec Islands
02/20	21.16.05	2.79	60	R	21.16.27.7	67.647	33.555	0F	1.98	IMS	European Russia
				R	21.16.50.5	67.918	33.951	0F	2.39	IMS	European Russia
02/21	08.59.39	2.74	103	R	08.59.25.1	67.657	33.791	0F	2.63	IMS	European Russia
02/21	11.01.46	3.14	173	R	11.01.53.5	64.672	30.801	0F	2.72	IMS	Finland-Russia border
02/21	12.49.06	2.99	135	R	12.50.11.2	69.341	30.688	0F	2.16	IMS	Norway-Russia border
				R	12.51.02.8	69.380	30.683	0F	2.46	IMS	Norway-Russia border
02/21	16.32.43	2.80	42	R	16.32.43.4	67.117	21.049	0F	2.02	IMS	Sweden
02/22	11.45.00	2.72	44	R	11.46.12.7	67.485	29.529	0F	1.87	IMS	Finland-Russia border
				R	11.46.59.0	67.558	30.328	0F	2.24	IMS	European Russia
02/22	11.59.31	2.70	35	R	12.00.18.7	67.599	33.659	0F	2.50	IMS	European Russia
02/28	08.58.22	2.75	36	R	08.58.59.1	67.617	33.769	0F	2.50	IMS	European Russia
02/28	12.07.37	2.63	2	R	12.09.56.9	59.170	27.332	0F	1.80	IMS	European Russia
02/28	12.19.10	2.69	37	G							Gap in ARCESS recording
02/28	12.43.14	2.92	243	R	12.45.11.0	69.365	30.647	0F	2.52	IMS	Norway-Russia border
02/28	14.30.16	2.68	17	R	14.30.29.5	67.709	33.695	0F	2.16	IMS	European Russia
				R	14.31.39.7	67.522	33.677	0F	2.31	IMS	European Russia

Table 7.8.1. List of peaks in the network threshold traces and the events causing the peaks. Following the definition of the CSTM peaks (i.e., date, time, maximum magnitude threshold, and number of seconds with the threshold exceeding $m_b = 2.6$), there is a bulletin of the events causing the peaks in the magnitude threshold traces. It can be seen that in some cases more than one event is contributing to the same peak in the threshold trace.

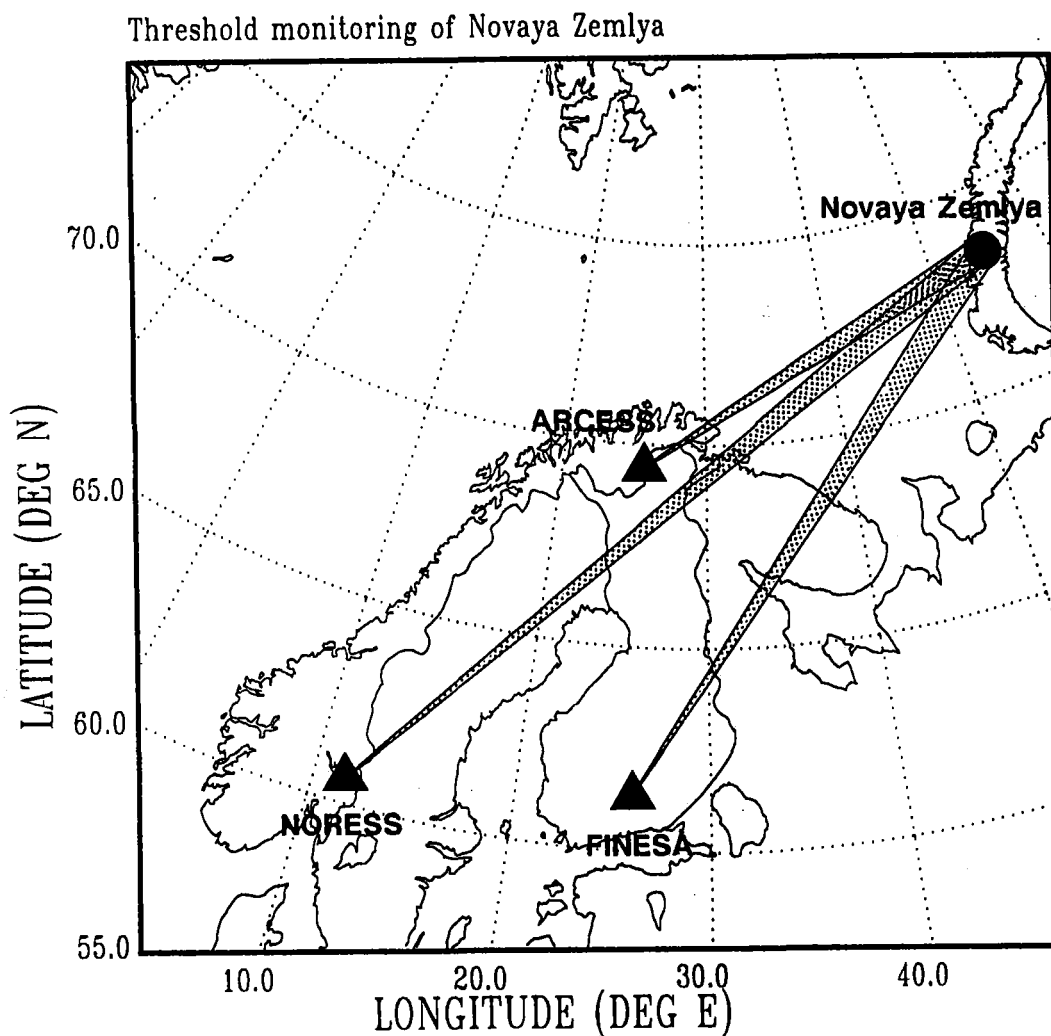


Fig. 7.8.1. Map showing the location of the northern Novaya Zemlya test site and the Fenoscandian array network. The distances of the three arrays from the test site are for NORESS 2280 km, for ARCESS 1100 km and for FINESA 1780 km.

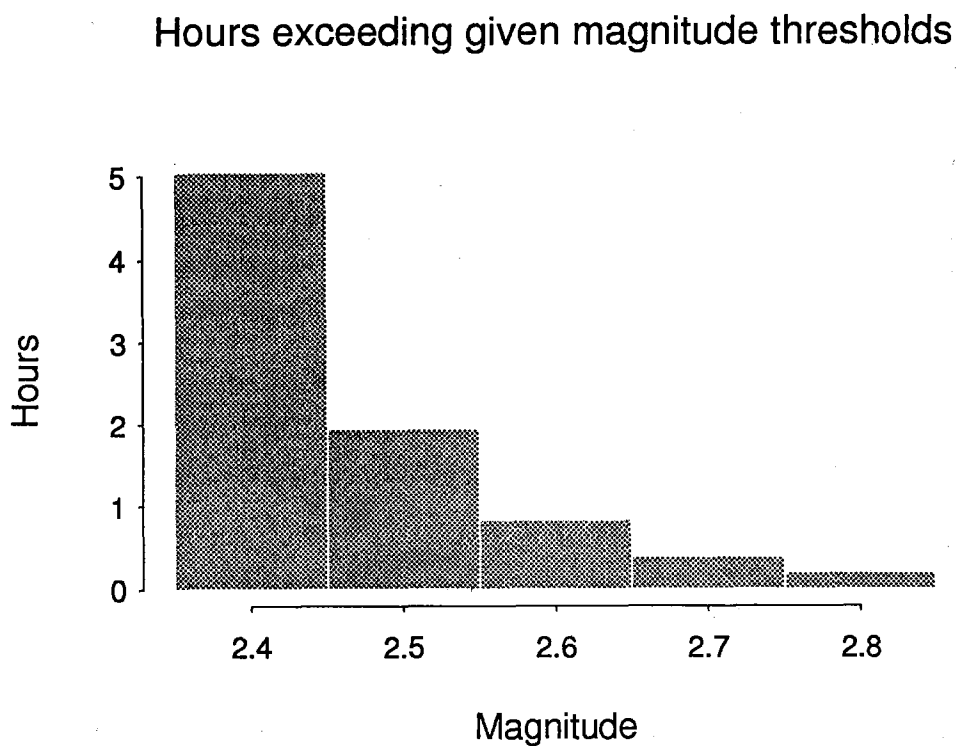


Fig. 7.8.2. Barplot showing the number of hours where the 90% network magnitude threshold exceeds a given magnitude, for the month of February, 1992.

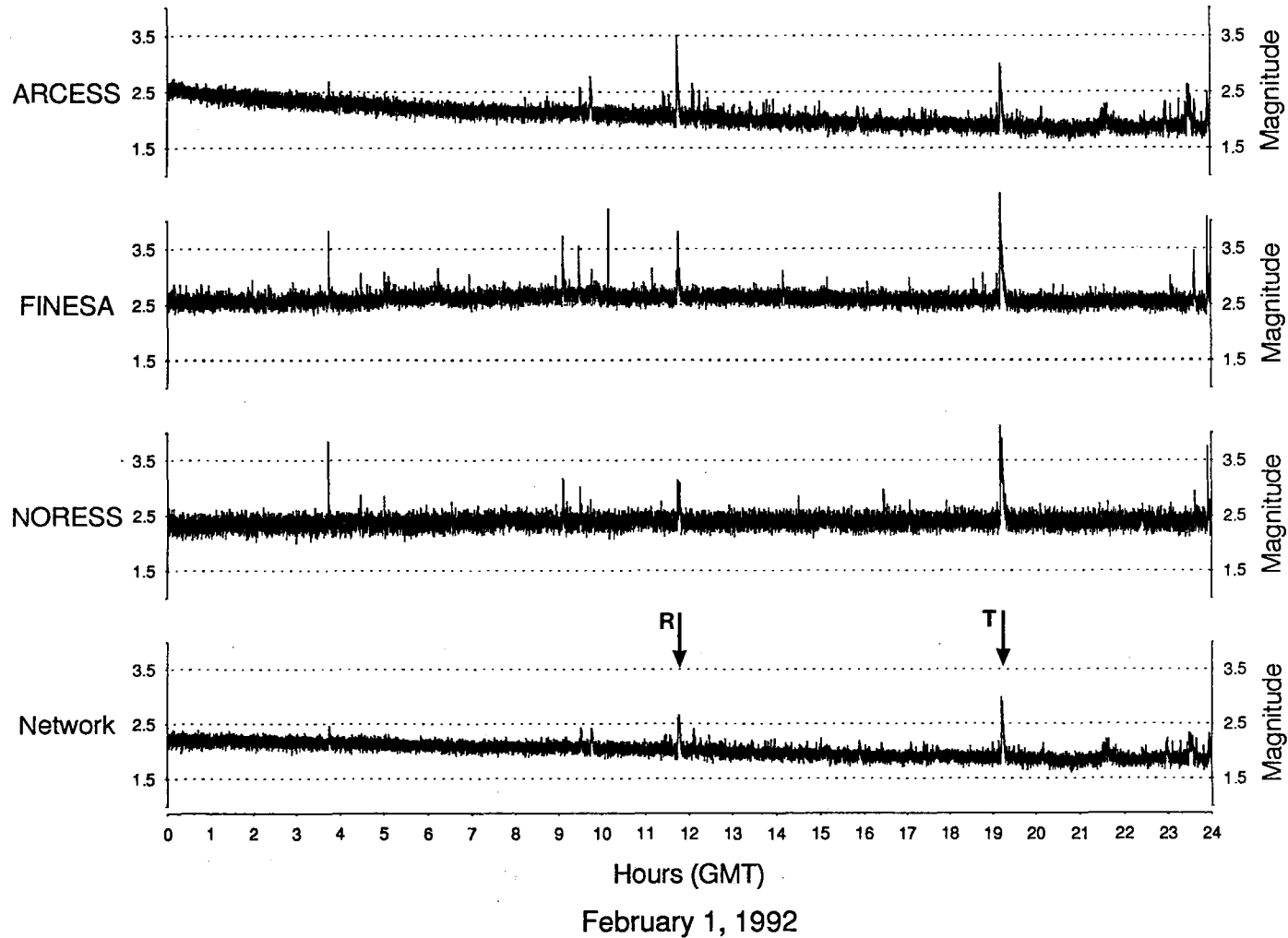


Fig. 7.8.3. The upper three traces represent the 90% magnitude thresholds obtained from the individual arrays, whereas the bottom trace illustrates the network threshold. The arrows indicate peaks with network magnitude threshold exceeding $m_b = 2.6$. A **T** at the arrow indicates that the peak is caused by signals from a teleseismic event, whereas an **R** indicates signals from a local or regional event.

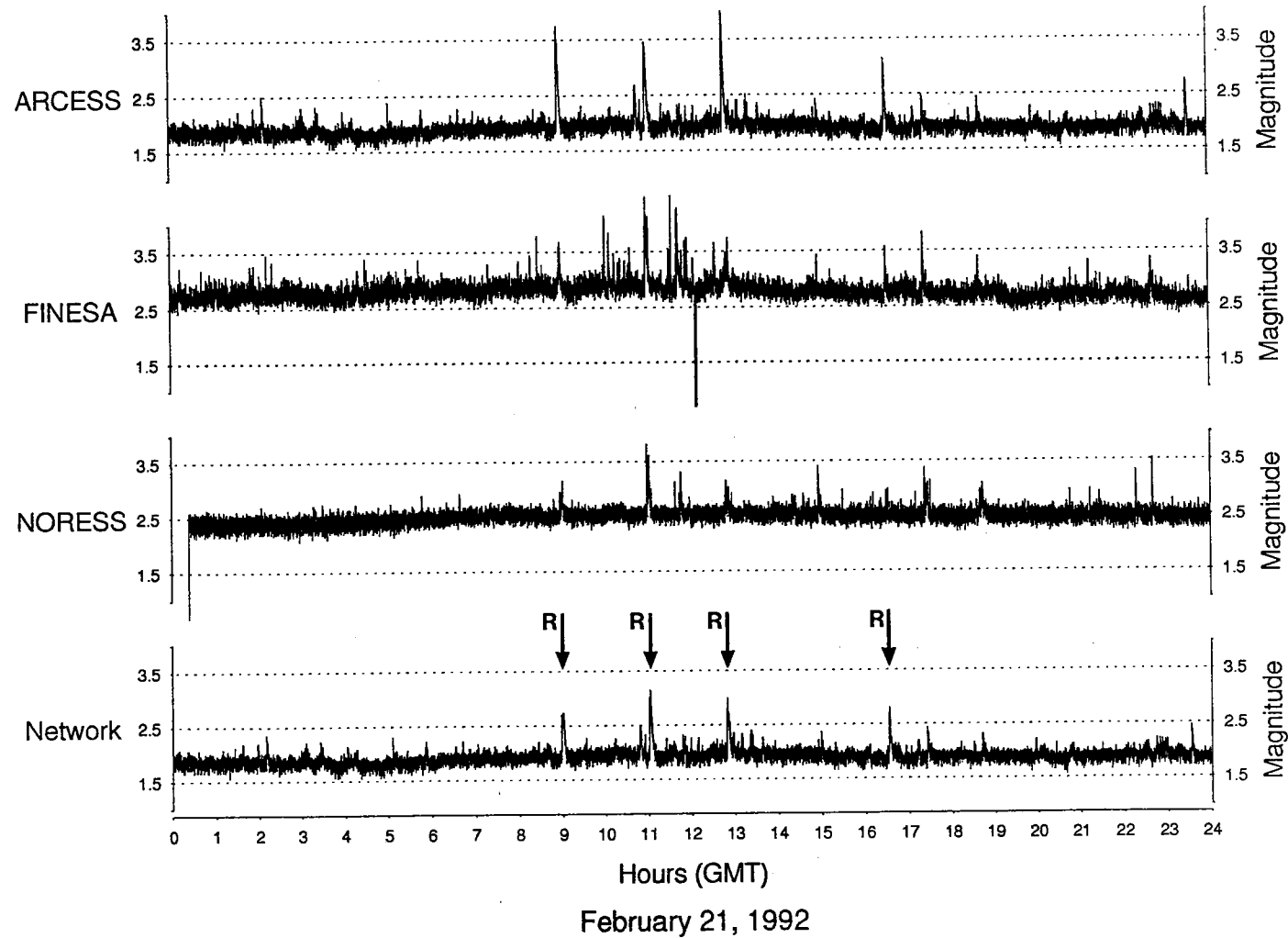


Fig. 7.8.4. The upper three traces represent the 90% magnitude thresholds obtained from the individual arrays, whereas the bottom trace illustrates the network threshold. The arrows indicate peaks with network magnitude threshold exceeding $m_b = 2.6$. A **T** at the arrow indicates that the peak is caused by signals from a teleseismic event, whereas an **R** indicates signals from a local or regional event.

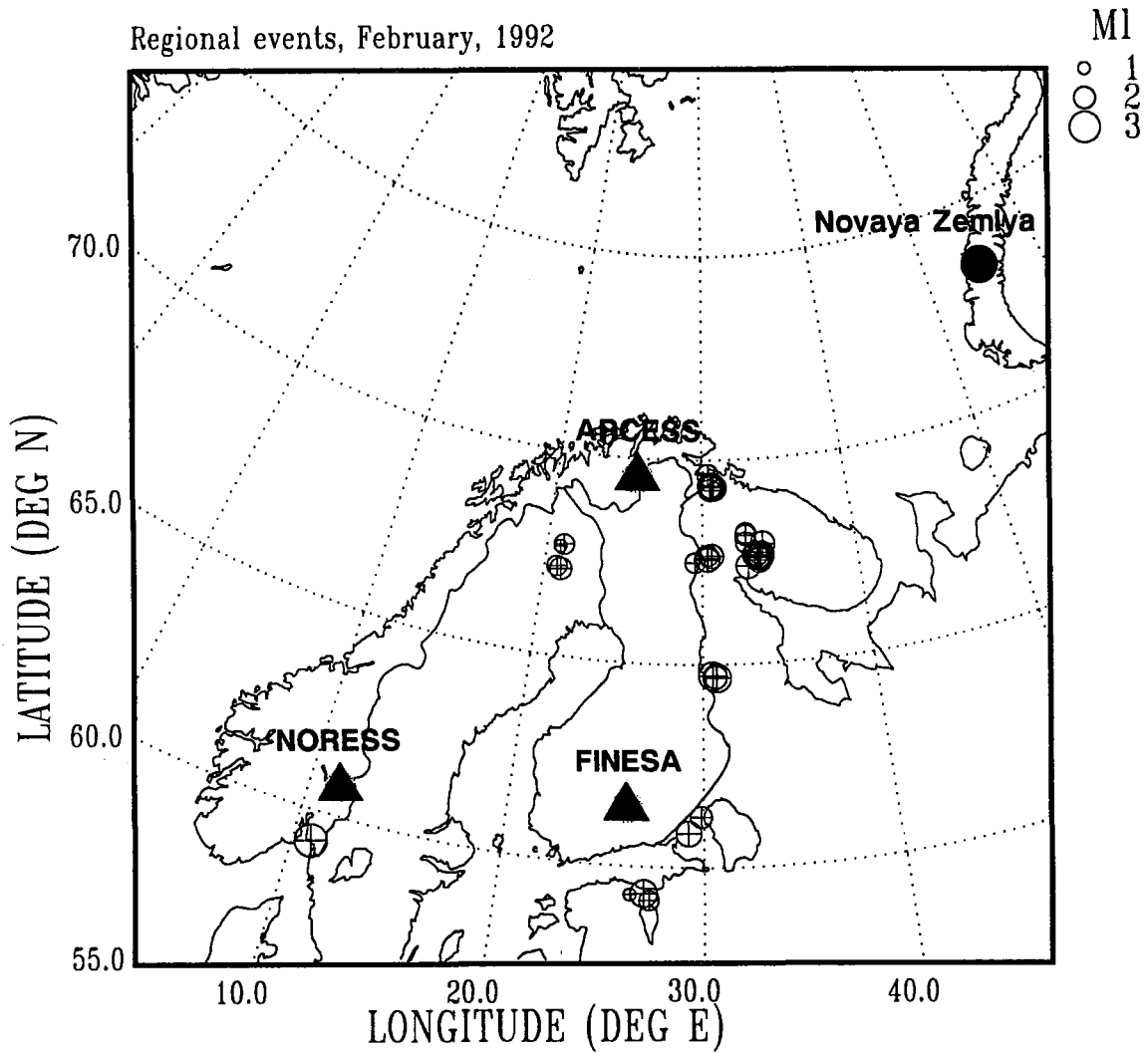


Fig. 7.8.5. Epicenters of regional events causing the network threshold to exceed $m_b = 2.6$. All events, except one felt earthquake in southern Norway, are probable mining explosions. Note the large number of events on the Kola peninsula.

ARCESS, NORESS, FINESA

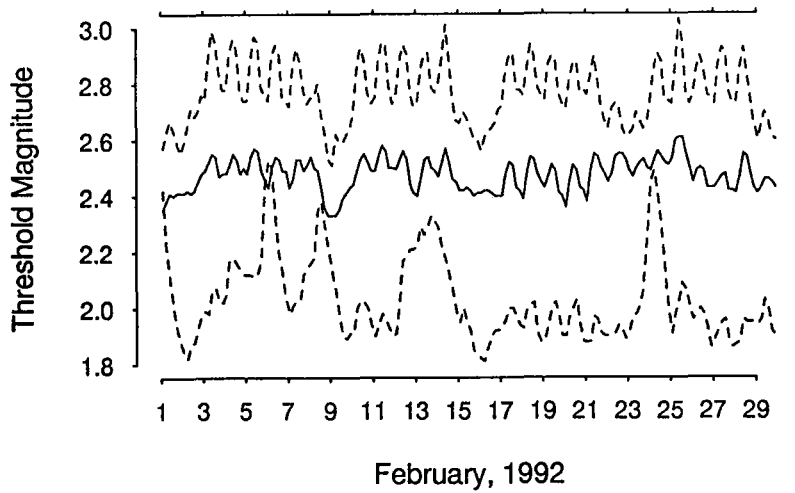


Fig. 7.8.6a. Four-hour medians of the magnitude thresholds for each array for the month of February 1992.

Lower dashed line: ARCESS
 Middle solid line: NORESS
 Upper dashed line: FINESA

Network and ARCESS

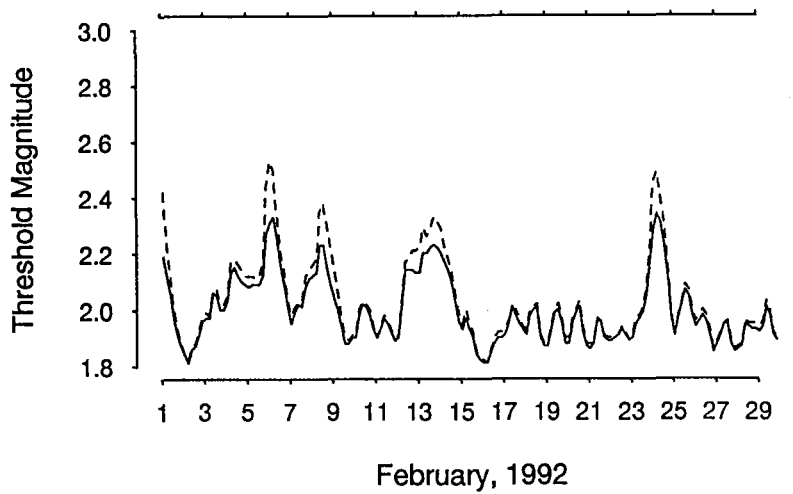


Fig. 7.8.6b. Four-hour medians of the magnitude thresholds for ARCESS and for the network for the month of February 1992.

Solid line: Network
 Dashed line: ARCESS

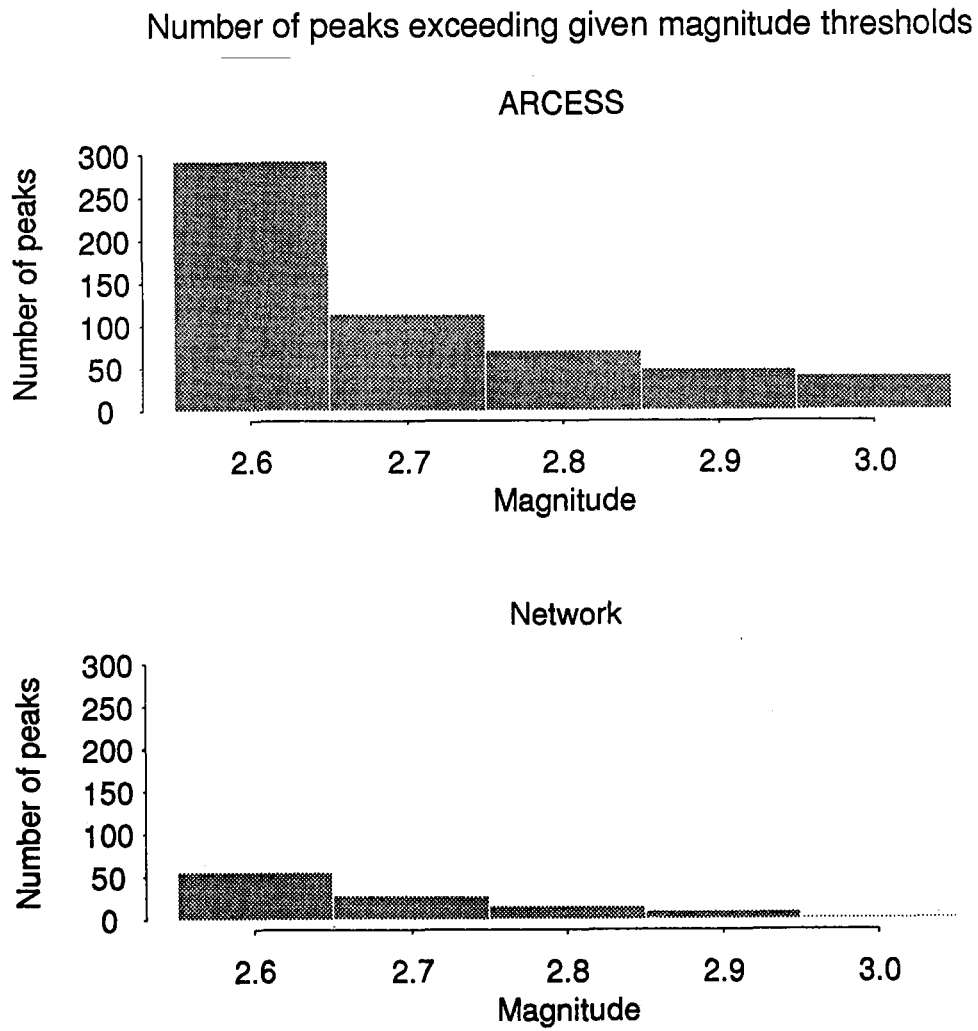


Fig. 7.8.7. Number of peaks exceeding given magnitude thresholds.

Upper part: ARCESS

Lower part: Network

7.9 Correlation between temperature and number of detections

When operating an automatic detector such as the STA/LTA detector in effect at the regional arrays in northern Europe, the number of false detections as a function of STA/LTA threshold, frequency and slowness is an important consideration. As discussed in Section 7.6, the f-k analysis is an effective tool at these arrays to separate such false alarms from real seismic detections, by using the calculated phase velocity. In addition, the estimated azimuths and signal frequency can be used to obtain some indications about the origins of these noise detections.

A number of sources contribute to such detections. Some are of cultural origin, others are environmentally determined. In some cases there are significant noise detection effects only during certain times of the year, or during certain environmental conditions.

Luosto and Saastamoinen (1964) have demonstrated a clear correlation between large temperature variations and ice-shocks in a lake. Ice-shocks were observed during the freezing period in early winter, and then a strong correlation between number of ice-shocks and temperature decline was found in March/April. During this latter spring period, the temperature goes above the freezing point during the day, and falls to 10-20 degrees Celsius below freezing point during the night.

In a study of NORESS noise detections, Kværna (1990) found a strong correlation between the water flow in the nearby river Glomma and the number of low-velocity phase detections. Fyen (1990) showed that the noise level is also strongly correlated with the water flow. The noise at certain frequencies is furthermore very strongly affected by various sources of industrial activity.

Many of such noise 'events' are very strong. For the ARCESS array, they are often located within, or very close to the array.

Figs. 7.9.1 and 7.9.2 show the number of detections and temperature at ARCESS and NORESS, respectively, each for a two-week period. We notice a clear correlation between temperature and detection rate. During nighttime, the detection rate is considerably higher than during daytime.

In Fig. 7.9.3, we report a longer period for ARCESS, and we see a very typical increase in the number of detections during the first freezing night in the autumn, but thereafter the connection between freezing temperature and number of detections is not as clear during the mid-winter. However, when the spring comes, we again see a clear correlation between large temperature variations and peaks in the number of detections.

Although these examples are clear enough, we find other periods when the number of detections increases dramatically, without any obvious correlation with temperature changes. One other potential source of such increase in the number of detections is the increase of waterflow in the nearby rivers (Kværna, 1990).

Fig. 7.9.4 illustrates the intensity of these events. The STA/LTA detector classifies this correctly as an "event", but the subsequent fk-analysis classifies it as a "false alarm", which is also correct with respect to what we are looking for.

J. Fyen

K. Hansvold

References

- Luosto, U. and P. Saastamoinen (1964): , Observations about ice-shocks on lake Saak-sjarvi, *Geophysica*, Vol. 9, No.1, University of Helsinki.
- Kværna, T. (1990): Sources of short-term fluctuations in the seismic noise level at NOR-ESS, *PEPI*, 63, 269-276.
- Fyen, J. (1990): Diurnal and seasonal variations in the microseismic noise level observed at the NORESS array, *Phys. Earth Planet. Int.*, 63, 252-268.

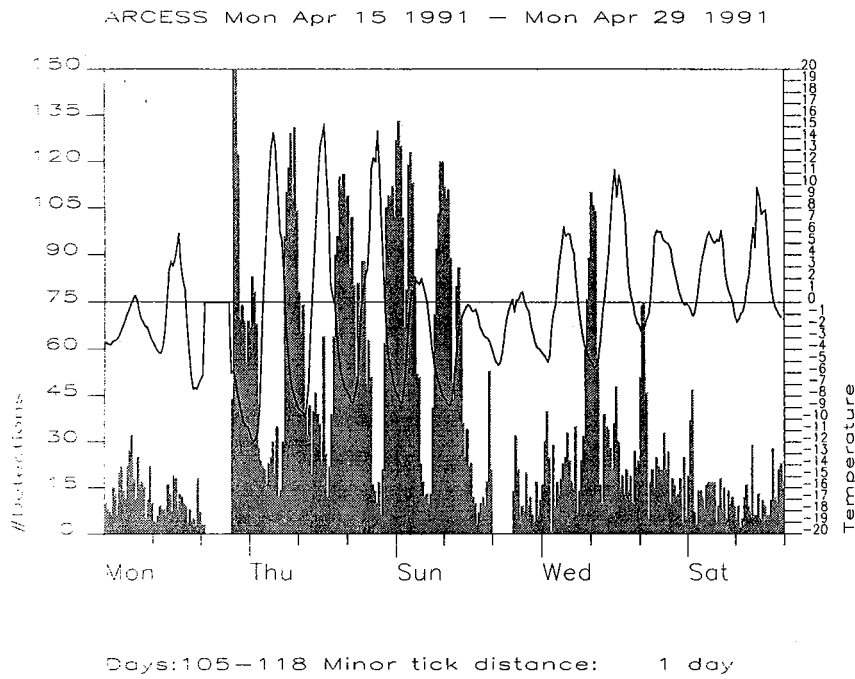


Fig. 7.9.1. Number of detections (shaded) and temperature for ARCESS during the period April 15 through April 28, 1991.

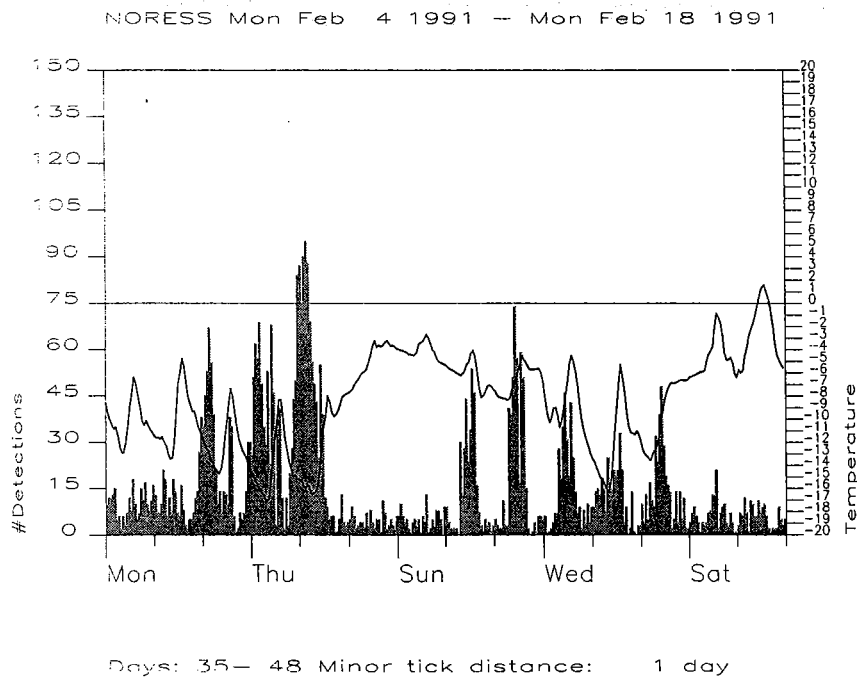


Fig. 7.9.2. Number of detections (shaded) and temperature for NORESS during the period February 4 through February 17, 1992)

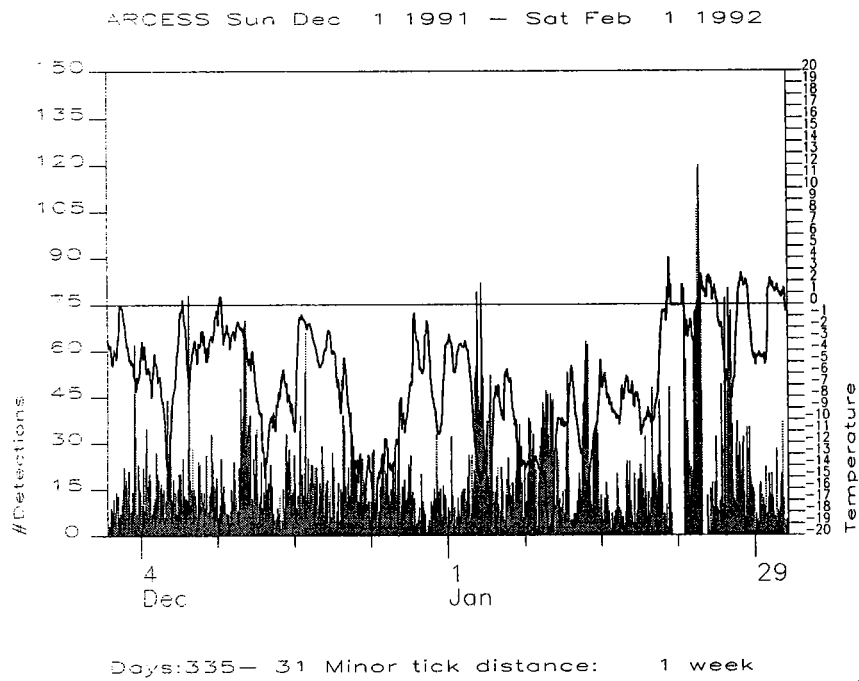
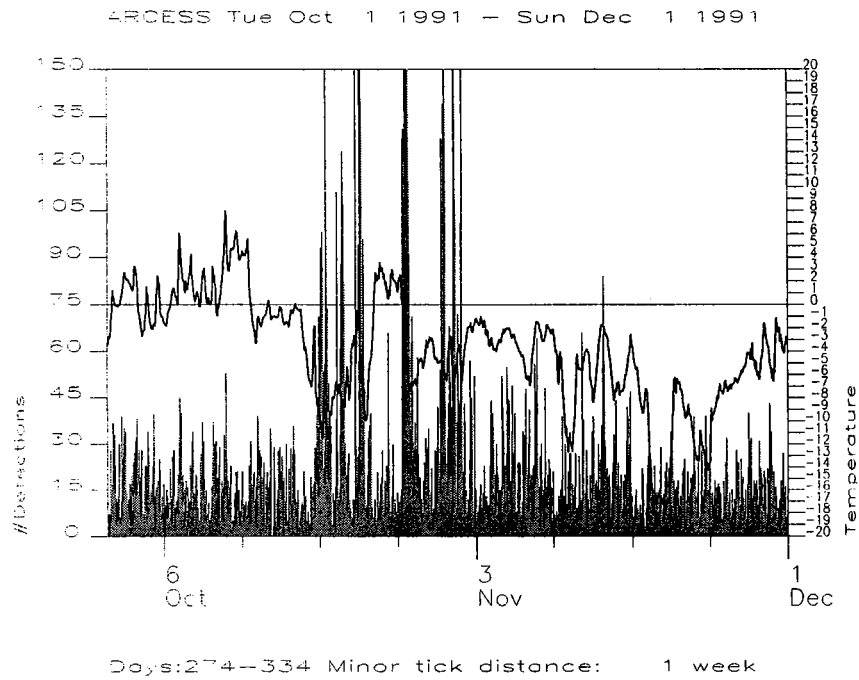


Fig. 7.9.3. Number of detections and temperature (bold line) for ARCESS during the period October 1 to December 1, 1991 (upper) and December 1, 1991, to February 1, 1992 (lower)..

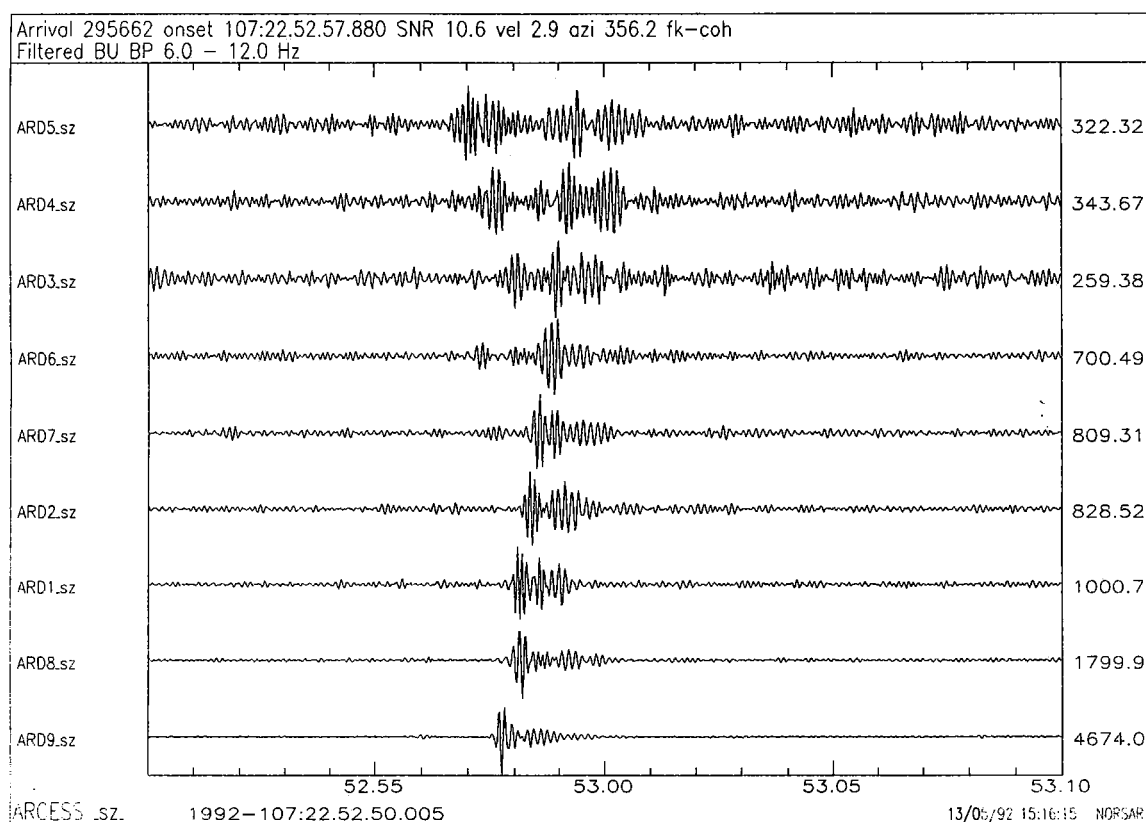


Fig. 7.9.4. Example of a “false alarm”. This event originated very close to the array, and is interpreted as an “ice-shock”. The fk-analysis classified this event as “noise”, by reporting apparent velocity 2.9.